

A Simplified Formulation for the Backward/Forward Sweep Power Flow Method

Paulo M. De Oliveira-De Jesus*

November 26, 2021

Abstract

This paper describes a simplified formulation of the Backward/Forward (BW/FW) Sweep Power Flow applied to radial distribution systems with distributed generation under positive sequence modelling. Proposed formulation was applied in an illustrative test system.

Keywords: Backward/forward sweep, load flow, power flow, distribution system analysis

1 Introduction

Several Backward/Forward (BW/FW) sweep algorithms have been discussed in literature. In 1967, Berg presented a paper which can be considered as the source for the all variants of BW/FW sweep methods [1]. Later, a similar approach was presented in [2] based on ladder network theory. The BW/FW Sweep algorithms use the Kirchhoff laws. Different formulations can be found [3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 15, 14]. BW/FW sweep methods typically present a slow convergence rate but computationally efficient at each iteration. Using these methods, power flow solution for a distribution network can be obtained without solving any set of simultaneous equations. In this work, the standard BW/FW sweep power flow is reformulated in convenient form. An illustrative four-bus example is solved.

*Electrical & Electronic Engineering Department, School of Engineering, Universidad de los Andes, Colombia, website: <https://power.uniandes.edu.co/pdeoliveira>, E-mail: pm.deoliveiradejes@uniandes.edu.co

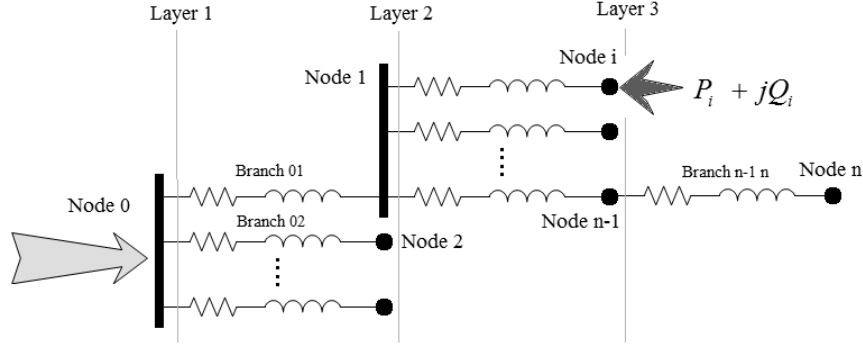


Figure 1: Branch and node numbering of a radial distribution network

2 The Method

The input data of this algorithm is given by node-branch oriented data used by most utilities. Basic data required is: active and reactive powers, nomenclature for sending and receiving nodes, and positive sequence impedance model for all branches.

In the following, the standard BW/FW sweep power flow method is written in matrix notation using complex variables. Branch impedances are stated as a vector \mathbf{Z} corresponding to a distribution line model containing a series positive sequence impedance for line or transformer. Shunt impedances are not considered in this first approach. Fig. 1 shows a radial distribution network with $n + 1$ nodes, and n branches and a single voltage source at the root node 0. Branches are organized according to an appropriate numbering scheme (list), which details are provided in [3].

$$\mathbf{Z} = [\bar{Z}_{01} \quad \dots \quad \bar{Z}_{ij} \quad \dots \quad \bar{Z}_{mn}] \quad (1)$$

where,

$$\bar{Z}_{ij} = R_{ij} + jX_{ij} \quad i, j = 1, \dots, n \quad i \neq j \quad (2)$$

Bus data is given by

$$\mathbf{S} = \begin{bmatrix} \bar{S}_1 \\ \vdots \\ \bar{S}_i \\ \vdots \\ \bar{S}_n \end{bmatrix} = \begin{bmatrix} P_1 + jQ_1 \\ \vdots \\ P_i + jQ_i \\ \vdots \\ P_n + jQ_n \end{bmatrix} \quad (3)$$

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where net nodal active and reactive powers are given by generated and demanded powers:

$$P_i = P_{Gi} - P_{Di} \quad (4)$$

$$Q_i = Q_{Gi} - Q_{Di} \quad (5)$$

The numbering of branches in one layer begins only after all the branches in the previous layer have been numbered. Considering that initial voltages are known: voltage at substation is set $\bar{V}_0 = V_{ref}$ and an initial voltage vector is given by:

$$\mathbf{V}^0 = \begin{bmatrix} \bar{V}_1^0 & \dots & \bar{V}_i^0 & \dots & \bar{V}_n^0 \end{bmatrix} \quad (6)$$

The state of the system is reached solving two steps iteratively.

2.1 Step 1 - Backward Sweep

For each iteration k , branch currents are aggregated from loads to origin:

$$\mathbf{J}^k = -\mathbf{T} \cdot \mathbf{I}^k \quad (7)$$

The relationship between nodal currents \mathbf{I}^k and branch currents \mathbf{J}^k is set through an upper triangular matrix \mathbf{T} accomplishing the Kirchhoff Current Laws (KCL). Each element \bar{I}_i^k of \mathbf{I}^k associated to node i is calculated as function of injected powers \bar{S}_i and its voltage profile \bar{V}_i^k as shown below:

$$\bar{I}_i^k = \frac{\bar{S}_i^*}{\bar{V}_i^{k*}} \quad i = 1, \dots, n \quad (8)$$

2.2 Step 2 - Forward Sweep

Nodal voltage vector \mathbf{V} is updated from the origin to loads according the Kirchhoff Voltage Laws (KVL), using previously calculated branch currents vector \mathbf{J} , branch impedances vector \mathbf{Z} :

$$\mathbf{V}^{k+1} = \mathbf{V}_0 - \mathbf{T}^T \cdot \mathbf{D}_Z \cdot \mathbf{J}^k \quad (9)$$

where \mathbf{V}_0 is a n -elements vector with all entries set at voltage at origin (swing node) \bar{V}_0 and branch impedances \mathbf{D}_Z is the diagonal matrix of vector \mathbf{Z} :

Using Eq. 7

$$\mathbf{V}^{k+1} = \mathbf{V}_0 + \mathbf{T}^T \cdot \mathbf{D}_Z \cdot \mathbf{T} \cdot \mathbf{I}^k \quad (10)$$

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Updated voltages can be updated using only one equation:

$$\mathbf{V}^{k+1} = \mathbf{V}_0 + \mathbf{TRX} \cdot \mathbf{I}^k \quad (11)$$

where $\mathbf{TRX} = \mathbf{T}^T \cdot \mathbf{D}_Z \cdot \mathbf{T}$

2.3 Convergence

Updated voltages are compared with previous voltages in order to perform convergence check in.

$$\varepsilon \leq |\overline{V}_i^{k+1} - \overline{V}_i^k| \quad i = 1, \dots, n \quad (12)$$

3 Illustrative Example: Simply 4-node Network

To illustrate the proposed methodology, it is used the 4-node example shown in Fig. 2. Length of all sections is 1 mile. Load demand at nodes 2 and 3 are 2MW with $\cos \varphi = 1.0$.

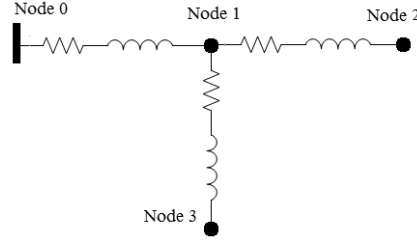


Figure 2: 4-Node Network Topology

Using the following bases $S_B = 10\text{MW}$ and $V_B = 12.47\text{kV}$, data and results are given in per unit. Loads are 0.2 in nodes 2 and 3. Reference voltage at node 0 is $\overline{V}_0 = 1 + j0$ and initial voltages are set $\mathbf{V}^0 = [1 + 0j \quad 1 + 0j \quad 1 + 0j]$.

Branches are represented by:

$$\mathbf{Z} = \mathbf{R} + j\mathbf{X} = \begin{bmatrix} .0296 \\ .0296 \\ .0296 \end{bmatrix} + j \begin{bmatrix} .0683 \\ .0683 \\ .0683 \end{bmatrix}$$

Network topology is represented through a 3x3 upper triangular matrix \mathbf{T} .

$$\mathbf{T} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Then, $\mathbf{D}_{\mathbf{Z}}$ is:

$$\mathbf{D}_{\mathbf{Z}} = \begin{bmatrix} .0296 + j.0683 & .0 & 0 \\ 0 & .0296 + j.0683 & 0 \\ 0 & 0 & .0296 + j.0683 \end{bmatrix}$$

Solution reached at iteration 3 for $\varepsilon = 10^{-4}$ and displayed in Table 1. Results are presented in per unit and degrees.

Table 1: 4 Node State of the System - balanced Approach

V_0	θ_0	V_1	θ_1	V_2	θ_2	V_3	θ_3
1.000	0.00	0.987	-1.59	0.981	-2.40	0.981	-2.40

4 Conclusion

This paper describes a convenient formulation of the Backward/Forward (BW/FW) Sweep Power Flow applied to radial distribution systems with distributed generation. Proposed formulation was applied in an illustrative test system.

5 Nomenclature

List of Symbols

$\mathbf{D}_{\mathbf{Z}}$	Diagonal matrix of branch impedance vector \mathbf{Z}
\mathbf{R}	Diagonal matrix of branch resistance vector $\Re\mathbf{Z}$
\mathbf{X}	Diagonal matrix of branch reactance vector $\Im\mathbf{Z}$
ε	Convergence criteria
\mathbf{I}	Current vector
\mathbf{J}	Branch Current vector \mathbf{J}
n	Number of nodes, excluding origin

P	Active Power Injected vector
Q	Reactive Power Injected vector
P_j	Active Power Injected at node j
Q_j	Reactive Power Injected at node j
P_{Dj}	Active Power Demanded at node j
Q_{Dj}	Reactive Power Demanded at node j
P_{Gj}	Active Power Generated at node j
Q_{Gj}	Reactive Power Generated at node j
R_{ij}	Resistance between node i and node j
S_{Dj}	Apparent Power Demanded at node j
S_{Gj}	Apparent Power Generated at node j
T	Triangular matrix
V	Voltage vector
X_{ij}	Reactance between node i and node j
Z	Branch Impedance vector Z
\overline{Z}^{ij}	Branch Impedance between node i and node j
\mathbf{Z}^{ij}	Impedance matrix between node i and node j

Operators

T	Transpose Matrix
D	Diagonal Matrix
$*$	Conjugate of a complex number

Sub-Indexes

i	Associated to node i
j	Associated to node j
k	Associated to iteration k

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