Four approaches for description of stochastic systems with small and finite inertia

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Abstract. We analyse four approaches to elimination of a fast variable, which are applicable to systems like passive Brownian particles: (i) moment formalism, (ii) corresponding cumulant formalism, (iii) Hermite function basis, (iv) formal 'cumulants' for the Hermit function basis. The accuracy and its strong order are assessed. The applicability and performance of two first approaches are also demonstrated for active Brownian particles.

1. Introduction

Characterization of dynamics of overdamped systems can be often reduced to a single variable, which can be coordinate for mechanical systems in a viscous media (like Brownian particles) [1, 2, 3] or an oscillation phase for self-sustained periodic oscillators [4, 5], where the transversal deviations from the limit cycle decay quick enough to be neglected. However, in stochastic systems with delta-correlated noise, this reduction becomes nontrivial as the inertia term is non-small for rapid fluctuations in mechanical systems [1, 2, 3, 6, 7, 8] and the deviations from the limit cycle are non-negligible for oscillatory systems [9, 10, 11]. For the phase equation of oscillatory systems, an effective inertia-like term may appear owing to different reasons leading to a significant increase of the dynamics complexity [12, 13, 14, 15, 16]. The problem of the transition to the small inertia limit, in other words, the problem of adiabatic elimination of a fast variable (velocity), was thoroughly addressed in the literature for passive Brownian particles [1, 2, 3, 6, 7, 8] and for some types of active Brownian particles [17].

Recently, a systematic approach to the construction of low-dimensional model reductions for oscillator populations was suggested on the basis of the circular cumulant representation [18, 19, 20]; this approach generalizes the Ott-Antonsen ansatz [21, 22] based on the Watanabe–Strogatz partial integrability [23, 24, 25, 26]. Application of this new approach to systems with non-negligible inertia necessitates a systematic analysis of possible approaches to the problem of elimination of a fast variable. In this paper we provide such an analysis with the focus on non-conventional techniques.

2. Results

We consider the Langevin equation with inertia

$$\mu \ddot{\varphi} + \dot{\varphi} = F(\varphi, t) + \sigma \xi(t), \qquad \mu \ll 1, \tag{1}$$

where μ is mass or a measure of 'inertia' in the system (for Josephson junctions [16], power grid models [27, 28], etc.), F is a deterministic force, σ is the noise strength, $\xi(t)$ is a normalized δ -correlated Gaussian noise: $\langle \xi \rangle = 0$, $\langle \xi(t) \xi(t') \rangle = 2\delta(t - t')$.

The Fokker–Planck equation for the probability density $\rho(v, \varphi)$, where $v \equiv \dot{\varphi}$, reads

$$\partial_t \rho = -v \partial_\varphi \rho + \partial_v \left[\frac{1}{\mu} \left(v - F(\varphi, t) \right) \rho \right] + \frac{\sigma^2}{\mu^2} \partial_v^2 \rho \tag{2}$$

(φ may be in a rotating reference frame, where it is useful).

Our aim is to eliminate the velocity and consider effective dynamics solely for φ . We analyse four approaches to accomplishing this task:

- Moment formalism: representation in terms of w_n(φ) = ∫^{+∞}_{-∞} vⁿρ(v, φ) dv; calculations with equations (3)–(5) (or equation (29) for active Brownian particles). Adiabatic elimination requires elements 0–2; the μ¹-correction: 0–4; the μ^m-approximation: 0–(2m + 2).
- Cumulant formalism: representation in terms of $K_n(\varphi)$ (or $\varkappa_n = \frac{K_n}{n!}$), defined as follows: $f(s,\varphi) = \sum_{n=0}^{\infty} w_n(\varphi) \frac{s^n}{n!}$, $\ln f = \phi(s,\varphi) = \sum_{n=0}^{\infty} K_n(\varphi) \frac{s^n}{n!}$ [29]; calculations with equations (12)–(13).

Adiabatic elimination requires elements 0–2; the μ^1 -correction: 0–2 (for the adiabatic elimination fewer number of contributions for these elements are included); the μ^m -approximation: 0–(m + 1).

• Basis of Hermite functions $h_n(u)$, which are the eigenfunctions of operator $\hat{L}_1 = \partial_u(u + \partial_u)$:

$$\rho(v,\varphi) = \sum_{n=0}^{\infty} \frac{\sigma}{\sqrt{\mu}} h_n\left(\frac{\sqrt{\mu}}{\sigma}v\right) W_n(\varphi,t);$$

calculations with equations (16)-(17).

Adiabatic elimination requires elements 0–1; the μ^1 -correction: 0–2; the μ^m -approximation: 0–(m + 1).

• An analogue of the cumulant representation for the basis of Hermite functions: representation in terms of \varkappa_n defined via $f(s,\varphi) = \sum_{n=0}^{\infty} W_n(\varphi)s^n$ (notice, no n!) and $\ln f = \phi(s,\varphi) = \sum_{n=0}^{\infty} \varkappa_n(\varphi)s^n$;

calculations with equations (20)-(21).

Adiabatic elimination requires elements 0–1; the μ^1 -correction: 0–2; the μ^m -approximation: 0–(m + 1).

The numerical simulations for $F = 0.5 - 1.8 \sin \varphi$, which is relevant for the study [12], revealed the following. The actual accuracy of all approximations for a given order of approximation is practically the same. Meanwhile, the behavior of elements with *n* significantly differs. The most regular scaling with the growth on *n* is observed for 'cumulants' for the Hermite basis. For the plain cumulants, the \varkappa_2 is large, as it should be, but the higher-order elements gradually decay. Noticeably, in spite these elements are not as small as the 'cumulants' for the Hermite basis, the truncation at the same *m*-th element leads to the same accuracy for the probability density evolution of φ .

For the case of active Brownian particles [17, 30, 31, 32], one can immediately employ the moment or cumulant formalisms, while the Hermit function basis needs to be significantly

corrected. With the latter approach an individual mathematical preparation for each new problem is required, which can be problematic. Generally, calculations with system (29) for active Brownian particles requires a large number of terms in series and might suffer from numerical instabilities. We overcome these challenges by employing a modification [33] of the exponential time differencing method [34] which provides high performance and accuracy for stiff systems.

3. Methods

3.1. Moment formalism for Fokker–Planck equation One can introduce the moments for v:

$$w_n(\varphi) = \int_{-\infty}^{+\infty} v^n \rho(v,\varphi) \,\mathrm{d}v \,.$$

For these moments the Fokker–Planck equation (2) yields

$$\partial_t w_0 + \partial_\varphi w_1 = 0, \tag{3}$$

$$w_1 + \mu \partial_t w_1 = F w_0 - \mu \partial_\varphi w_2 \,, \tag{4}$$

2

$$w_n + \frac{\mu}{n} \partial_t w_n = F w_{n-1} - \frac{\mu}{n} \partial_\varphi w_{n+1} + (n-1) \frac{\sigma^2}{\mu} w_{n-2} \quad \text{for } n \ge 2.$$
 (5)

For constructing a regular perturbation theory with respect to small parameter μ it is convenient to take the scaling laws for $\langle v^n \rangle$ with respect to μ [8] into account explicitly by means of rescaling

$$w_n = \begin{cases} \frac{1}{\mu^{n/2}} W_n, & \text{for even n};\\ \frac{1}{\mu^{(n-1)/2}} W_n, & \text{for odd n}. \end{cases}$$

Then equations (3)–(5) can be recast in a form free from $1/\mu$ -coefficients:

$$\partial_t W_0 + \partial_\varphi W_1 = 0, \tag{6}$$

$$W_1 = FW_0 - \partial_{\varphi}W_2 - \mu \partial_t W_1 \,, \tag{7}$$

$$W_n = (n-1)\sigma^2 W_{n-2} + \mu \left[F W_{n-1} - \frac{1}{n} \partial_{\varphi} W_{n+1} - \frac{1}{n} \partial_t W_n \right] \qquad \text{for } n = 2m \,, \tag{8}$$

$$W_n = (n-1)\sigma^2 W_{n-2} + FW_{n-1} - \frac{1}{n}\partial_{\varphi}W_{n+1} - \frac{\mu}{n}\partial_t W_n \qquad \text{for } n = 2m+1.$$
(9)

3.1.1. Elimination of a fast variable System (6)–(9) for $\mu = 0$ yields, after some algebra [8],

$$\partial_t W_0 + \partial_\varphi (FW_0) - \sigma^2 \partial_\varphi^2 W_0 = 0.$$
⁽¹⁰⁾

Thus, we obtain a conventional Fokker–Planck equation for W_0 , and all $W_{n\geq 1}$ are trivially determined by W_0 (see [8] for detailed equations).

Keeping μ^1 -corrections for W_0 , one can find from the infinite equation system (6)–(9) [8];

$$\partial_t W_0 + \partial_{\varphi} \left[\left(F - \mu (\partial_t F + F \partial_{\varphi} F) \right) W_0 \right] - \sigma^2 \partial_{\varphi} \left[\left(1 - \mu \partial_{\varphi} F \right) \partial_{\varphi} W_0 \right] = 0.$$
(11)

This is the corrected Smoluchowski equation [2, 6].

The conventional adiabatic elimination of a fast variable requires first three moments w_0 , w_1 , w_2 ; the first correction for small μ requires w_3 and w_4 . Running equation system (3)–(5) for w_0 , w_1 , ..., w_{2m+2} with formal closure $w_{2m+3} = 0$ yields the order of accuracy μ^m .

3.2. Cumulant formalism

The equation system for w_n ,

$$nw_n + \mu \partial_t w_n = nFw_{n-1} - \mu \partial_{\varphi} w_{n+1} + n(n-1)\frac{\sigma^2}{\mu} w_{n-2} \,,$$

in terms of $f(s,\varphi) = \sum_{n=0}^{+\infty} w_n \frac{s^n}{n!}$ acquires the following form:

$$(s\partial_s + \mu\partial_t)f = (sF - \mu\partial_s\partial_\varphi + s^2\frac{\sigma^2}{\mu})f$$

For $\phi = \ln f$, $\partial f = f \partial \phi$,

$$(s\partial_s + \mu\partial_t)\phi = sF + s^2 \frac{\sigma^2}{\mu} - \mu[\partial_s \partial_\varphi \phi + (\partial_s \phi)(\partial_\varphi \phi)].$$

With $\phi = \sum_{n=0}^{+\infty} K_n \frac{s^n}{n!}$,

$$\mu \partial_t K_0 = -\mu [\partial_\varphi K_1 + K_1 \partial_\varphi K_0], \qquad (12)$$

$$(n+\mu\partial_t)K_n = F\delta_{1n} + \frac{2\sigma^2}{\mu}\delta_{2n} - \mu \left[\partial_{\varphi}K_{n+1} + \sum_{j=0}^n \frac{n!}{j!(n-j)!}K_{j+1}\partial_{\varphi}K_{n-j}\right] \quad \text{for } n \ge 1.$$
(13)

Notice, with equations (12)–(13), the conventional elimination of a fast variable requires the first three cumulants (or w_0 , w_1 , w_2 with equations (3)–(5)); the first correction for small μ requires additionally w_3 and w_4 , while, as was shown in [8], within the framework of a cumulant formalism the same first three equations of (12)–(13) are sufficient to obtain

$$\partial_{t}K_{0} = -(\partial_{\varphi} + K_{0}') \left[F - \sigma^{2}K_{0}' + \mu(\partial_{t}F + F'F + \sigma^{2}F'K_{0}') \right] + \mathcal{O}(\mu^{2}),$$
(14)

$$K_{1} = F - \sigma^{2}K_{0}' - \mu \left(\partial_{t}F + F'F + \sigma^{2}F'K_{0}' \right) + \mathcal{O}(\mu^{2}),$$
(14)

$$K_{2} = \frac{\sigma^{2}}{\mu} - \sigma^{2}F' + \sigma^{4}K_{0}'' + \mathcal{O}(\mu).$$

We can see that equation (14) is equivalent to corrected Smoluchowski equation (11), if one substitutes $K_0 = \ln W_0$ and notices that $\partial K_0 = W_0^{-1} \partial W_0$, $(\partial_{\varphi} + K'_0)(\cdot) = W_0^{-1} \partial_{\varphi}(W_0(\cdot))$.

To summarize, cumulant equations (12)–(13) for finite μ are significantly more lengthy, than equations for moments w_n . However, the convergence properties of K_n for $\mu \to 0$ are better, than that of w_n . The adiabatic elimination of velocity in terms of K_n and w_n requires the first three elements. However, the μ^1 -correction to the Smoluchowski equation in terms of w_n requires 5 terms (see [6] for the multiple-dimension case), while in terms of cumulants K_n the same first three elements K_0 , K_1 , K_2 are sufficient. Generally, for the μ^m -correction one needs the leading order accuracy for K_{m+1} , i.e., the first m + 2 cumulants are required. Meanwhile, in terms of w_n (or W_n), one needs the first 2m + 3 moments.

3.3. Basis of Hermite functions

A conventional way for handling the fast velocity variable in the Fokker–Planck equation is the employment of the basis of Hermite functions for v [2, 12]. For operator $\hat{L}_1 = \partial_u (u + \partial_u)$ —which lies in the foundation of the adiabatic elimination of the velocity in FP equation (2) for $\rho(v, \varphi)$:

$$\partial_t \rho = -v \partial_{\varphi} \rho + \partial_v \left[\frac{1}{\mu} \left(v - F(\varphi, t) \right) \rho \right] + \frac{\sigma^2}{\mu^2} \partial_v^2 \rho$$

—one can see that $\hat{L}_1 h_n(u) = -nH_n(u)$,

$$h_n(u) = H_n(u) \frac{1}{\sqrt{2\pi}} e^{-u^2/2}$$

 $H_n(u)$ is the *n*-th Hermite polynomial of the order *n*, which obeys

$$H_n'' - uH_n' = -nH_n. aga{15}$$

With normalization condition

$$\int_{-\infty}^{+\infty} \mathrm{d}u \, h_n(u) h_m(u) = \frac{n! \, \delta_{nm}}{\sqrt{2\pi}}$$

(which provides $\int_{-\infty}^{+\infty} du h_0(u) = 1$), the following recursive formulae are valid: $H'_n = nH_{n-1}$ and $uH_n = nH_{n-1} + H_{n+1}$. With these recursive formulae, the Fokker–Planck equation (2) (see also equation (4) in [12]) for

$$\rho = \sum_{n=0}^{\infty} \frac{\sigma}{\sqrt{\mu}} h_n \left(\frac{\sqrt{\mu}}{\sigma}v\right) W_n(\varphi, t)$$

yields

$$\dot{W}_0 = -\frac{\sigma}{\sqrt{\mu}} \partial_{\varphi} W_1 \,, \tag{16}$$

$$\dot{W}_n = \frac{\sigma}{\sqrt{\mu}} \left((\sigma^{-2}F - \partial_{\varphi})W_{n-1} - (n+1)\partial_{\varphi}W_{n+1} \right) - \frac{n}{\mu}W_n \quad \text{for } n \ge 1.$$
(17)

3.3.1. Elimination of a fast variable For $\mu \ll 1$, it is more convenient to rewrite equations (16)–(17) as

$$\dot{W}_0 = -\frac{\sigma}{\sqrt{\mu}} \partial_{\varphi} W_1 \,, \tag{18}$$

$$W_n = \frac{\sqrt{\mu}\sigma}{n} \left((\sigma^{-2}F - \partial_{\varphi})W_{n-1} - (n+1)\partial_{\varphi}W_{n+1} \right) - \frac{\mu}{n}\partial_t W_n \quad \text{for } n \ge 1.$$
(19)

With equations (18)–(19), one finds $W_n \sim \mu^{n/2}$.

Taking the leading order for W_N , one has $\operatorname{error}(W_N) \sim \mu^{N/2+1}$, $\operatorname{error}(W_{N-1}) \sim \mu^{N/2+1+1/2}$, ..., $\operatorname{error}(W_1) \sim \mu^{N/2+1+(N-1)/2}$, and $\operatorname{error}(\partial_t W_0) \sim \mu^N$. Thus, the truncation after W_N leads to inaccuracy $\sim \mu^N$.

3.4. "Cumulant" formalism for the Hermite function basis

Let us construct an analogue of cumulant representation for v. For generating function $f(s,\varphi) = \sum_{n=0}^{\infty} W_n(\varphi) s^n$ (it will be essential below to use s^n , but not $s^n/n!$), one finds

$$\dot{f} = \frac{\sigma}{\sqrt{\mu}} \left(s(\sigma^{-2}F - \partial_{\varphi})f - \partial_{s}\partial_{\varphi}f \right) - \frac{1}{\mu}s\partial_{s}f$$

For $\Phi = \ln f$, $\partial \Phi = \partial f / f$,

$$\dot{\Phi} = \frac{\sigma}{\sqrt{\mu}} \left(s(\sigma^{-2}F - \partial_{\varphi}\Phi) - \partial_{s}\partial_{\varphi}\Phi - (\partial_{s}\Phi)(\partial_{\varphi}\Phi) \right) - \frac{1}{\mu}s\partial_{s}\Phi$$

With $\Phi(s,\varphi) = \sum_{n=0}^{\infty} \varkappa_n(\varphi) s^n$, the latter equation yields

$$\dot{\varkappa}_0 = -\frac{\sigma}{\sqrt{\mu}} (\partial_\varphi \varkappa_1 + \varkappa_1 \partial_\varphi \varkappa_0) \,, \tag{20}$$

$$\dot{\varkappa}_n = \frac{\sigma}{\sqrt{\mu}} \left(\sigma^{-2} F \delta_{1n} - \partial_{\varphi} \varkappa_{n-1} - (n+1) \partial_{\varphi} \varkappa_{n+1} - \sum_{\substack{n_1 + n_2 \\ = n+1}} n_1 \varkappa_{n_1} \partial_{\varphi} \varkappa_{n_2} \right) - \frac{n}{\mu} \varkappa_n \quad \text{for } n \ge 1 \,. \tag{21}$$

For $\mu \ll 1$, it is convenient to recast the latter system as

$$\dot{\varkappa}_{0} = -\frac{\sigma}{\sqrt{\mu}} (\partial_{\varphi} \varkappa_{1} + \varkappa_{1} \partial_{\varphi} \varkappa_{0}), \qquad (22)$$
$$\varkappa_{n} = \frac{\sqrt{\mu} \sigma}{n} \left(\sigma^{-2} F \delta_{1n} - \partial_{\varphi} \varkappa_{n-1} - (n+1) \partial_{\varphi} \varkappa_{n+1} - \sum_{\substack{n_{1}+n_{2} \\ =n+1}} n_{1} \varkappa_{n_{1}} \partial_{\varphi} \varkappa_{n_{2}} \right) - \frac{\mu}{n} \partial_{t} \varkappa_{n} \quad \text{for } n \ge 1.$$

For the μ^1 -approximation,

$$\dot{\varkappa}_0 = -(\varkappa'_0 + \partial_\varphi) \left[F - \mu(\partial_t + F')F - \sigma^2(1 - \mu F')\varkappa'_0 \right] + \mathcal{O}(\mu^2) \,, \tag{24}$$

$$\varkappa_1 = \sqrt{\mu} \,\sigma \left(\sigma^{-2} F - \partial_{\varphi} \varkappa_0 - \mu \left[\sigma^{-2} (\partial_t + F') F - F' \varkappa'_0 \right] \right) + \mathcal{O}(\mu^{5/2}) \,, \tag{25}$$

$$\varkappa_2 = -\frac{\sqrt{\mu}\sigma}{2}\partial_{\varphi}\varkappa_1 + \mathcal{O}(\mu^2).$$
⁽²⁶⁾

Equation (24) is equivalent to (11) (see explanations after equation (14)). For system (22)–(23), $\varkappa_n \sim \mu^{n/2}$; the μ^N -approximation requires truncation after \varkappa_{N+1} . Here, there seems to be no preference between the W_n - and \varkappa_n -representations, except the equations in terms of \varkappa_n are more lengthy.

In this subsection, it is essential that the definition of the generating function $f(s, \varphi)$ with $W_n s^n / n!$ is inappropriate, since such a definition leads to the term $\partial_s^{-1} f$ in the governing equation for f; this term cannot be represented with simple regular sums in terms of \varkappa_n .

3.5. Moment and cumulant formalisms for active Brownian particles Let us consider the following Langevin equation

$$\mu \ddot{\varphi} + \alpha \dot{\varphi} + \beta \dot{\varphi}^3 = F(\varphi, t) + \sigma \xi(t) , \quad \mu \ll 1 , \qquad (27)$$

where $\beta > 0$. This example can be useful only as an illustration since the fluctuation term and the leading dissipation term here are not in concordance with the Fluctuation–Dissipation Theorem.

With the Fokker–Planck equation

$$\partial_t \rho = -v \partial_{\varphi} \rho + \partial_v \left[\frac{\alpha v + \beta v^3 - F(\varphi, t)}{\mu} \rho \right] + \frac{\sigma^2}{\mu^2} \partial_v^2 \rho \,, \tag{28}$$

the moment equation system acquires the following form:

$$\alpha n w_n + \beta n w_{n+2} + \mu \partial_t w_n = n F w_{n-1} - \mu \partial_\varphi w_{n+1} + n(n-1) \frac{\sigma^2}{\mu} w_{n-2} , \qquad (29)$$

which yields in terms of $f(s, \varphi) = \sum_{n=0}^{+\infty} w_n \frac{s^n}{n!}$:

$$(\alpha s\partial_s + \beta s\partial_s^3 + \mu\partial_t)f = (sF - \mu\partial_s\partial_\varphi + s^2\frac{\sigma^2}{\mu})f$$

For $\phi = \ln f$, $\partial f = f \partial \phi$,

$$(\alpha s\partial_s + \mu\partial_t)\phi + \beta s[\partial_s^3\phi + 3\partial_s\phi\partial_s^2\phi + (\partial_s\phi)^3] = sF + s^2\frac{\sigma^2}{\mu} - \mu[\partial_s\partial_\varphi\phi + (\partial_s\phi)(\partial_\varphi\phi)].$$
With $\phi = \sum^{+\infty} K \frac{s^n}{2}$

$$\mu \partial_t K_0 = -\mu [\partial_{\varphi} K_1 + K_1 \partial_{\varphi} K_0], \qquad (30)$$

$$(\alpha n + \mu \partial_t) K_n + \beta n \left[K_{n+2} + 3 \sum_{j=1}^{n} \frac{(n-1)!}{(j-1)!(n-j)!} K_j K_{n+2-j} + \sum_{\substack{j_1+j_2+j_3\\=n+2}}^{n} \frac{(n-1)!}{(j_1-1)!(j_2-1)!(j_3-1)!} K_{j_1} K_{j_2} K_{j_3} \right]$$
$$= F \delta_{1n} + \frac{2\sigma^2}{\mu} \delta_{2n} - \mu \left[\partial_{\varphi} K_{n+1} + \sum_{j=0}^{n} \frac{n!}{j!(n-j)!} K_{j+1} \partial_{\varphi} K_{n-j} \right] \quad \text{for } n \ge 1.$$
(31)

For the first five equations of (30)–(31),

$$\begin{aligned} \partial_t K_0 &= -\partial_{\varphi} K_1 - K_1 \partial_{\varphi} K_0 \,, \\ (\alpha + \mu \partial_t) K_1 + \beta [K_3 + 3K_1 K_2 + K_1^3] &= F - \mu [\partial_{\varphi} K_2 + K_1 \partial_{\varphi} K_1 + K_2 \partial_{\varphi} K_0] \,, \\ (2\alpha + \mu \partial_t) K_2 + 2\beta [K_4 + 3(K_1^2 + K_1 K_3) + 3K_1^2 K_2] \\ &= \frac{2\sigma^2}{\mu} - \mu [\partial_{\varphi} K_3 + K_1 \partial_{\varphi} K_2 + 2K_2 \partial_{\varphi} K_1 + K_3 \partial_{\varphi} K_0] \,, \\ (3\alpha + \mu \partial_t) K_3 + 3\beta [K_5 + 3(3K_3 K_2 + K_1 K_4) + 3K_1^2 K_3 + 6K_2^2 K_1] \\ &= -\mu [\partial_{\varphi} K_4 + K_1 \partial_{\varphi} K_3 + 3K_2 \partial_{\varphi} K_2 + 3K_3 \partial_{\varphi} K_1 + K_4 \partial_{\varphi} K_0] \,, \\ (4\alpha + \mu \partial_t) K_4 + 4\beta [K_6 + 3(4K_4 K_2 + 3K_3^2 + K_1 K_5) + 6K_2^3 + 18K_1 K_2 K_3 + 3K_1^2 K_4] \\ &= -\mu [\partial_{\varphi} K_5 + K_1 \partial_{\varphi} K_4 + 4K_2 \partial_{\varphi} K_3 + 6K_3 \partial_{\varphi} K_2 + 4K_4 \partial_{\varphi} K_1 + K_5 \partial_{\varphi} K_0] \,, \end{aligned}$$

The inspection of equation system (32) reveals the following scaling properties of K_n with respect to μ :

$$K_n \sim \begin{cases} \mu^{-\frac{n}{4}} & \text{for even n,} \\ \mu^{\frac{3}{4}-\frac{n}{4}} & \text{for odd n.} \end{cases}$$

With such scaling properties the β - and σ^2 -terms for even n in equation system (32) dominate and one cannot truncate the equation chain without affecting the leading order with respect to μ . Moreover, one faces similar issue with even n; which is coupled with the F-term in the leading order. Thus, the calculations in the leading order require β -, F- and σ^2 -terms and these calculations in terms of K_n (or w_n) are extremely challenging. This problem can be more efficiently solved with the Fokker–Planck equation (28) where all terms without β , F or σ^2 are dropped. One finds

$$\rho = C(\varphi)e^{\frac{\mu}{\sigma^2}(-\frac{\beta v^4}{4} + Fv)} + \dots$$

where ... stand for higher-order corrections. After laborious but straightforward calculations one can obtain:

$$w_{2n+1} \approx \frac{4F}{\beta} \frac{\Gamma(\frac{n}{2} + \frac{3}{4})}{\Gamma(\frac{1}{4})} \left(\frac{2\sigma}{\sqrt{\beta\mu}}\right)^{n-1} w_0, \qquad (33)$$

$$w_{2n} \approx \frac{\Gamma(\frac{n}{2} + \frac{1}{4})}{\Gamma(\frac{1}{4})} \left(\frac{2\sigma}{\sqrt{\beta\mu}}\right)^n w_0.$$
(34)

Corresponding cumulants:

$$K_{0} = \ln w_{0}, \qquad K_{2} \approx \frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \frac{2\sigma}{\sqrt{\beta\mu}}, \qquad K_{4} \approx -\left(3 \left[\frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})}\right]^{2} - \frac{1}{4}\right) \frac{4\sigma^{2}}{\beta\mu},$$

$$K_{6} \approx 3 \frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \left(10 \left[\frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})}\right]^{2} - 1\right) \left(\frac{2\sigma}{\sqrt{\beta\mu}}\right)^{3}, \dots,$$

$$K_{1} \approx \frac{4F}{\beta} \frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \frac{\sqrt{\beta\mu}}{2\sigma}, \qquad K_{3} \approx -\frac{4F}{\beta} \left(3 \left[\frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})}\right]^{2} - \frac{1}{4}\right),$$

$$K_{5} \approx 3 \frac{4F}{\beta} \frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \left(10 \left[\frac{\Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})}\right]^{2} - 1\right) \frac{2\sigma}{\sqrt{\beta\mu}}, \dots.$$

Obviously, the cumulant representation can be beneficiary mainly for the systems where the distribution of the fast variable is close to the Gaussian distribution. An example of the latter is the case of passive Brownian particles, where the Fluctuation–Dissipation theorem requires the Gaussian distribution for the unperturbed state, and can be often relevant for active Brownian particles, where the leading dissipation term is in concordance with the fluctuations-term.

4. Conclusion

The four analyzed formalisms for elimination of a fast variable (velocity) yield a comparable accuracy for the same strong order of accuracy with respect to the inertia parameter μ (mass). However, for the moment formalism employing $w_n(\varphi) = \int v^n \rho(v, \varphi) dv$, the strong order μ^m requires 2m + 3 equations (from the order 0 to the order 2m + 2); for corresponding cumulants K_n , only m + 2 equations are required (from 0th to (m + 1)th orders); for the Hermite function basis and its formal 'cumulant' version, the same m + 2 equations are required.

For the case of active Brownian particles one cannot employ the Hermite function basis, while one can still use the moment or cumulant formalisms. Practical implementation of these formalisms for numerical simulation can be efficiently performed with employment of a modification of the exponential time differencing method [33].

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