# Bayesian Markov-Switching Vector Autoregressive Process 

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#### Abstract

This study introduces marginal density functions of the general Bayesian Markov-Switching Vector Autoregressive (MS-VAR) process. In the case of the Bayesian MS-VAR process, we provide closed-form density functions and Monte-Carlo simulation algorithms, including the importance sampling method. The Monte-Carlo simulation method departs from the previous simulation methods because it removes the duplication in a regime vector.


Keywords: Bayesian MS-VAR process, Monte-Carlo simulation method, Stochastic DDM.

## 1 Introduction

Classic Vector Autoregressive (VAR) process was proposed by Sims (1980) who criticize large-scale macro-econometric models, which are designed to model interdependencies of economic variables. Besides Sims (1980), there are some other important works on multiple time series modeling, see, e.g., Tiao and Box (1981), where a class of vector autoregressive moving average models was studied. For the VAR process, a variable in the process is modeled by its past values and the past values of other variables in the process. After the work of Sims (1980), VARs have been used for macroeconomic forecasting and policy analysis. However, if the number of variables in the system increases or the time lag is chosen high, then too many parameters need to be estimated. This will reduce the degrees of freedom of the model and entail a risk of over-parametrization.

Therefore, to reduce the number of parameters in a high-dimensional VAR process, Litterman (1979) introduced probability distributions for coefficients that are centered at the desired restrictions but that have a small and nonzero variance. Those probability distributions are known as Minnesota prior in Bayesian VAR (BVAR) literature, which is widely used in practice. Due to overparametrization, the generally accepted result is that the forecast of the BVAR model is better than the VAR model estimated by the frequentist technique. Research works have shown that BVAR is an appropriate tool for modeling large data sets; for example, see Bańbura, Giannone, and Reichlin (2010).

Sudden and dramatic changes in the financial market and economy are caused by events such as wars, market panics, or significant changes in government policies. To model those events, some authors used regime-switching models. The regime-switching model was introduced by seminal works of Hamilton $(1989,1990)$ (see also books of Hamilton (1994) and Krolzig (1997)), and the model is hidden Markov model with dependencies; see Zucchini, MacDonald, and Langrock (2016). However, Markov regime-switching models have been introduced before Hamilton (1989), see, Goldfeld and Quandt (1973), Quandt (1958), and Tong (1983). The regime-switching model assumes that a discrete unobservable Markov process randomly switches among a finite set of regimes and that a particular parameter set defines each regime. The model fits some financial data well and has become popular in financial modeling, including equity options, bond prices, and others.

[^0]A model that considers all of the above is the Bayesian Markov-Switching VAR (MS-VAR) process. Its applications in finance can be found in Battulga (2023b), Battulga (2024a), and Battulga (2024b). In some existing option pricing models, the underlying asset price is governed by some stochastic process, and economic variables such as GDP, inflation, unemployment rate, and so on are not taken into account. For this reason, the author has developed option pricing models, depending on economic variables. Applying the Bayesian MS-VAR process, with direct calculation and change of probability measure for some frequently used options, Battulga (2024b) derived pricing formulas. Also, the author used the Bayesian MS-VAR process to price equity-linked life insurance products and rainbow options, see Battulga (2024a) and Battulga (2023b).

Monte-Carlo simulation methods using the Gibbs sampling algorithm for Bayesian MS-VAR process are proposed by some authors. In particular, the Monte-Carlo simulation method of the Bayesian MS-AR(p) process is provided by Albert and Chib (1993), and its multidimensional extension is given by Krolzig (1997). In this paper, we introduce a new Monte-Carlo simulation method that removes duplication in a regime vector. We also introduce importance sampling method to estimate probability of rare event, which corresponds to endogenous variables. Importance sampling is an effective variance reduction technique for studying the rare events. Glasserman, Heidelberger, and Shahabuddin (2000) used the importance sampling method to model portfolio loss random variable by using approximation. Also, Glasserman and Li (2005) study a loss random variable of credit portfolio applying the method, see also McNeil, Frey, and Embrechts (2005).

Dividend discount models (DDMs), first introduced by Williams (1938), are common methods for stock valuation. The basic idea is that a stock price of a firm is equal to a sum of dividend paid by the firm and the stock price of the firm, which correspond to the next period and which are discounted at required rate of return on stock. As the outcome of DDMs depends crucially on dividend payment forecasts, most research in the last few decades has been around the proper estimations of dividend development. To model the dividends of a firm, Battulga, Jacob, Altangerel, and Horsch (2022) used the compound Poisson process. Also, parameter estimation of DDMs is a challenging task. Battulga et al. (2022) introduced parameter estimation methods for practically popular DDMs. Battulga (2023a) provided parameter estimation methods of the required rate of returns for public and private companies. Under the normal framework, Battulga (2022) obtained pricing and hedging formulas for the European options and equity-linked life insurance products by introducing a DDM with regimeswitching process. A review of some existing DDMs, including deterministic and stochastic models can be found in D'Amico and De Blasis (2020).

The rest of the paper is organized as follows: In Section 2, for the general Bayesian MS-VAR process, we obtain some conditional density functions, which are helpful for general Monte-Carlo simulation. Section 3 is dedicated to studying a special case of the process, where we obtain closedform conditional density functions of our model's random components. Some of the conditional density functions have not been explored before. In Section 3, we provide Monte-Carlo simulation methods, including the importance sampling method. Section 4 gives numerical results on three companies, listed in the S\&P 500 index. Finally, Section 5 concludes the study.

## 2 Bayesian MS-VAR ( $p$ ) process

Let $\left(\Omega, \mathcal{H}_{T}, \mathbb{P}\right)$ be a complete probability space, where $\mathbb{P}$ is a given physical or real-world probability measure. Other elements of the probability space will be defined below. To introduce a regimeswitching, we assume that $\left\{s_{t}\right\}_{t=1}^{T}$ is a homogeneous Markov chain with $N$ state and $P:=\left\{p_{i j}\right\}_{i=0, j=1}^{N}$ is a random transition probability matrix, including an initial probability vector, where $\left\{p_{0 j}\right\}_{j=1}^{N}$ is the initial probability vector. We consider a Bayesian Markov-Switching Vector Autoregressive process of $p$ order $(\operatorname{MS}-\operatorname{VAR}(p))$, which is given by the following equation

$$
\begin{equation*}
y_{t}=A_{0, s_{t}} \psi_{t}+A_{1, s_{t}} y_{t-1}+\cdots+A_{p, s_{t}} y_{t-p}+\xi_{t}, t=1, \ldots, T, \tag{1}
\end{equation*}
$$

where $y_{t}=\left(y_{1, t}, \ldots, y_{n, t}\right)^{\prime}$ is an $(n \times 1)$ vector of endogenous variables, $\psi_{t}=\left(1, \psi_{2, t}, \ldots, \psi_{l, t}\right)^{\prime}$ is an $(l \times 1)$ vector of exogenous variables, $\xi_{t}=\left(\xi_{1, t}, \ldots, \xi_{n, t}\right)^{\prime}$ is an $(n \times 1)$ residual process, $A_{0, s_{t}}$ is an $(n \times l)$ random coefficient matrix at regime $s_{t}$, corresponding to the vector of exogenous variables, for $i=1, \ldots, p, A_{i, s_{t}}$ are $(n \times n)$ random coefficient matrices at regime $s_{t}$, corresponding to $y_{t-1}, \ldots, y_{t-p}$. Equation (1) can be written by

$$
\begin{equation*}
y_{t}=\Pi_{s_{t}} Y_{t}+\xi_{t}, t=1, \ldots, T \tag{2}
\end{equation*}
$$

where $\Pi_{s_{t}}:=\left[A_{0, s_{t}}: A_{1, s_{t}}: \cdots: A_{p, s_{t}}\right]$ is an $(n \times d)$ random coefficient matrix with $d:=l+n p$ at regime $s_{t}$, which consist of all the random coefficient matrices and $\mathrm{Y}_{t}:=\left(\psi_{t}^{\prime}, y_{t-1}^{\prime}, \ldots, y_{t-p}^{\prime}\right)^{\prime}$ is a $(d \times 1)$ vector, which consist of exogenous variable $\psi_{t}$ and last $p$ lagged values of the process $y_{t}$. The process $\mathrm{Y}_{t}$ is measurable with respect to a $\sigma$-field $\mathcal{F}_{t-1}$, which is defined below.

For the residual process $\xi_{t}$, we assume that it has $\xi_{t}:=\Sigma_{s_{t}}^{1 / 2} \varepsilon_{t}, t=1, \ldots, T$ representation, see Lütkepohl (2005) and McNeil et al. (2005), where $\Sigma_{s_{t}}^{1 / 2}$ is a Cholesky factor of a positive definite ( $n \times n$ ) random matrix $\Sigma_{s_{t}}$, which is measurable with respect to $\sigma$-field $\mathcal{H}_{t-1}$, defined below and depends on $\left(n_{*} \times d_{*}\right)$ random coefficient matrix $\Gamma_{s_{t}}:=\left[B_{0, s_{t}}: B_{1, s_{t}}: \cdots: B_{p_{*}+q_{*}, s_{t}}\right]$ with $d_{*}:=l_{*}+n_{*}\left(p_{*}+q_{*}\right)$. Here $B_{0, s_{t}}$ is an ( $n_{*} \times l_{*}$ ) random matrix, for $i=1, \ldots, p_{*}+q_{*}, B_{i, s_{t}}$ are ( $n_{*} \times n_{*}$ ) random matrices, and $\varepsilon_{1}, \ldots, \varepsilon_{T}$ is a random sequence of independent identically multivariate normally distributed random vectors with means of 0 and covariance matrices of $n$ dimensional identity matrix $I_{n}$. Then, in particular, for multivariate GARCH process of $\left(p_{*}, q_{*}\right)$ order, dependence of $\Sigma_{s_{t}}^{1 / 2}$ on $\Gamma_{s_{t}}$ is given by

$$
\begin{equation*}
\operatorname{vech}\left(\Sigma_{s_{t}}\right)=B_{0, s_{t}}+\sum_{i=1}^{p_{*}} B_{i, s_{t}} \operatorname{vech}\left(\xi_{t-i} \xi_{t-i}^{\prime}\right)+\sum_{j=1}^{q_{*}} B_{p_{*}+j, s_{t}} \operatorname{vech}\left(\Sigma_{s_{t}-j}\right) \tag{3}
\end{equation*}
$$

where $B_{0, s_{t}}$ and $B_{i, s_{t}}$ for $i=1, \ldots, p_{*}+q_{*}$ are suitable $([n(n+1) / 2] \times 1)$ random vector and suitable $([n(n+1) / 2] \times[n(n+1) / 2])$ matrices, respectively, and the vech is an operator that stacks elements on and below a main diagonal of a square matrix.

Let us introduce stacked vectors and matrices: $y:=\left(y_{1}^{\prime}, \ldots, y_{T}^{\prime}\right)^{\prime}, s:=\left(s_{1}, \ldots, s_{T}\right)^{\prime}, \Pi_{s}:=\left[\Pi_{s_{1}}\right.$ : $\left.\cdots: \Pi_{s_{T}}\right]$, and $\Gamma_{s}:=\left[\Gamma_{s_{1}}: \cdots: \Gamma_{s_{T}}\right]$. We also assume that the strong white noise process $\left\{\varepsilon_{t}\right\}_{t=1}^{T}$ is independent of the random coefficient matrices $\Pi_{s}$ and $\Gamma_{s}$, random transition matrix P , and regime vector $s$ conditional on initial information $\mathcal{F}_{0}:=\sigma\left(y_{1-p}^{\prime}, \ldots, y_{0}^{\prime}, \psi_{1}, \ldots, \psi_{T}, \Sigma_{1-q_{*}}, \ldots, \Sigma_{0}\right)$. Here for a generic random vector $X, \sigma(X)$ denotes a $\sigma$-field generated by the random vector $X, \Sigma_{1-q_{*}}, \ldots, \Sigma_{0}$ is initial values of the random matrix process $\Sigma_{s t}, \psi_{1}, \ldots, \psi_{T}$ are values of exogenous variables and they are known at time zero. We further suppose that the transition probability matrix $P$ is independent of the random coefficient matrices $\Pi_{s}$ and $\Gamma_{s}$ given initial information $\mathcal{F}_{0}$ and regime vector $s$.

To ease of notations, for a generic vector $o=\left(o_{1}^{\prime}, \ldots, o_{T}^{\prime}\right)^{\prime}$, we denote its first $t$ and last $T-t$ sub vectors by $\bar{o}_{t}$ and $\bar{o}_{t}^{c}$, respectively, that is, $\bar{o}_{t}:=\left(o_{1}^{\prime}, \ldots, o_{t}^{\prime}\right)^{\prime}$ and $\bar{o}_{t}^{c}:=\left(o_{t+1}^{\prime}, \ldots, o_{T}^{\prime}\right)^{\prime}$. We define $\sigma$-fields: for $t=0, \ldots, T, \mathcal{F}_{t}:=\mathcal{F}_{0} \vee \sigma\left(\bar{y}_{t}\right)$ and $\mathcal{H}_{t}:=\mathcal{F}_{t} \vee \sigma\left(\Pi_{s}\right) \vee \sigma\left(\Gamma_{s}\right) \vee \sigma(s) \vee \sigma(\mathrm{P})$ where for generic sigma fields $\mathcal{O}_{1}$ and $\mathcal{O}_{2}, \mathcal{O}_{1} \vee \mathcal{O}_{2}$ is the minimal $\sigma$-field containing the $\sigma$-fields $\mathcal{O}_{1}$ and $\mathcal{O}_{2}$. For the first-order Markov chain, a conditional probability that the regime at time $t+1, s_{t+1}$ equals some particular value conditional on the past regimes $\bar{s}_{t}$, transition probability matrix P , and initial information $\mathcal{F}_{0}$ depends only through the most recent regime at time $t$, $s_{t}$, transition probability matrix P , and initial information $\mathcal{F}_{0}$, that is,

$$
\begin{equation*}
p_{s_{t} s_{t+1}}:=\mathbb{P}\left[s_{t+1}=s_{t+1} \mid s_{t}=s_{t}, \mathrm{P}, \mathcal{F}_{0}\right]=\mathbb{P}\left[s_{t+1}=s_{t+1} \mid \bar{s}_{t}=\bar{s}_{t}, \mathrm{P}, \mathcal{F}_{0}\right] \tag{4}
\end{equation*}
$$

for $t=0, \ldots, T-1$, where $p_{s_{1}}:=p_{s_{0} s_{1}}=\mathbb{P}\left[s_{1}=s_{1} \mid \mathrm{P}, \mathcal{F}_{0}\right]$ is an initial probability. A distribution of a residual random vector $\xi:=\left(\xi_{1}^{\prime}, \ldots, \xi_{T}^{\prime}\right)^{\prime}$ is given by

$$
\begin{equation*}
\xi=\left(\xi_{1}^{\prime}, \ldots, \xi_{T}^{\prime}\right)^{\prime} \mid \mathcal{H}_{0} \sim \mathcal{N}\left(0, \Sigma_{s}\right) \tag{5}
\end{equation*}
$$

where $\Sigma_{s}:=\operatorname{diag}\left\{\Sigma_{s_{1}}, \ldots, \Sigma_{s_{T}}\right\}$ is a block diagonal matrix.

To remove duplicates in the random coefficient matrix $\left(\Pi_{s}, \Gamma_{s}\right)$, for a generic regime vector with length $k, o=\left(o_{1}, \ldots, o_{k}\right)^{\prime}$, we define sets

$$
\begin{equation*}
\mathcal{A}_{\bar{o}_{t}}:=\mathcal{A}_{\bar{o}_{t-1}} \cup\left\{o_{t} \in\left\{o_{1}, \ldots, o_{k}\right\} \mid o_{t} \notin \mathcal{A}_{\bar{o}_{t-1}}\right\}, \quad t=1, \ldots, k, \tag{6}
\end{equation*}
$$

where for $t=1, \ldots, k, o_{t} \in\{1, \ldots, N\}$ and an initial set is empty set, i.e., $\mathcal{A}_{\bar{o}_{0}}=\emptyset$. The final set $\mathcal{A}_{o}=\mathcal{A}_{\bar{o}_{k}}$ consists of different regimes in regime vector $o=\bar{o}_{k}$ and $\left|\mathcal{A}_{o}\right|$ represents a number of different regimes in the regime vector $o$.

Let us assume that elements of sets $\mathcal{A}_{s}, \mathcal{A}_{\bar{s}_{t}}, \mathcal{A}_{\bar{s}_{t}^{c}}$, intersection set of the sets $\mathcal{A}_{\bar{s}_{t}}$ and $\mathcal{A}_{\bar{s}_{t}^{c}}$, and difference sets between the sets $\mathcal{A}_{\bar{s}_{t}^{c}}$ and $\mathcal{A}_{\bar{s}_{t}}$ are given by $\mathcal{A}_{s}=\left\{\hat{s}_{1}, \ldots, \hat{s}_{r_{\hat{s}}}\right\}, \mathcal{A}_{\bar{s}_{t}}=\left\{\alpha_{1}, \ldots, \alpha_{r_{\alpha}}\right\}$, $\mathcal{A}_{\bar{s}_{t}^{c}}=\left\{\beta_{1}, \ldots, \beta_{r_{\beta}}\right\}, \mathcal{A}_{\bar{s}_{t}} \cap \mathcal{A}_{\bar{s}_{t}^{c}}=\left\{\gamma_{1}, \ldots, \gamma_{r_{\gamma}}\right\}, \mathcal{A}_{\bar{s}_{t}^{c}} \backslash \mathcal{A}_{\bar{s}_{t}}=\left\{\delta_{1}, \ldots, \delta_{r_{\delta}}\right\}$, and $\mathcal{A}_{\bar{s}_{t}} \backslash \mathcal{A}_{\bar{s}_{t}^{c}}=\left\{\epsilon_{1}, \ldots, \epsilon_{r_{\epsilon}}\right\}$, respectively, where $r_{\hat{s}}:=\left|\mathcal{A}_{s}\right|, r_{\alpha}:=\left|\mathcal{A}_{\bar{s}_{t}}\right|, r_{\beta}:=\left|\mathcal{A}_{\bar{s}_{t}^{c}}\right|, r_{\gamma}:=\left|\mathcal{A}_{\bar{s}_{t}} \cap \mathcal{A}_{\bar{s}_{t}^{c}}\right|, r_{\delta}:=\left|\mathcal{A}_{\bar{s}_{t}^{c}} \backslash \mathcal{A}_{\bar{s}_{t}}\right|$, and $r_{\epsilon}:=\left|\mathcal{A}_{\bar{s}_{t}} \backslash \mathcal{A}_{\bar{s}_{t}^{c}}\right|$ are numbers of elements of the sets, respectively. Note that

$$
\begin{align*}
& \mathcal{A}_{\bar{s}_{t}}=\left(\mathcal{A}_{\bar{s}_{t}} \backslash \mathcal{A}_{\bar{s}_{t}^{c}}\right) \cup\left(\mathcal{A}_{\bar{s}_{t}} \cap \mathcal{A}_{\bar{s}_{t}^{c}}\right),  \tag{7}\\
& \mathcal{A}_{\bar{s}_{t}^{c}}=\left(\mathcal{A}_{\bar{s}_{t}} \cap \mathcal{A}_{\bar{s}_{t}^{c}}\right) \cup\left(\mathcal{A}_{\bar{s}_{t}^{c}} \backslash \mathcal{A}_{\bar{s}_{t}}\right), \tag{8}
\end{align*}
$$

and

$$
\begin{equation*}
\mathcal{A}_{s}=\mathcal{A}_{\bar{s}_{t}} \cup \mathcal{A}_{\bar{s}_{t}^{c}}=\left(\mathcal{A}_{\bar{s}_{t}} \backslash \mathcal{A}_{\bar{s}_{t}^{c}}\right) \cup \mathcal{A}_{\bar{s}_{t}^{c}}=\mathcal{A}_{\bar{s}_{t}} \cup\left(\mathcal{A}_{\bar{s}_{t}^{c}} \backslash \mathcal{A}_{\bar{s}_{t}}\right) \tag{9}
\end{equation*}
$$

and intersection sets of the sets of right hand sides of equations (7) and (8), and (9) are empty sets. We introduce the following regime vectors: $\hat{s}:=\left(\hat{s}_{1}, \ldots, \hat{s}_{r_{\hat{s}}}\right)^{\prime}$ is an $\left(r_{\hat{s}} \times 1\right)$ vector, $\alpha:=\left(\alpha_{1}, \ldots, \alpha_{r_{\alpha}}\right)^{\prime}$ is an $\left(r_{\alpha} \times 1\right)$ vector, $\beta=\left(\beta_{1}, \ldots, \beta_{r_{\beta}}\right)^{\prime}$ is an $\left(r_{\beta} \times 1\right)$ vector, $\gamma=\left(\gamma_{1}, \ldots, \gamma_{r_{\gamma}}\right)^{\prime}$ is an $\left(r_{\gamma} \times 1\right)$ vector, $\delta=\left(\delta_{1}, \ldots, \delta_{r_{\delta}}\right)^{\prime}$ is an $\left(r_{\delta} \times 1\right)$ vector, and $\epsilon=\left(\epsilon_{1}, \ldots, \epsilon_{r_{\epsilon}}\right)^{\prime}$ is an $\left(r_{\epsilon} \times 1\right)$ vector. For the regime vector $a=\left(a_{1}, \ldots, a_{r_{a}}\right)^{\prime} \in\{\hat{s}, \alpha, \beta, \gamma, \delta, \epsilon\}$, we also introduce duplication removed random coefficient matrices, whose block matrices are different: $\Pi_{a}=\left[\Pi_{a_{1}}: \cdots: \Pi_{a_{r_{a}}}\right]$ is an $\left(n \times\left[d r_{a}\right]\right)$ matrix, $\Gamma_{a}=\left[\Gamma_{a_{1}}: \cdots: \Gamma_{a_{r_{a}}}\right]$ is an $\left(n_{*} \times\left[d_{*} r_{a}\right]\right)$ matrix, and $\left(\Pi_{a}, \Gamma_{a}\right)$.

We assume that for given duplication removed regime vector $\hat{s}$ and initial information $\mathcal{F}_{0}$, the coefficient matrices $\left(\Pi_{\hat{s}_{1}}, \Gamma_{\hat{s}_{1}}\right), \ldots,\left(\Pi_{\hat{s}_{r_{\hat{s}}}}, \Gamma_{\hat{s}_{r_{\hat{s}}}}\right)$ are independent. Under the last assumption, a joint density function of the random coefficient random matrix $\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}}\right)$ is represented by

$$
\begin{equation*}
f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid \hat{s}, \mathcal{F}_{0}\right)=\prod_{t=1}^{r_{\hat{s}}} f\left(\Pi_{\hat{s}_{t}}, \Gamma_{\hat{s}_{t}} \mid \hat{s}_{t}, \mathcal{F}_{0}\right) \tag{10}
\end{equation*}
$$

where for a generic random vector $X$, we denote its density function by $f(X)$. Throughout the paper we fix $t=1, \ldots, T-1$. For the regime vectors $\alpha$ and $\beta$, the above joint density function can be written by

$$
\begin{equation*}
f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid \hat{s}, \mathcal{F}_{0}\right)=f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \alpha, \mathcal{F}_{0}\right) f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right) \tag{11}
\end{equation*}
$$

where the density function $f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right)$ equals

$$
f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right):= \begin{cases}f\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right), & \text { if } \quad r_{\delta} \neq 0  \tag{12}\\ 1, & \text { if } \quad r_{\delta}=0\end{cases}
$$

Then, the following Proposition, which is useful for Monte-Carlo simulation holds, see below.
Proposition 1. Conditional on initial information $\mathcal{F}_{0}$, a joint density function of the random vectors $\bar{y}_{t}$ and $s$ and random matrices $\Pi_{\hat{s}}, \Gamma_{\hat{s}}$, and P is given by

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t} \mid \mathcal{F}_{0}\right) f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right) f\left(s, \mathrm{P} \mid \mathcal{F}_{0}\right) / f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right) . \tag{13}
\end{equation*}
$$

In particular, the following relationships holds

$$
\begin{equation*}
f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{t}\right)=f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) \tag{14}
\end{equation*}
$$

$$
\begin{gather*}
f\left(\Pi_{\delta}, \Gamma_{\delta} \mid \Pi_{\alpha}, \Gamma_{\alpha}, s, \mathcal{F}_{t}\right)=f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right)  \tag{15}\\
f\left(\Pi_{\beta}, \Gamma_{\beta} \mid s, \mathcal{F}_{t}\right)=f\left(\Pi_{\gamma}, \Gamma_{\gamma} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right)  \tag{16}\\
f\left(\mathrm{P} \mid \bar{s}_{t}, \mathcal{F}_{t}\right)=f\left(\mathrm{P} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)  \tag{17}\\
f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathrm{P}, \mathcal{F}_{0}\right) \tag{18}
\end{gather*}
$$

and

$$
\begin{equation*}
f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathcal{F}_{t}\right) \tag{19}
\end{equation*}
$$

Proof. Let us consider a joint density function of the random vectors $\bar{y}_{t}$ and $s$ and random matrices $\Pi_{\hat{s}}, \Gamma_{\hat{s}}$, and P for given initial information $\mathcal{F}_{0}$. According to the conditional probability formula, one gets that

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t} \mid \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{0}\right) f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathrm{P}, \mathcal{F}_{0}\right) f\left(s \mid \mathrm{P}, \mathcal{F}_{0}\right) f\left(\mathrm{P} \mid \mathcal{F}_{0}\right) \tag{20}
\end{equation*}
$$

Since the random vector $\bar{y}_{t}$ depends on $\Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t}$, the first joint density function of the right-hand side of the above equation equals $f\left(\bar{y}_{t} \mid \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)$. As the random coefficient matrix $\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}}\right)$ is independent of the transition probability matrix P conditional on $s$ and $\mathcal{F}_{0}$, the second joint density function of the right-hand side can be represented by equation (11). According to the Markov property (4), the third joint density function equals $f\left(\bar{s}_{t} \mid \mathrm{P}, \mathcal{F}_{0}\right) f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathrm{P}, \mathcal{F}_{0}\right)$. Consequently, one obtains equation (13). If we integrate equation (13) by $P$, then one finds that

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t} \mid \mathcal{F}_{0}\right) f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right) f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) \tag{21}
\end{equation*}
$$

By integrating the above equation by the random matrix $\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}}\right)$, one obtains equation (14). Since $f\left(\bar{y}_{t} \mid \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t}, \bar{s}_{t}^{c}, \mathcal{F}_{0}\right)=f\left(\bar{y}_{t} \mid \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)$ and $f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \bar{s}_{t}^{c}, \mathcal{F}_{0}\right)=f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)$, we have that

$$
\begin{align*}
f\left(\bar{y}_{t}, \bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) & =\int_{\Pi_{\alpha}, \Gamma_{\alpha}} f\left(\bar{y}_{t} \mid \Pi_{\alpha}, \Gamma_{\alpha}, \bar{s}_{t}, \bar{s}_{t}^{c}, \mathcal{F}_{0}\right) f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \bar{s}_{t}^{c}, \mathcal{F}_{0}\right) f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t} \mathcal{F}_{0}\right) d \Pi_{\alpha} d \Gamma_{\alpha} \\
& =f\left(\bar{y}_{t} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) \tag{22}
\end{align*}
$$

Thus, conditional on $\bar{s}_{t}$ and $\mathcal{F}_{0}$, the random vectors $\bar{y}_{t}$ and $\bar{s}_{t}^{c}$ are independent. Consequently, it holds that

$$
\begin{equation*}
f\left(\bar{y}_{t}, s \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \bar{s}_{t} \mid \mathcal{F}_{0}\right) f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) \tag{23}
\end{equation*}
$$

If we divide equation (21) by the above equation, then one obtains

$$
\begin{equation*}
f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathcal{F}_{t}\right)=f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) f_{*}\left(\Pi_{\delta}, \Gamma_{\delta} \mid \delta, \mathcal{F}_{0}\right) . \tag{24}
\end{equation*}
$$

Since $f\left(\bar{y}_{t}, \Pi_{\alpha}, \Gamma_{\alpha} \mid s, \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)$ and conditional on $\bar{s}_{t}$ and $\mathcal{F}_{0}$, the random vectors $\bar{y}_{t}$ and $\bar{s}_{t}^{c}$ are independent, we have $f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid s, \mathcal{F}_{t}\right)=f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{t}\right)$. Consequently, due to the conditional probability formula, we have that

$$
\begin{equation*}
f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathcal{F}_{t}\right)=f\left(\Pi_{\alpha}, \Gamma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) f\left(\Pi_{\delta}, \Gamma_{\delta} \mid \Pi_{\alpha}, \Gamma_{\alpha}, s, \mathcal{F}_{0}\right) \tag{25}
\end{equation*}
$$

Thus, equating equation (24) with the above equation, we get equation (15). If we integrate equation (24) by $\left(\Pi_{\epsilon}, \Gamma_{\epsilon}\right)$, then by equation (7) and (9), we obtain equation (16). Integrating equation (13) by $\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}}\right)$, one obtains that

$$
\begin{equation*}
f\left(\bar{y}_{t}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \bar{s}_{t} \mid \mathcal{F}_{0}\right) f\left(s, \mathrm{P} \mid \mathcal{F}_{0}\right) / f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right) . \tag{26}
\end{equation*}
$$

Consequently if we integrate equation (26) by $\bar{s}_{t}^{c}$ and divide $f\left(\bar{y}_{t}, \bar{s}_{t} \mid \mathcal{F}_{0}\right)$, we get equation (17). Thus, conditional on $\bar{s}_{t}$ and $\mathcal{F}_{0}, \bar{y}_{t}$ and P are independent. Also, it follows from equation (26) that

$$
\begin{equation*}
f\left(\bar{s}_{t}^{c}, \mathrm{P} \mid \bar{s}_{t}, \mathcal{F}_{t}\right)=f\left(s, \mathrm{P} \mid \mathcal{F}_{0}\right) / f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right) \tag{27}
\end{equation*}
$$

By dividing the above equation by equation (17), we obtain equation (18). To prove equation (19), let us consider a conditional density function $f\left(\Pi_{\hat{s}}, \Gamma_{\hat{s}}, \mathrm{P} \mid s, \mathcal{F}_{t}\right)$. Equation (20) can be written by

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathcal{F}_{0}\right) f\left(s, \mathrm{P} \mid \mathcal{F}_{0}\right) \tag{28}
\end{equation*}
$$

On the other hand, by the conditional probability formula, it holds

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}} \mid s, \mathrm{P}, \mathcal{F}_{0}\right) f\left(s, \mathrm{P} \mid \mathcal{F}_{0}\right) . \tag{29}
\end{equation*}
$$

Therefore, one conclude that conditional on $s$ and $\mathcal{F}_{0}$, the random matrix $\left(\bar{y}_{t}, \Pi_{\hat{s}}, \Gamma_{\hat{s}}\right)$ and transition probability matrix $P$ are independent. Thus, equation (19) holds. That completes the proof.

It should be noted that according to the Markov property (4), it follows from equation (18) that the assumption for a Markov chain in the book of Hamilton (1994) always holds, namely,

$$
\begin{equation*}
f\left(s_{t+1} \mid \bar{s}_{t}, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(s_{t+1} \mid s_{t}, \mathrm{P}, \mathcal{F}_{0}\right) \tag{30}
\end{equation*}
$$

## 3 Special Case of Bayesian MS-VAR $(p)$ process

In this section, we consider a special case of the Bayesian MS-VAR $(p)$ process. The Bayesian MS$\operatorname{VAR}(p)$ process can be written by the following equation

$$
\begin{equation*}
y_{t}=\Pi_{s_{t}} \mathrm{Y}_{t}+\xi_{t}=\left(\mathrm{Y}_{t}^{\prime} \otimes I_{n}\right) \pi_{s_{t}}+\xi_{t}, \quad t=1, \ldots, T \tag{31}
\end{equation*}
$$

where $\otimes$ is the Kronecker product of two matrices and $\pi_{s_{t}}:=\operatorname{vec}\left(\Pi_{s_{t}}\right)$ is an $(n d \times 1)$ vectorization of the random coefficient matrix $\Pi_{s_{t}}$. Now we define distributions of the random coefficient vector $\pi_{s_{t}}$ and covariance matrix $\Sigma_{s_{t}}$. We assume that conditional on the regime $s_{t}$ and initial information $\mathcal{F}_{0}$, a distribution of the random covariance matrix $\Sigma_{s_{t}}$ is given by

$$
\begin{equation*}
\Sigma_{s_{t}} \mid s_{t}, \mathcal{F}_{0} \sim \mathcal{I} \mathcal{W}\left(\nu_{0, s_{t}}, V_{0, s_{t}}\right) \tag{32}
\end{equation*}
$$

where the notation $\mathcal{I W}$ denotes the Inverse-Wishart distribution, $\nu_{0, s_{t}}>n-1$ is a degrees of freedom and $V_{0, s_{t}}$ is a positive definite scale matrix and both are prior hyperparameters, corresponding to the regime $s_{t}$. Consequently, a distribution of the residual vector $\xi_{t}$ equals

$$
\begin{equation*}
\xi_{t} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0} \sim \mathcal{N}\left(0, \Sigma_{s_{t}}\right) \tag{33}
\end{equation*}
$$

where $\mathcal{N}$ denotes the normal distribution. Also, we assume that conditional on the covariance matrix $\Sigma_{s_{t}}$, regime $s_{t}$, and initial information $\mathcal{F}_{0}$, a distribution of the random coefficient vector $\pi_{s_{t}}$ is given by

$$
\begin{equation*}
\pi_{s_{t}} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0} \sim \mathcal{N}\left(\pi_{0, s_{t}}, \Lambda_{0, s_{t}} \otimes \Sigma_{s_{t}}\right) \tag{34}
\end{equation*}
$$

where $\pi_{0, s_{t}}$ is an $(n d \times 1)$ prior hyperparameter vector at regime $s_{t}$ and $\Lambda_{0, s_{t}}$ is a symmetric positive definite $(d \times d)$ prior hyperparameter matrix at regime $s_{t}$.

### 3.1 Distributions

For the regime vector $\bar{s}_{t}$ and regime $\alpha_{k}$, we define sets

$$
\begin{equation*}
S_{t, \alpha_{k}}:=\left\{u \in\{1, \ldots, t\} \mid s_{u}=\alpha_{k}, u=1, \ldots, t\right\}, \quad k=1, \ldots, r_{\alpha} \tag{35}
\end{equation*}
$$

For $k=1, \ldots, r_{\alpha}$, the set $S_{t, \alpha_{k}}$ consists of indexes of regimes in the regime vector $\bar{s}_{t}$ that equal the regime $\alpha_{k}$. Let us suppose that $q_{t, \alpha_{k}}:=\left|S_{t, \alpha_{k}}\right|$ is a number of regimes in the regime vector $\bar{s}_{t}$ that equal the regime $\alpha_{k}$ and elements of the set $S_{t, \alpha_{k}}$ are given by

$$
\begin{equation*}
S_{t, \alpha_{k}}=\left\{k_{t, 1}, \ldots, k_{t, q_{t, \alpha_{k}}}\right\}, \quad k=1, \ldots, r_{\alpha} \tag{36}
\end{equation*}
$$

Further, we define indexes

$$
\begin{equation*}
o_{t}:=\left\{k \in\left\{1, \ldots, r_{\alpha}\right\} \mid s_{t}=\alpha_{k}, k=1, \ldots, r_{\alpha}\right\}, \quad t=1, \ldots, t \tag{37}
\end{equation*}
$$

The index $o_{t}$ represents a position of the regime $s_{t}$ in the regime vector $\alpha$. Let $\pi_{\alpha}:=\left(\pi_{\alpha_{1}}^{\prime}, \ldots, \pi_{\alpha_{r_{\alpha}}}^{\prime}\right)^{\prime}$ be an $\left(\left[n d r_{\alpha}\right] \times 1\right)$ random coefficient vector, whose sub-vectors are different and which corresponds to the regime vector $\bar{s}_{t}, y_{t, \alpha_{k}}:=\left(y_{k_{t, 1}}^{\prime}, \ldots, y_{k_{t, q_{t, \alpha_{k}}}^{\prime}}\right)^{\prime}$ be an $\left(\left[n q_{t, \alpha_{k}}\right] \times 1\right)$ vector of endogenous variables, corresponding to the regime $\alpha_{k}$, and $\mathrm{Y}_{t, \alpha_{k}}^{\circ}:=\left[\mathrm{Y}_{k_{t, 1}}: \cdots: \mathrm{Y}_{k_{t, q_{t, \alpha_{k}}}}\right]$ be a $\left(d \times q_{t, \alpha_{k}}\right)$ matrix of exogenous and endogenous variables, corresponding to the regime $\alpha_{k}$. By using a $\left(t \times r_{\alpha}\right)$ matrix $D_{\alpha}:=\left[j_{o_{1}}\right.$ : $\left.\cdots: j_{o_{t}}\right]^{\prime}$ one can revive the vector $\pi_{\bar{s}_{t}}:=\operatorname{vec}\left(\Pi_{\bar{s}_{t}}\right)$ from the vector $\pi_{\alpha}$, that is, $\pi_{\bar{s}_{t}}=\left(D_{\alpha} \otimes I_{n d}\right) \pi_{\alpha}$, where $j_{o}$ is an $\left(r_{\alpha} \times 1\right)$ unit vector, whose $o$-th element equals one and others zero.

### 3.1.1 Conditional Distributions

It follows from equations (33) and (34) that distributions of the random vectors $\bar{\xi}_{t}$ and $\pi_{\alpha}$ are obtained by

$$
\begin{equation*}
\bar{\xi}_{t} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0} \sim \mathcal{N}\left(0, \Sigma_{\bar{s}_{t}}\right) \tag{38}
\end{equation*}
$$

and

$$
\begin{equation*}
\pi_{\alpha} \mid \Sigma_{\alpha}, \alpha, \mathcal{F}_{0} \sim \mathcal{N}\left(\pi_{0, \alpha}, \Sigma_{\pi_{\alpha}}\right) \tag{39}
\end{equation*}
$$

respectively, where $\Sigma_{\bar{s}_{t}}:=\operatorname{diag}\left\{\Sigma_{s_{1}}, \ldots, \Sigma_{s_{t}}\right\}$ is an $([n t] \times[n t])$ block diagonal matrix, corresponding to the regime vector $\bar{s}_{t}$ and $\Sigma_{\alpha}:=\left[\Sigma_{\alpha_{1}}: \cdots: \Sigma_{\alpha_{r_{\alpha}}}\right]^{\prime}$ is an $\left(\left[n r_{\alpha}\right] \times n\right)$ matrix, $\pi_{0, \alpha}:=\left(\pi_{0, \alpha_{1}}^{\prime}, \ldots, \pi_{0, \alpha_{r_{\alpha}}}^{\prime}\right)^{\prime}$ is an $\left(\left[n d r_{\alpha}\right] \times 1\right)$ prior hyperparameter vector, and $\Sigma_{\pi_{\alpha}}:=\operatorname{diag}\left\{\Lambda_{0, \alpha_{1}} \otimes \Sigma_{\alpha_{1}}, \ldots, \Lambda_{0, \alpha_{r_{\alpha}}} \otimes \Sigma_{\alpha_{r_{\alpha}}}\right\}$ is an $\left(\left[n d r_{\alpha}\right] \times\left[n d r_{\alpha}\right]\right)$ block diagonal matrix, all of which correspond to the duplication removed regime vector $\alpha$. A connection between the random matrices $\Sigma_{\bar{s}_{t}}$ and $\Sigma_{\alpha}$ is

$$
\begin{equation*}
\Sigma_{\bar{s}_{t}}=\operatorname{diag}\left\{\left(\left(D_{\alpha} \otimes I_{n}\right) \Sigma_{\alpha}\right)_{1}, \ldots,\left(\left(D_{\alpha} \otimes I_{n}\right) \Sigma_{\alpha}\right)_{t}\right\} \tag{40}
\end{equation*}
$$

where the matrix $\left(\left(D_{\alpha} \otimes I_{n}\right) \Sigma_{\alpha}\right)_{j}$ equals $j$-th block matrix of the matrix $\left(D_{\alpha} \otimes I_{n}\right) \Sigma_{\alpha}$. On the other hand, by following Battulga (2024b), a distribution of $([n T] \times 1)$ the random vector $y=\left(y_{1}^{\prime}, \ldots, y_{T}^{\prime}\right)^{\prime}$ is given by

$$
\begin{equation*}
y \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathcal{F}_{0} \sim \mathcal{N}\left(\Psi_{s}^{-1} \varphi_{s}, \Psi_{s}^{-1} \Sigma_{s}\left(\Psi_{s}^{-1}\right)^{\prime}\right) \tag{41}
\end{equation*}
$$

where the matrix $\Psi_{s}$ and the vector $\delta_{s}$ are

$$
\Psi_{s}:=\left[\begin{array}{ccccccc}
I_{n} & 0 & \ldots & 0 & \ldots & 0 & 0  \tag{42}\\
-A_{1, s_{2}} & I_{n} & \ldots & 0 & \ldots & 0 & 0 \\
\vdots & \vdots & \ldots & \vdots & \ldots & \vdots & \vdots \\
0 & 0 & \ldots & -A_{p-1, s_{T-1}} & \ldots & I_{n} & 0 \\
0 & 0 & \ldots & -A_{p, s_{T}} & \ldots & -A_{1, s_{T}} & I_{n}
\end{array}\right]
$$

and

$$
\varphi_{s}:=\left[\begin{array}{c}
A_{0, s_{1}} \psi_{1}+A_{1, s_{1}} y_{0}+\cdots+A_{p, s_{1}} y_{1-p}  \tag{43}\\
A_{0, s_{2}} \psi_{2}+A_{2, s_{2}} y_{0}+\cdots+A_{p, s_{2}} y_{2-p} \\
\vdots \\
A_{0, s_{T-1}} \psi_{T-1} \\
A_{0, s_{T}} \psi_{T}
\end{array}\right],
$$

respectively. To price default-free options, Battulga (2024b) used the conditional distribution of the random vector $y$. For a generic vector $o=\left(o_{1}^{\prime}, \ldots, o_{n}^{\prime}\right)^{\prime}$ with $(m \times 1)$ vector $o_{i}$, we introduce an $(m \times n)$ matrix notation $o^{\circ}:=\left[o_{1}: \cdots: o_{n}\right]$. Then, the following Proposition holds.
Proposition 2. Let for $t=1, \ldots, T-1, \pi_{s_{t}} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0} \sim \mathcal{N}\left(\pi_{0, s_{t}}, \Lambda_{0, s_{t}} \otimes \Sigma_{s_{t}}\right)$, and $\Sigma_{s_{t}} \mid s_{t}, \mathcal{F}_{0} \sim$ $\mathcal{I} \mathcal{W}\left(\nu_{0, s_{t}}, V_{0, s_{t}}\right)$. Then, first, conditional on the regime vector $\bar{s}_{t}$ and initial information $\mathcal{F}_{0}$, a joint density function of the random vector $\bar{y}_{t}$ is given by

$$
\begin{equation*}
f\left(\bar{y}_{t} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)=\frac{1}{\pi^{n t / 2}} \prod_{k=1}^{r_{\alpha}} \frac{\left|\Lambda_{0, \alpha_{k}}^{-1}\right|^{n / 2} \Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2\right)\left|V_{0, \alpha_{k}}\right|^{\nu_{0, \alpha_{k}} / 2}}{\left|\Lambda_{0, \alpha_{k} \mid t} t^{n / 2} \Gamma_{n}\left(\nu_{0, \alpha_{k}} / 2\right)\right| \bar{B}_{t, \alpha_{k}}+\left.V_{0, \alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}, \tag{44}
\end{equation*}
$$

where $\Gamma_{n}(\cdot)$ is the multivariate gamma function, $\Lambda_{0, \alpha_{k} \mid t}:=\mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}+\Lambda_{0, \alpha_{k}}^{-1}$ is a $(d \times d)$ matrix, and $\bar{B}_{t, \alpha_{k}}$ is an $(n \times n)$ positive semi-definite matrix and equals

$$
\begin{align*}
\bar{B}_{t, \alpha_{k}} & :=y_{t, \alpha_{k}}^{\circ}\left(y_{t, \alpha_{k}}^{\circ}\right)^{\prime}+\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1}\left(\pi_{0, \alpha_{k}}^{\circ}\right)^{\prime}-C_{t, \alpha_{k}} \Lambda_{0, \alpha_{k} \mid t} C_{t, \alpha_{k}}^{\prime}  \tag{45}\\
& =\left(y_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)\left(I_{t, \alpha_{k}}+\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{-1}\left(y_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}
\end{align*}
$$

with $(n \times d)$ matrix $C_{t, \alpha_{k}}:=\left(y_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}+\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1}\right) \Lambda_{0, \alpha_{k} \mid t}^{-1}$. Second, conditional on the random covariance matrix $\Sigma_{\alpha}$, regime vector $\bar{s}_{t}$, and information $\mathcal{F}_{t}, a$ joint density function of the random coefficient vector $\pi_{\alpha}$ is given by

$$
\begin{align*}
& f\left(\pi_{\alpha} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{t}\right) \\
& =\frac{1}{\left.(2 \pi)^{n d r_{\alpha} / 2} \prod_{k=1}^{r_{\alpha}}\left|A_{\alpha_{k}}\right|\right|^{1 / 2}} \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)^{\prime} A_{\alpha_{k}}^{-1}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)\right\}, \tag{46}
\end{align*}
$$

where for $k=1, \ldots, r_{\alpha}, A_{\alpha_{k}}:=\left(\Lambda_{0, \alpha_{k} \mid t}^{-1} \otimes \Sigma_{\alpha_{k}}\right)$ is an $([n d] \times[n d])$ matrix and $b_{\alpha_{k}}:=\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ} \otimes\right.$ $\left.\Sigma_{\alpha_{k}}^{-1}\right) y_{t, \alpha_{k}}+\left(\Lambda_{0, \alpha_{k}}^{-1} \otimes \Sigma_{\alpha_{k}}^{-1}\right) \pi_{0, \alpha_{k}}$ is an $([n d] \times 1)$ vector. Third, conditional on the regime vector $\bar{s}_{t}$ and information $\mathcal{F}_{t}$, a joint density function of the random coefficient matrix $\Sigma_{\alpha}$ is given by

$$
\begin{align*}
f\left(\Sigma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) & =\prod_{k=1}^{r_{\alpha}} \frac{\left|\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}{\Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2\right) 2^{n\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}\left|\Sigma_{\alpha_{k}}\right|^{-\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}+n+1\right) / 2} \\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}} \operatorname{tr}\left(\left(\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right) \Sigma_{\alpha_{k}}^{-1}\right)\right\} . \tag{47}
\end{align*}
$$

Finally, conditional on the regime vector $s$ and information $\mathcal{F}_{t}$, a joint density function of the random coefficient matrix $\pi_{\beta}^{\circ}$ is given by

$$
\begin{align*}
f\left(\pi_{\beta}^{\circ} \mid s, \mathcal{F}_{t}\right) & =\prod_{k=1}^{r_{\gamma}} \frac{\left|\Lambda_{0, \gamma_{k} \mid t}\right|^{n / 2}\left|\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right|^{-d / 2} \Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}+d\right) / 2\right)}{\pi^{n d / 2} \Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right) / 2\right)} \\
& \times\left|I_{n}+\left(\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right)^{-1}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right) \Lambda_{0, \gamma_{k} \mid t}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right)^{\prime}\right|^{-\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}+d\right) / 2} \\
& \times \prod_{\ell=1}^{r_{\delta}} \frac{\left|\Lambda_{0, \delta_{\ell}}\right|^{-n / 2}\left|V_{0, \delta_{\ell}}\right|^{-d / 2} \Gamma_{n}\left(\left(\nu_{0, \delta_{\ell}}+d\right) / 2\right)}{\pi^{n d / 2} \Gamma_{n}\left(\nu_{0, \delta_{\ell}} / 2\right)}  \tag{48}\\
& \times \mid I_{n}+V_{0, \delta_{\ell}}^{-1}\left(\pi_{\delta_{\ell}}^{\circ}-\pi_{0, \delta_{\ell}}^{\circ}\right) \Lambda_{0, \delta_{\ell}}^{-1}\left(\pi_{\delta_{\ell}}^{\circ}-\left.\left.\pi_{0, \delta_{\ell}}^{\circ}\right|^{\prime}\right|^{-\left(\nu_{0, \delta_{\ell}}+d\right) / 2} .\right.
\end{align*}
$$

Proof. First, since $\left(\pi_{\alpha_{1}}, \Sigma_{\alpha_{1}}\right), \ldots,\left(\pi_{r_{\alpha}}, \Sigma_{r_{\alpha}}\right)$ are independent for given regime vector $\bar{s}_{t}$ and initial information $\mathcal{F}_{0}$, observe that conditional density functions of the random vectors $y$ and $\pi_{\hat{s}}$ and random matrix $\Sigma_{\hat{s}}$ are given by

$$
\begin{align*}
& f\left(\bar{y}_{t} \mid \pi_{\alpha}, \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)= \frac{1}{(2 \pi)^{n t / 2}} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-q_{t, \alpha_{k}} / 2}  \tag{49}\\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(y_{t, \alpha_{k}}-\left(\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \otimes I_{n}\right) \pi_{\alpha_{k}}\right)^{\prime}\left(I_{q_{t, \alpha_{k}}} \otimes \Sigma_{\alpha_{k}}^{-1}\right)\left(y_{t, \alpha_{k}}-\left(\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \otimes I_{n}\right) \pi_{\alpha_{k}}\right)\right\} \\
& f\left(\pi_{\alpha} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)= \frac{1}{(2 \pi)^{n r_{\alpha} d / 2} \prod_{k=1}^{r_{\alpha}}\left|\Lambda_{0, \alpha_{k}}\right|^{n / 2}} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-d / 2}  \tag{50}\\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(\pi_{\alpha_{k}}-\pi_{0, \alpha_{k}}\right)^{\prime}\left(\Lambda_{0, \alpha_{k}}^{-1} \otimes \Sigma_{\alpha_{k}}^{-1}\right)\left(\pi_{\alpha_{k}}-\pi_{0, \alpha_{k}}\right)\right\}
\end{align*}
$$

and

$$
\begin{equation*}
f\left(\Sigma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)=\prod_{k=1}^{r_{\alpha}} \frac{\left|V_{0, \alpha_{k}}\right|^{\nu_{0, \alpha_{k}} / 2}}{\Gamma_{n}\left(\nu_{0, \alpha_{k}} / 2\right) 2^{n \nu_{0, \alpha_{k}} / 2}}\left|\Sigma_{\alpha_{k}}\right|^{-\left(\nu_{0, \alpha_{k}}+n+1\right) / 2} \exp \left\{-\frac{1}{2} \operatorname{tr}\left(V_{0, \alpha_{k}} \Sigma_{\alpha_{k}}^{-1}\right)\right\} \tag{51}
\end{equation*}
$$

respectively. Consequently, by the completing square method, a joint conditional density function of the random vectors $y$ and $\pi_{\hat{s}}$ is

$$
\begin{align*}
& f\left(\bar{y}_{t}, \pi_{\alpha} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right) \\
& =c_{1} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-\left(q_{t, \alpha_{k}}+d\right) / 2} \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)^{\prime} A_{\alpha_{k}}^{-1}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)\right\}  \tag{52}\\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(y_{t, \alpha_{k}}^{\prime}\left(I_{q_{t, \alpha_{k}}} \otimes \Sigma_{\alpha_{k}}^{-1}\right) y_{t, \alpha_{k}}+\pi_{0, \alpha_{k}}^{\prime}\left(\Lambda_{0, \alpha_{k}}^{-1} \otimes \Sigma_{\alpha_{k}}^{-1}\right) \pi_{0, \alpha_{k}}-b_{\alpha_{k}}^{\prime} A_{\alpha_{k}} b_{\alpha_{k}}\right)\right\},
\end{align*}
$$

where normalizing coefficient equals

$$
\begin{equation*}
c_{1}:=\frac{1}{(2 \pi)^{n\left(t+r_{\alpha} d\right) / 2} \prod_{k=1}^{r_{\alpha}}\left|\Lambda_{0, \alpha_{k}}\right|^{n / 2}} . \tag{53}
\end{equation*}
$$

If we integrate from the above joint density function with respect to the vector $\pi_{\alpha}$, then an integral, corresponding to the first exponential is proportional to $\prod_{k=1}^{r_{\alpha}}\left|A_{\alpha_{k}}\right|^{1 / 2}=\prod_{k=1}^{r_{\alpha}} \mid\left(\mathrm{Y}_{t, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\prime}+\right.$ $\left.\Lambda_{0, \alpha_{k}}^{-1}\right)\left.\right|^{-n / 2}\left|\Sigma_{\alpha_{k}}\right|^{d / 2}$. Therefore, we have that

$$
\begin{align*}
& f\left(\bar{y}_{t} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)=c_{2} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-q_{t, \alpha_{k}} / 2} \\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}}\left(y_{t, \alpha_{k}}^{\prime}\left(I_{q_{t, \alpha_{k}}} \otimes \Sigma_{\alpha_{k}}^{-1}\right) y_{t, \alpha_{k}}+\pi_{0, \alpha_{k}}^{\prime}\left(\Lambda_{0, \alpha_{k}}^{-1} \otimes \Sigma_{\alpha_{k}}^{-1}\right) \pi_{0, \alpha_{k}}-b_{\alpha_{k}}^{\prime} A_{\alpha_{k}} b_{\alpha_{k}}\right)\right\}, \tag{54}
\end{align*}
$$

where the normalizing coefficient equals

$$
\begin{equation*}
c_{2}:=\frac{1}{(2 \pi)^{n t / 2} \prod_{k=1}^{r_{\alpha}}\left|\Lambda_{0, \alpha_{k}}\right|^{n / 2}\left|\Lambda_{0, \alpha_{k} \mid t}\right|^{n / 2}} . \tag{55}
\end{equation*}
$$

Hence, according to the well-known formula that for suitable matrices $A, B, C, D$,

$$
\begin{equation*}
\operatorname{vec}(A)^{\prime}(B \otimes C) \operatorname{vec}(D)=\operatorname{tr}\left(D B^{\prime} A^{\prime} C\right) \tag{56}
\end{equation*}
$$

we find that

$$
\begin{equation*}
f\left(\bar{y}_{t} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{0}\right)=c_{2} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-q_{t, \alpha_{k}} / 2} \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}} \operatorname{tr}\left(\bar{B}_{t, \alpha_{k}} \Sigma_{\alpha_{k}}^{-1}\right)\right\} . \tag{57}
\end{equation*}
$$

Thus, it follows from equations (51) and (57) that a joint conditional density of the random vector $y$ and random matrix $\Sigma_{\hat{s}}$ is

$$
\begin{equation*}
f\left(\bar{y}_{t}, \Sigma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)=c_{3} \prod_{k=1}^{r_{\alpha}}\left|\Sigma_{\alpha_{k}}\right|^{-\left(q_{t, \alpha_{k}}+\nu_{0, \alpha_{k}}+n+1\right) / 2} \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\alpha}} \operatorname{tr}\left(\left(\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right) \Sigma_{\alpha_{k}}^{-1}\right)\right\}, \tag{58}
\end{equation*}
$$

where the normalizing coefficient equals

$$
\begin{equation*}
c_{3}:=\frac{1}{(2 \pi)^{n t / 2}} \prod_{k=1}^{r_{\alpha}} \frac{\left|V_{0, \alpha_{k}}\right|^{| |_{0, \alpha_{k}} / 2}}{\left.\left|\Lambda_{0, \alpha_{k}}\right|^{n / 2}\left|\Lambda_{0, \alpha_{k}}\right|\right|^{n / 2} \Gamma_{n}\left(\nu_{0, \alpha_{k}} / 2\right) 2^{n \nu_{0, \alpha_{k}} / 2}} . \tag{59}
\end{equation*}
$$

Consequently, a prior density of the random vector $y$ is given by

$$
\begin{align*}
f\left(\bar{y}_{t} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) & =\int_{\Sigma_{\Sigma_{1}, \ldots, \Sigma_{s_{r_{\alpha}}}>0} f\left(\bar{y}_{t}, \hat{\Sigma}_{\bar{s}_{t}} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) d \Sigma_{\hat{s}_{1}} \ldots d \Sigma_{\hat{s}_{r_{\alpha}}}} \\
& =c_{3} \prod_{k=1}^{r_{\alpha}} \frac{\Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2\right) 2^{n\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}{\left.\left|\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right|\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}} . \tag{60}
\end{align*}
$$

If we divide equations (52) and (58) by equations (54) and (60), respectively, then one obtains equations (46) and (47). According to equation (16), we have that

$$
\begin{equation*}
f\left(\pi_{\beta}, \Sigma_{\beta} \mid s, \mathcal{F}_{t}\right)=f\left(\pi_{\gamma}, \Sigma_{\gamma} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) f_{*}\left(\pi_{\delta}, \Sigma_{\delta} \mid \delta, \mathcal{F}_{0}\right) \tag{61}
\end{equation*}
$$

We consider the first joint conditional density of the right-hand side of the above equation. By integrating a product of density functions (46) and (47) by ( $\pi_{\epsilon}, \Sigma_{\epsilon}$ ) and taking account that

$$
\begin{equation*}
\sum_{k=1}^{r_{\gamma}}\left(\pi_{\gamma_{k}}-A_{\gamma_{k}} b_{\gamma_{k}}\right)^{\prime} A_{\gamma_{k}}^{-1}\left(\pi_{\gamma_{k}}-A_{\gamma_{k}} b_{\gamma_{k}}\right)=\sum_{k=1}^{r_{\gamma}} \operatorname{tr}\left(\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right) \Lambda_{0, \gamma_{k} \mid t}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right)^{\prime} \Sigma_{\gamma_{k}}^{-1}\right) \tag{62}
\end{equation*}
$$

the joint conditional density function is

$$
\begin{align*}
& f\left(\pi_{\gamma}, \Sigma_{\gamma} \mid \bar{s}_{t}, \mathcal{F}_{t}\right)=c_{4} \prod_{k=1}^{r_{\gamma}}\left|\Sigma_{\gamma_{k}}\right|^{-\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}+d+n+1\right) / 2} \\
& \times \exp \left\{-\frac{1}{2} \sum_{k=1}^{r_{\gamma}} \operatorname{tr}\left(\left(\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}+\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right) \Lambda_{0, \gamma_{k} \mid t}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right)^{\prime}\right) \Sigma_{\alpha_{k}}^{-1}\right)\right\}, \tag{63}
\end{align*}
$$

where the normalizing coefficient equals

$$
\begin{equation*}
c_{4}:=\frac{1}{(2 \pi)^{n d r_{\gamma} / 2} \prod_{k=1}^{r_{\gamma}}\left|\Lambda_{0, \gamma_{k} \mid t}\right|^{-n / 2}} \prod_{k=1}^{r_{\gamma}} \frac{\left|\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right|^{\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right) / 2}}{\Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right) / 2\right) 2^{n\left(\nu_{0, \gamma_{k}}+q_{\left.t, \gamma_{k}\right) / 2}\right.}} . \tag{64}
\end{equation*}
$$

If we integrate the above equation by $\Sigma_{\gamma}$, then one obtains that

$$
\begin{align*}
f\left(\pi_{\gamma}^{\circ} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) & =\prod_{k=1}^{r_{\gamma}} \frac{\left|\Lambda_{0, \gamma_{k} \mid t}\right|^{n / 2}\left|\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right|^{-d / 2} \Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}+d\right) / 2\right)}{\pi^{n d / 2} \Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right) / 2\right)}  \tag{65}\\
& \times\left|I_{n}+\left(\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right)^{-1}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right) \Lambda_{0, \gamma_{k} \mid t}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right)^{\prime}\right|^{-\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}+d\right) / 2} .
\end{align*}
$$

Similarly, if $r_{\delta}>0$, it can be shown that

$$
\begin{align*}
f\left(\pi_{\delta}^{\circ} \mid \delta, \mathcal{F}_{0}\right) & =\prod_{\ell=1}^{r_{\delta}} \frac{\left|\Lambda_{0, \delta_{\ell}}\right|^{-n / 2}\left|V_{0, \delta_{\ell}}\right|^{-d / 2} \Gamma_{n}\left(\left(\nu_{0, \delta_{\ell}}+d\right) / 2\right)}{\pi^{n d / 2} \Gamma_{n}\left(\nu_{0, \delta_{\ell}} / 2\right)} \\
& \times\left|I_{n}+V_{0, \delta_{\ell}}^{-1}\left(\pi_{\delta_{\ell}}^{\circ}-\pi_{0, \delta_{\ell}}^{\circ}\right) \Lambda_{0, \delta_{\ell}}^{-1}\left(\pi_{\delta_{\ell}}^{\circ}-\pi_{0, \delta_{\ell}}^{\circ}\right)^{\prime}\right|^{-\left(\nu_{0, \delta_{\ell}}+d\right) / 2} \tag{66}
\end{align*}
$$

Therefore, equation (48) holds. By the completing square method, the matrix $\bar{B}_{t, \alpha_{k}}$ can be written by

$$
\begin{align*}
\bar{B}_{t, \alpha_{k}} & =\left(\tilde{y}_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}^{-1}\right) \Phi_{t, \alpha_{k}}^{-1}\left(\tilde{y}_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}^{-1}\right)^{\prime} \\
& -\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}^{-1}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \Lambda_{0, \alpha_{k}}^{-1}\left(\pi_{0, \alpha_{k}}^{\circ}\right)^{\prime} \\
& +\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1}\left(\pi_{0, \alpha_{k}}^{\circ}\right)^{\prime}-\pi_{0, \alpha_{k}}^{\circ} \Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \Lambda_{0, \alpha_{k}}^{-1}\left(\pi_{0, \alpha_{k}}^{\circ}\right)^{\prime} \tag{67}
\end{align*}
$$

where $\Phi_{t, \alpha_{k}}:=I_{q_{t, \alpha_{k}}}-\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ}$ is a symmetric $\left(q_{t, \alpha_{k}} \times q_{t, \alpha_{k}}\right)$ matrix. We consider the following product

$$
\begin{equation*}
I_{t, \alpha_{k}}:=\left(I_{q_{t, \alpha_{k}}}+\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)\left(I_{q_{t, \alpha_{k}}}-\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right) \tag{68}
\end{equation*}
$$

It equals

$$
\begin{align*}
I_{t, \alpha_{k}} & =I_{q_{t, \alpha_{k}}}+\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}-\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \\
& -\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \tag{69}
\end{align*}
$$

If we add and subtract the matrix $\Lambda_{0, \alpha_{k}}^{-1}$ into the term $\mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}$ in the last line of the above equation, then the product matrix equals $I_{t, \alpha_{k}}=I_{q_{t, \alpha_{k}}}$. Consequently, the matrix $I_{q_{t, \alpha_{k}}}+\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}$ is an inverse matrix of the matrix $\Phi_{t, \alpha_{k}}$, that is,

$$
\begin{equation*}
\Phi_{t, \alpha_{k}}^{-1}=I_{q_{t, \alpha_{k}}}+\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \tag{70}
\end{equation*}
$$

Since it is a positive definite matrix, the matrix $\bar{B}_{t, \alpha_{k}}$ is a positive semi-definite matrix. Now, we consider the term $\Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}^{-1}$ in the first line in equation (67). Similarly as before, by adding and subtracting $\Lambda_{0, \alpha_{k}}^{-1}$ into the term $\mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}$, one obtains that

$$
\begin{equation*}
\Lambda_{0, \alpha_{k}}^{-1} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}^{-1}=\mathrm{Y}_{t, \alpha_{k}}^{\circ} \tag{71}
\end{equation*}
$$

Consequently, the sum of the second and third line of equation (67) equals zero. Let $\Lambda_{0, \alpha_{k}}^{1 / 2}$ be the Cholesky factor of the matrix $\Lambda_{0, \alpha_{k}}$, i.e., $\Lambda_{0, \alpha_{k}}=\left(\Lambda_{0, \alpha_{k}}^{1 / 2}\right)^{\prime} \Lambda_{0, \alpha_{k}}^{1 / 2}$. Then, according to the Sylvester's determinant theorem, see Lütkepohl (2005), a determinant of the matrix $\Phi_{t, \alpha_{k}}^{-1}$ is

$$
\begin{equation*}
\left|\Phi_{t, \alpha_{k}}^{-1}\right|=\left|I_{q_{t, \alpha_{k}}}+\left(\Lambda_{0, s_{t}}^{1 / 2} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, s_{t}}^{1 / 2} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right|=\left|I_{d}+\Lambda_{0, s_{t}}^{1 / 2} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}\left(\Lambda_{0, s_{t}}^{1 / 2}\right)^{\prime}\right| \tag{72}
\end{equation*}
$$

That completes the proof of the Proposition.
It follows from equations (46) and (47) that sub coefficient vectors and sub covariance matrices are conditional independent. Note that the conditional independence is consistent with the assumption (10). From equations (46) and (47) one deduces that for $k=1, \ldots, r_{\alpha}$, the conditional density functions of the coefficient vector $\pi_{\alpha_{k}}$ and the covariance matrix $\Sigma_{\alpha_{k}}$ are given by

$$
\begin{equation*}
f\left(\pi_{\alpha_{k}} \mid \Sigma_{\alpha_{k}}, \alpha_{k}, \mathcal{F}_{t}\right)=\frac{1}{(2 \pi)^{n d / 2}\left|A_{\alpha_{k}}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)^{\prime} A_{\alpha_{k}}^{-1}\left(\pi_{\alpha_{k}}-A_{\alpha_{k}} b_{\alpha_{k}}\right)\right\} \tag{73}
\end{equation*}
$$

and

$$
\begin{align*}
f\left(\Sigma_{\alpha_{k}} \mid \alpha_{k}, \mathcal{F}_{t}\right) & =\frac{\left|\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}{\Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2\right) 2^{n\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}\left|\Sigma_{\alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}+n+1\right) / 2}} \\
& \times \exp \left\{-\frac{1}{2} \operatorname{tr}\left(\left(\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right) \Sigma_{\alpha_{k}}^{-1}\right)\right\} \tag{74}
\end{align*}
$$

respectively. Thus, the conditional distribution functions of the coefficient vector $\pi_{\alpha_{k}}$ and the covariance matrix $\Sigma_{\alpha_{k}}$ are multivariate normal and inverse Wishart, respectively. Also, it follows from equation (48) that the conditional density function of the random coefficient matrix $\pi_{\beta}^{\circ}$ equals products of matrix variate student $t$ density functions. The conditional density function of the random matrix $\pi_{\beta}^{\circ}$ can be used to impulse response analysis. Because marginal density functions of the random coefficient matrix $\pi_{\beta}^{\circ}$ are the matrix variate student $t$, their means are given by

$$
\begin{equation*}
\mathbb{E}\left[\pi_{\gamma_{k}}^{\circ} \mid \gamma_{k}, \mathcal{F}_{t}\right]=C_{t, \gamma_{k}}, \quad k=1, \ldots, r_{\gamma} \tag{75}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbb{E}\left[\pi_{\delta_{k}}^{\circ} \mid \delta_{k}, \mathcal{F}_{0}\right]=\pi_{0, \delta_{k}}, \quad k=1, \ldots, r_{\delta} \tag{76}
\end{equation*}
$$

Because, according to equation (45), density function (44) has a form of the matrix variate student $t$ distribution, we refer to the density function as a conditional matrix variate student $t$ density function. Furthermore, it follows from equation (9) and (44) that conditional on the regime vector $s$ and information $\mathcal{F}_{t}$, a density function of future values of the vector of endogenous variables is given by the following equation

$$
\begin{align*}
& f\left(\bar{y}_{t}^{c} \mid s, \mathcal{F}_{t}\right)=\frac{1}{\pi^{n(T-t) / 2}} \prod_{k=1}^{r_{\alpha}} \frac{\left.\left|\Lambda_{0, \alpha_{k}}\right|\right|^{n / 2} \Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{T, \alpha_{k}}\right) / 2\right)\left|\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}}\right) / 2}}{\left|\Lambda_{0, \alpha_{k} \mid T}\right|^{n / 2} \Gamma_{n}\left(\left(\nu_{0, \alpha_{k}}+q_{t, \alpha_{k}} / 2\right)\left|\bar{B}_{T, \alpha_{k}}+V_{0, \alpha_{k}}\right|^{\left(\nu_{0, \alpha_{k}}+q_{T, \alpha_{k}}\right) / 2}\right.} \\
& \times \prod_{\ell=1}^{r_{\delta}} \frac{\left.\left|\Lambda_{0, \delta_{\ell}}^{-1}{ }^{n / 2} \Gamma_{n}\left(\left(\nu_{0, \delta_{\ell}}+q_{T, \delta_{\ell}}\right) / 2\right)\right| V_{0, \delta_{\ell}}\right|^{\nu_{0, \delta_{\ell}} / 2}}{\left|\Lambda_{0, \delta_{\ell} \mid T}\right|^{n / 2} \Gamma_{n}\left(\nu_{0, \delta_{\ell}} / 2\right)\left|\bar{B}_{T, \delta_{\ell}}+V_{0, \delta_{\ell}}\right|^{\left(\nu_{0, \delta_{\ell}}+q_{T, \delta_{\ell}}\right) / 2}} . \tag{77}
\end{align*}
$$

Let us consider the following matrix

$$
\begin{equation*}
\Theta_{t, \alpha_{k}}:=\Lambda_{0, \alpha_{k}}-\Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ} \Phi_{t, \alpha_{k}}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} . \tag{78}
\end{equation*}
$$

Since $\Phi_{t, \alpha_{k}}=I_{q t, \alpha_{k}}-\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ}$, we have that

$$
\begin{equation*}
\Theta_{t, \alpha_{k}}=\Lambda_{0, \alpha_{k}}-\Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}}+\Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \tag{79}
\end{equation*}
$$

If we substitute the matrix $\mathrm{Y}_{t, \alpha_{k}}^{\circ}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime}=\Lambda_{0, \alpha_{k} \mid t}-\Lambda_{0, \alpha_{k}}^{-1}$ into the above equation, one obtains $\Theta_{t, \alpha_{k}}=$ $\Lambda_{0, \alpha_{k} \mid t}^{-1}$. Consequently, by the formula of partitioned matrix's inverse (e.g., see Lütkepohl (2005)) it can be shown that the matrix $\bar{B}_{T, \alpha_{k}}+V_{0, \alpha_{k}}$ equals

$$
\begin{align*}
\bar{B}_{T, \alpha_{k}}+V_{0, \alpha_{k}} & =\bar{B}_{t, \alpha_{k}}+V_{0, \alpha_{k}} \\
& +\left(y_{t, \alpha_{k}}^{*}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{*}-\left(y_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right) \Phi_{t, \alpha_{k}}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{*}\right) \\
& \times\left(I_{q_{t, \alpha}^{*}}^{*}+\mathrm{Y}_{t, \alpha_{k}}^{*} \Lambda_{0, \alpha_{k} \mid t}^{-1} \mathrm{Y}_{t, \alpha_{k}}^{*}\right)^{-1} \\
& \times\left(y_{t, \alpha_{k}}^{*}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{*}-\left(y_{t, \alpha_{k}}^{\circ}-\pi_{0, \alpha_{k}}^{\circ} \mathrm{Y}_{t, \alpha_{k}}^{\circ}\right) \Phi_{t, \alpha_{k}}\left(\mathrm{Y}_{t, \alpha_{k}}^{\circ}\right)^{\prime} \Lambda_{0, \alpha_{k}} \mathrm{Y}_{t, \alpha_{k}}^{*}\right)^{\prime}, \tag{80}
\end{align*}
$$

where the matrices $y_{t, \alpha_{k}}^{*}$ and $Y_{t, \alpha_{k}}^{*}$ are come from the matrices $y_{T, \alpha_{k}}^{\circ}=\left[y_{t, \alpha_{k}}^{\circ}: y_{t, \alpha_{k}}^{*}\right]$ and $Y_{T, \alpha_{k}}^{\circ}=$ $\left[\mathrm{Y}_{t, \alpha_{k}}^{\circ}: \mathrm{Y}_{t, \alpha_{k}}^{*}\right]$, corresponding to the random vectors $\bar{y}_{t}$ and $\bar{y}_{t}^{c}$, and $q_{t, \alpha_{k}}^{*}=q_{T, \alpha_{k}}-q_{t, \alpha_{k}}$. As a result, density function (77) is represented by a product of the conditional matrix variate student $t$ density
functions. Using the idea of proof of Proposition 2, one obtains conditional density function of the random vector $y_{t}$ for given $s_{t}$ and $\mathcal{F}_{t}$

$$
\begin{equation*}
f\left(y_{t} \mid s_{t}, \mathcal{F}_{t}\right)=\frac{1}{\pi^{n / 2}} \frac{\left|\Lambda_{0, s_{t}}\right|^{-n / 2} \Gamma_{n}\left(\left(\nu_{0, s_{t}}+1\right) / 2\right)\left|V_{0, s_{t}}\right|^{\nu_{0, s_{t}} / 2}}{\left(1+\mathrm{Y}_{t}^{\prime} \Lambda_{0, s_{t}} \mathrm{Y}_{t}\right)^{n / 2} \Gamma_{n}\left(\nu_{0, s_{t}} / 2\right)\left|B_{t, s_{t}}+V_{0, s_{t}}\right|^{\left(\nu_{0, s_{t}}+1\right) / 2}}, \tag{81}
\end{equation*}
$$

where

$$
\begin{equation*}
B_{t, s_{t}}:=\frac{1}{1+\mathrm{Y}_{t}^{\prime} \Lambda_{0, s_{t}} \mathrm{Y}_{t}}\left(y_{t}-\pi_{0, s_{t}}^{\circ} \mathrm{Y}_{t}\right)\left(y_{t}-\pi_{0, s_{t}}^{\circ} \mathrm{Y}_{t}\right)^{\prime} \tag{82}
\end{equation*}
$$

is a symmetric positive semi-definite $(n \times n)$ matrix. Note that the conditional density function only depends on the regime $s_{t}$ and does not depend on the other regimes. To calculate smoothed probabilities, the conditional density function will be used, see below.

Let us assume that the prior density functions of each row of the transition probability matrix $P$ follow Dirichlet distribution and they are mutually independent. Under the assumption, a joint density function of them is given by

$$
\begin{equation*}
f\left(\mathrm{P} \mid \mathcal{F}_{0}\right)=\prod_{i=0}^{N} \frac{\Gamma\left(\sum_{j=1}^{N} \alpha_{i j}\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}\right)} \prod_{j=1}^{N} p_{i j}^{\alpha_{i j}-1} \tag{83}
\end{equation*}
$$

where $\Gamma(\cdot)$ is the gamma function and the parameters of Dirichlet distribution satisfy $\alpha_{i j}>0$ for $i=0, \ldots, N$ and $j=1, \ldots, N$. Let us denote $i$-th row of the random transition probability matrix P by $\mathrm{P}_{i}$, corresponding prior hyperparameter by $\alpha_{i}:=\left(\alpha_{i 1}, \ldots, \alpha_{i N}\right)^{\prime}$, and Dirichlet distribution by $\operatorname{Dir}\left(\alpha_{i}\right)$. Then, the following Lemma holds.

Proposition 3. Let for $i=0, \ldots, N, \mathrm{P}_{i} \sim \operatorname{Dir}\left(\alpha_{i}\right)$ and they are mutually independent. Then, the followings are hold
(i) for $t=1, \ldots, T$, conditional on the information $\mathcal{F}_{0}$, a density function of regime vector $\bar{s}_{t}$ is given by

$$
\begin{equation*}
f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right)=\prod_{i=0}^{N} \frac{\Gamma\left(\sum_{j=1}^{N} \alpha_{i j}\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}\right)} \frac{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)}{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)\right)} \tag{84}
\end{equation*}
$$

(ii) and for $t=2, \ldots, T$, conditional on the regime vector $\bar{s}_{t}$ and information $\mathcal{F}_{0}$, a density function of regime $s_{t}$ is given by

$$
\begin{equation*}
f\left(s_{t} \mid \bar{s}_{t-1}, \mathcal{F}_{0}\right)=\frac{\alpha_{s_{t-1} s_{t}}+n_{s_{t-1} s_{t}}\left(\bar{s}_{t-1}\right)}{\sum_{s_{t}=1}^{N}\left(\alpha_{s_{t-1} s_{t}}+n_{s_{t-1} s_{t}}\left(\bar{s}_{t-1}\right)\right)}, \tag{85}
\end{equation*}
$$

where the random variable $n_{i j}\left(\bar{s}_{t}\right)$ equals

$$
\begin{equation*}
n_{i j}\left(\bar{s}_{t}\right):=\#\left\{m \in\{0,1, \ldots, t-1\} \mid s_{m-1}=i, s_{m}=j, m=2, \ldots, t\right\} \tag{86}
\end{equation*}
$$

for $t=2, \ldots, T, i=1, \ldots, N$, and $j=1, \ldots, N$ and

$$
n_{i j}\left(s_{1}\right):=\left\{\begin{array}{lll}
1 & \text { if } \quad i=0, s_{1}=j  \tag{87}\\
0 & \text { if } \quad \text { otherwise }
\end{array}\right.
$$

for $i=0, \ldots, N$ and $j=1, \ldots, N$.

Proof. Since for $t=2, \ldots, T$, the random variable $n_{i j}\left(\bar{s}_{t}\right)$ represents a number of consequential elements, which equals $(i, j)$ of the regime vector $\bar{s}_{t}$, we have that

$$
\begin{equation*}
f\left(\bar{s}_{t} \mid \mathrm{P}, \mathcal{F}_{0}\right)=\prod_{m=1}^{t} p_{s_{m-1} s_{m}}=\prod_{i=0}^{N} \prod_{j=1}^{N} p_{i j}^{n_{i j}\left(\bar{s}_{t}\right)} \tag{88}
\end{equation*}
$$

Consequently, it follows from the joint density function of the random transition probability matrix $P$, which is given by equation (75) that

$$
\begin{equation*}
f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right)=\int_{\mathrm{P}} f\left(\bar{s}_{t} \mid \mathrm{P}, \mathcal{F}_{0}\right) f\left(\mathrm{P} \mid \mathcal{F}_{0}\right) d \mathrm{P}=\prod_{i=0}^{N} \frac{\Gamma\left(\sum_{j=1}^{N} \alpha_{i j}\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}\right)} \frac{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)}{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)\right)} \tag{89}
\end{equation*}
$$

On the other hand, as $f\left(s_{t} \mid \bar{s}_{t}, \mathcal{F}_{0}\right)=f\left(\bar{s}_{t} \mid \mathcal{F}_{0}\right) / f\left(\bar{s}_{t-1} \mid \mathcal{F}_{0}\right)$, one obtains

$$
\begin{equation*}
f\left(s_{t} \mid \bar{s}_{t-1}, \mathcal{F}_{0}\right)=\prod_{i=0}^{N} \frac{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)}{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)\right)} \frac{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t-1}\right)\right)\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t-1}\right)\right)} \tag{90}
\end{equation*}
$$

Consequently, since $n_{i j}\left(\bar{s}_{t}\right)=n_{i j}\left(\bar{s}_{t-1}\right)+\delta_{i j}\left(s_{t}\right)$ for $t=2, \ldots, T$ and $\Gamma(x+1)=x \Gamma(x)$ for $x>0$, we find that

$$
\begin{equation*}
f\left(s_{t} \mid \bar{s}_{t-1}, \mathcal{F}_{0}\right)=\frac{\alpha_{s_{t-1} s_{t}}+n_{s_{t-1} s_{t}}\left(\bar{s}_{t-1}\right)}{\sum_{s_{t}=1}^{N}\left(\alpha_{s_{t-1} s_{t}}+n_{s_{t-1} s_{t}}\left(\bar{s}_{t-1}\right)\right)} \tag{91}
\end{equation*}
$$

where the random variable $\delta_{i j}\left(s_{t}\right)$ equals

$$
\delta_{i j}\left(s_{t}\right)=\left\{\begin{array}{lll}
1 & \text { if } & s_{t-1}=i, s_{t}=j  \tag{92}\\
0 & \text { if } & \text { otherwise }
\end{array}\right.
$$

That completes the proof.
It is worth mentioning that according to equation (85) in the above Proposition, conditional on $\mathcal{F}_{0}$, the regime-switching process $s_{t}$ is not a Markov chain.

### 3.1.2 Characteristic Function

By equation (62), for $k=1, \ldots, r_{\gamma}$, equation (73) can be written by

$$
\begin{align*}
f\left(\pi_{\gamma_{k}}^{\circ} \mid \Sigma_{\gamma_{k}}, \gamma_{k}, \mathcal{F}_{t}\right) & =\frac{1}{(2 \pi)^{n d / 2} \mid \Lambda_{0, \gamma_{k}|t|^{-n / 2}\left|\Sigma_{\gamma_{k}}\right|^{d / 2}}} \\
& \left.\times \exp \left\{-\frac{1}{2} \operatorname{tr}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right) \Lambda_{0, \gamma_{k} \mid t}\left(\pi_{\gamma_{k}}^{\circ}-C_{t, \gamma_{k}}\right)^{\prime} \Sigma_{\gamma_{k}}^{-1}\right)\right\} \tag{93}
\end{align*}
$$

To obtain characteristic function of the random coefficient matrix $\pi_{\gamma_{k}}^{\circ}$ for given regime $\gamma_{k}$ and information $\mathcal{F}_{t}$, we use the matrix generalized inverse Gaussian (MGIG) distribution. For a positive definite $(n \times n)$ matrix $\Sigma$, the density function of the MGIG distribution is given by

$$
\begin{equation*}
f(\Sigma)=\frac{2^{n \lambda}}{|\mathrm{~A}|^{\lambda} \mathcal{B}_{\lambda}\left(\frac{1}{4} \mathrm{BA}\right)}|\Sigma|^{\lambda-(n+1) / 2} \exp \left\{-\frac{1}{2} \operatorname{tr}\left(\mathrm{~A} \Sigma^{-1}+\mathrm{B} \Sigma\right)\right\} \tag{94}
\end{equation*}
$$

where $\mathcal{B}_{\lambda}(\cdot)$ is the matrix argument modified Bessel function of the second kind with index $\lambda$, which is defined by

$$
\begin{equation*}
\mathcal{B}_{\lambda}\left(\frac{1}{4} \mathrm{BA}\right):=\left|\frac{1}{2} \mathrm{~B}\right|^{-\lambda} \int_{\Sigma>0}|\Sigma|^{-\lambda-(n+1) / 2} \exp \left\{-\frac{1}{2} \operatorname{tr}\left(\mathrm{~A} \Sigma^{-1}+\mathrm{B} \Sigma\right)\right\} d \Sigma \tag{95}
\end{equation*}
$$

and for $n \geq 2$, the index $\lambda \in \mathbb{R}$ and the $(n \times n)$ matrices $A$ and $B$ satisfy

$$
\left\{\begin{array}{l}
\mathrm{A} \geq 0, \mathrm{~B}>0 \quad \text { if } \quad \lambda \geq \frac{1}{2}  \tag{96}\\
\mathrm{~A}>0, \mathrm{~B}>0 \quad \text { if } \quad-\frac{1}{2}(n-1) \leq \lambda<\frac{1}{2} \\
\mathrm{~A}>0, \mathrm{~B} \geq 0
\end{array} \quad \text { if } \quad \lambda<-\frac{1}{2}(n-1) ~ \$\right.
$$

see Butler (1998). Its one dimensional version is called generalized inverse Gaussian distribution and it is widely used to model returns of financial assets, see McNeil et al. (2005). It is the well-known fact that a characteristic function of the random coefficient matrix $\pi_{\gamma_{k}}^{\circ}$ for given regime $\gamma_{k}$, covariance matrix $\Sigma_{\gamma_{k}}$, and information $\mathcal{F}_{t}$ is given by

$$
\begin{align*}
\varphi\left(Z_{\gamma_{k}} \mid \Sigma_{\gamma_{k}}, \gamma_{k}, \mathcal{F}_{t}\right) & =\mathbb{E}\left[\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\gamma_{k}}^{\prime} \pi_{\gamma_{k}}^{\circ}\right)\right\} \mid \Sigma_{\gamma_{k}}, \gamma_{k}, \mathcal{F}_{t}\right] \\
& =\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\gamma_{k}}^{\prime} C_{t, \gamma_{k}}-\frac{1}{2} Z_{\gamma_{k}}^{\prime} \Lambda_{0, \gamma_{k} \mid t}^{-1} Z_{\gamma_{k}} \Sigma_{\gamma_{k}}\right)\right\} \tag{97}
\end{align*}
$$

where $\mathrm{i}=\sqrt{-1}$ is the imaginary unit, $Z_{\gamma_{k}}$ is an $(n \times d)$ matrix, corresponding to the regime $\gamma_{k}$. Consequently, by the iterated expectation formula, conditional density function (74), and the above characteristic function of the matrix normal distribution, conditional on the regime $\gamma_{k}$ and information $\mathcal{F}_{t}$, a characteristic function of the random coefficient matrix $\pi_{\gamma_{k}}^{\circ}$ is obtained by

$$
\begin{align*}
\varphi\left(Z_{\gamma_{k}} \mid \gamma_{k}, \mathcal{F}_{t}\right) & =\mathbb{E}\left[\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\gamma_{k}}^{\prime} \pi_{\gamma_{k}}^{\circ}\right)\right\} \mid \gamma_{k}, \mathcal{F}_{t}\right] \\
& =\frac{\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\gamma_{k}}^{\prime} C_{t, \gamma_{k}}\right)\right\}\left|\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right|^{\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}}\left|Z_{\gamma_{k}}^{\prime} \Lambda_{0, \gamma_{k} \mid t}^{-1} Z_{\gamma_{k}}\right|^{\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}}}{\Gamma_{n}\left(\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right) / 2\right) 2^{n\left(\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}\right)}} \\
& \times \mathcal{B}_{\nu_{0, \gamma_{k}}+q_{t, \gamma_{k}}}\left(Z_{\gamma_{k}}^{\prime} \Lambda_{0, \gamma_{k} \mid t}^{-1} Z_{\gamma_{k}}\left(\bar{B}_{t, \gamma_{k}}+V_{0, \gamma_{k}}\right) / 4\right) \tag{98}
\end{align*}
$$

Similarly, it can be shown that

$$
\begin{align*}
\varphi\left(Z_{\delta_{k}} \mid \delta_{k}, \mathcal{F}_{0}\right) & =\mathbb{E}\left[\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\delta_{k}}^{\prime} \pi_{\delta_{k}}^{\circ}\right)\right\} \mid \delta_{k}, \mathcal{F}_{0}\right] \\
& =\frac{\exp \left\{\operatorname{tr}\left(\mathrm{i} Z_{\delta_{k}}^{\prime} \pi_{0, \delta_{k}}^{\circ}\right)\right\}\left|V_{0, \delta_{k}}\right|^{\nu_{0, \delta_{k}}}\left|Z_{\delta_{k}}^{\prime} \Lambda_{0, \delta_{k}} Z_{\delta_{k}}\right|^{\nu_{0, \delta_{k}}}}{\Gamma_{n}\left(\left(\nu_{0, \delta_{k}}\right) / 2\right) 2^{n \nu_{0, \delta_{k}}}} \\
& \times \mathcal{B}_{\nu_{0, \delta_{k}}}\left(Z_{\delta_{k}}^{\prime} \Lambda_{0, \delta_{k}} Z_{\delta_{k}} V_{0, \delta_{k}} / 4\right) \tag{99}
\end{align*}
$$

The above characteristic functions can be used to obtain raw moments of the random coefficient matrix $\pi_{\beta}^{\circ}$ for given the regime vector $s$ and information $\mathcal{F}_{t}$. For example, since conditional on $s$ and $\mathcal{F}_{t}$, for $k=1, \ldots, r_{\gamma}$ and $\ell=1, \ldots, r_{\delta}$, coefficient matrices $\pi_{\beta_{k}}$ and $\pi_{\delta_{\ell}}$ are independent, we have that

$$
\begin{align*}
& \mathbb{E}\left[\left(\pi_{\gamma_{1}}^{\circ}\right)_{i_{\gamma_{1}}, j_{\gamma_{1}}}^{m_{\gamma_{1}}} \ldots\left(\pi_{\gamma_{r_{\gamma}}}^{\circ}\right)_{i_{\gamma_{r_{\gamma}}}, j_{\gamma_{r_{\gamma}}}}^{m_{\gamma_{r_{\gamma}}}}\left(\pi_{\delta_{1}}^{\circ}\right)_{i_{\delta_{1}}, j_{\delta_{1}}}^{m_{\delta_{1}}} \ldots\left(\pi_{\delta_{r_{\delta}}}^{\circ}\right)_{\left.i_{\delta_{r_{\delta}}, j_{\delta_{r_{\delta}}}}^{m_{\delta_{r_{\delta}}}} \mid s, \mathcal{F}_{t}\right]}^{=\prod_{k=1}^{r_{\gamma}} \frac{1}{\mathrm{i}^{m_{\gamma_{k}}}} \frac{\partial^{m_{\gamma_{k}}} \varphi\left(Z_{\gamma_{k}} \mid \gamma_{k}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k}}\right)_{i_{\gamma_{k}}, j_{\gamma_{k}}}^{m_{\gamma_{k}}}} \times \prod_{\ell=1}^{r_{\delta}} \frac{1}{\mathrm{i}^{m_{\delta_{\ell}}}} \frac{\partial^{m_{\delta_{\ell}}} \varphi\left(Z_{\delta_{\ell}} \mid \delta_{\ell}, \mathcal{F}_{0}\right)}{\partial\left(Z_{\gamma_{k}}\right)_{i_{\delta_{k}}, j_{\delta_{\ell}}}^{m_{\delta_{\ell}}}},}\right.
\end{align*}
$$

where for a generic $(n \times m)$ matrix $O,(O)_{i, j}$ denotes an $(i, j)$-th element of the matrix $O$ for $i=$ $1, \ldots, n$ and $j=1, \ldots, m$. The partial derivatives can be calculated by the numerical methods. The raw moments may be used to obtain forecast of the vector of endogenous variables. In particular, conditional on $\bar{s}_{t+2}$, the optimal forecast, which minimizes the mean squared errors for forecast horizon 2 at forecast origin $t$ equals an expectation of the vector of endogenous variables at time $(t+2)$ for given $\mathcal{F}_{t}$. Thus, the forecast is given by the following equation

$$
\begin{align*}
\mathbb{E}\left[y_{t+2} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right] & =\mathbb{E}\left[A_{0, s_{t+2}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]+\mathbb{E}\left[A_{1, s_{t+2}} A_{0, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right] \psi_{t+1}  \tag{101}\\
& +\sum_{k=1}^{p} \mathbb{E}\left[A_{1, s_{t+2}} A_{k, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right] y_{t+1-k}+\sum_{k=2}^{p} \mathbb{E}\left[A_{k, s_{t+2}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right] y_{t+2-k}
\end{align*}
$$

where the conditional expectations $\mathbb{E}\left[A_{k, s_{t+2}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]$ for $k=0,2, \ldots, p$ are calculated by equations (75) and (76) and the conditional expectations $\mathbb{E}\left[A_{1, s_{t+2}} A_{k, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]$ for $k=0, \ldots, p$ are calculated equation (100). To illustrative purpose, we assume that $s_{t+1}, s_{t+2} \in \mathcal{A}_{\bar{s}_{t}} \cap \mathcal{A}_{\bar{s}_{t}^{c}}$ and positions of the regimes $s_{t+1}$ and $s_{t+2}$ in the regime vector $\gamma$ are $k_{1 *}$ and $k_{2 *}$, respectively, that is,

$$
\begin{equation*}
k_{i *}=\left\{k \in\left\{1, \ldots, r_{\gamma}\right\} \mid \gamma_{k}=s_{t+i}, k=1, \ldots, r_{\gamma}\right\} \tag{102}
\end{equation*}
$$

for $i=1,2$. Then, we have that for $i=1, \ldots, n, j=1, \ldots, l$, and $k=0$,

$$
\begin{equation*}
\left(\mathbb{E}\left[A_{1, s_{t+2}} A_{k, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]\right)_{i, j}=-\sum_{\ell=1}^{n} \frac{\partial \varphi\left(Z_{\gamma_{k_{2 *}}} \mid \gamma_{k_{2 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{2 *}}}\right)_{i, l+\ell}} \frac{\partial \varphi\left(Z_{\gamma_{k_{1 *}}} \mid \gamma_{k_{1 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{1 *}}}\right)_{\ell, j}} \tag{103}
\end{equation*}
$$

for $s_{t+1}=s_{t+2}, i=1, \ldots, n$, and $k=1$,

$$
\begin{align*}
& \left(\mathbb{E}\left[A_{1, s_{t+2}} A_{k, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]\right)_{i, i} \\
& =-\sum_{\ell=1, \ell \neq i}^{n} \frac{\partial \varphi\left(Z_{\gamma_{k_{1 *}}} \mid \gamma_{k_{1 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{1 *}}}\right)_{i, l+\ell}} \frac{\partial \varphi\left(Z_{\gamma_{k_{1 *}}} \mid \gamma_{k_{1 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{1 *}}}\right)_{l+\ell, i}}-\frac{\partial^{2} \varphi\left(Z_{\gamma_{k_{1 *}}} \mid \gamma_{k_{1 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{1 *}}}\right)_{i, l+i}} \tag{104}
\end{align*}
$$

and for other cases $(i, j=1, \ldots, n$ and $k=1, \ldots, p)$,

$$
\begin{equation*}
\left(\mathbb{E}\left[A_{1, s_{t+2}} A_{k, s_{t+1}} \mid \bar{s}_{t+2}, \mathcal{F}_{t}\right]\right)_{i, j}=-\sum_{\ell=1}^{n} \frac{\partial \varphi\left(Z_{\gamma_{k_{2 *}}} \mid \gamma_{k_{2 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{2 *}}}\right)_{i, l+\ell}} \frac{\partial \varphi\left(Z_{\gamma_{k_{1 *}}} \mid \gamma_{k_{1 *}}, \mathcal{F}_{t}\right)}{\partial\left(Z_{\gamma_{k_{1 *}}}\right)_{l+(k-1) p+\ell, j}} \tag{105}
\end{equation*}
$$

Because the exact calculation of forecast of the process of endogenous variables is complicated, we consider an approximation, which is used to calculate the forecast of the endogenous variables in Bańbura et al. (2010). For $u=t+1, \ldots, T$, by the iterated expectation formula, conditional on the regime vector $s$, the exact forecast is given by the following equation

$$
\begin{equation*}
\mathbb{E}\left[y_{u} \mid s, \mathcal{F}_{t}\right]=\mathbb{E}\left[\Pi_{s_{u}} \mathrm{Y}_{u} \mid s, \mathcal{F}_{t}\right]=\mathbb{E}\left[\mathbb{E}\left[\Pi_{s_{u}} \mid s, \mathcal{F}_{u-1}\right] \mathrm{Y}_{u} \mid s, \mathcal{F}_{t}\right] \tag{106}
\end{equation*}
$$

Bańbura et al. (2010) approximate the last expression by $\mathbb{E}\left[\Pi_{s_{u}} \mid s, \mathcal{F}_{u-1}\right] \mathbb{E}\left[\mathrm{Y}_{u} \mid s, \mathcal{F}_{t}\right]$. Consequently, the forecast is approximated by

$$
\begin{equation*}
\mathbb{E}\left[y_{u} \mid s, \mathcal{F}_{t}\right] \approx \mathbb{E}\left[\Pi_{s_{u}} \mid s, \mathcal{F}_{u-1}\right] \mathbb{E}\left[\mathrm{Y}_{u} \mid s, \mathcal{F}_{t}\right] \tag{107}
\end{equation*}
$$

For $t=u-1$, the approximation becomes exact, namely,

$$
\begin{equation*}
\mathbb{E}\left[y_{u} \mid s, \mathcal{F}_{u-1}\right]=\mathbb{E}\left[\Pi_{s_{u}} \mid s, \mathcal{F}_{u-1}\right] \mathrm{Y}_{u} \tag{108}
\end{equation*}
$$

However, for $u=t+2, \ldots, T$, one should study the quality of the very simple approximation.

### 3.1.3 Minnesota Prior

In practice, one usually adopts Minnesota prior to estimating the parameters of the VAR $(p)$ process. The first version of Minnesota prior was introduced by Litterman (1979). Also, Bańbura et al. (2010) used Minnesota prior for large Bayesian VAR and showed that the forecast of large Bayesian VAR is better than small Bayesian VAR. However, there are many different variants of the Minnesota prior, we consider a prior, which is included in Miranda-Agrippino and Ricco (2018). The idea of Minnesota prior is that it shrinks diagonal elements of the matrix $A_{1}$ toward $\phi_{i}$ and off-diagonal elements of $A_{1, s_{t}}$ and all elements of other matrices $A_{0, s_{t}}, A_{2, s_{t}}, \ldots, A_{p, s_{t}}$ toward 0 , where $\phi_{i}$ is 0 for a stationary variable $y_{i, t}$ and 1 for a variable with unit root $y_{i, t}$. For the prior, it is assumed that conditional on
$\Sigma_{s_{t}}, s_{t}$, and $\mathcal{F}_{0}, A_{0}, A_{1}, \ldots, A_{p}$ are jointly normally distributed, and for $(i, j)$-th element of the matrix $A_{\ell, s_{t}}(\ell=0, \ldots, p)$, it holds

$$
\begin{gather*}
\mathbb{E}\left(\left(A_{\ell, s_{t}}\right)_{i, j} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0}\right)= \begin{cases}\phi_{i} & \text { if } i=j, \ell=1 \\
0 & \text { if otherwise }\end{cases}  \tag{109}\\
\operatorname{Var}\left(\left(A_{0, s_{t}}\right)_{i, j} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0}\right)=\left(\sigma_{i, s_{t}} / \varepsilon_{s_{t}}\right)^{2} \tag{110}
\end{gather*}
$$

and

$$
\operatorname{Var}\left(\left(A_{\ell, s_{t}}\right)_{i j} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0}\right)=\left\{\begin{array}{ll}
\left(\frac{\sigma_{i, s_{t}}}{\ell^{\lambda_{2, s_{t}}} \lambda_{1, s_{t}} \tau_{i, s_{t}}}\right)^{2} & \text { if } \quad i=j,  \tag{111}\\
\left(\frac{\sigma_{i, s_{t}}}{\ell^{\lambda_{2, s_{t}} \lambda_{1, s_{t}} \tau_{j, s_{t}}}}\right)^{2} & \text { if otherwise }
\end{array} \quad \text { for } \ell=1, \ldots, p\right.
$$

The parameter $\varepsilon_{s_{t}}^{2}$ is a small number and it corresponds to an uninformative diffuse prior for $\left(A_{0, s_{t}}\right)_{i, j}$, the parameter $\lambda_{1, s_{t}}$ controls the overall tightness of the prior distribution, the parameter $\lambda_{2, s_{t}}$ controls amount of information prior information at higher lags, and $\tau_{i, s_{t}}$ is a scaling parameter, see MirandaAgrippino and Ricco (2018). Thus, the factor $1 / \ell^{2 \lambda_{2, s_{t}}}$ represents a rate at which prior variance decreases with increasing lag length.

According to Bańbura et al. (2010), it can be shown that the following equation satisfies the prior conditions (109), (110), and (111)

$$
\begin{equation*}
\hat{y}_{s_{t}}^{\circ}=\Pi_{s_{t}} \hat{Y}_{s_{t}}^{\circ}+\hat{\xi}^{\circ} \tag{112}
\end{equation*}
$$

where $\hat{y}_{s_{t}}^{\circ}$ and $\hat{\mathrm{Y}}_{s_{t}}^{\circ}$ are $(n \times d)$ and $(d \times d)$ matrices of dummy variables and are defined by

$$
\begin{equation*}
\hat{y}_{s_{t}}^{\circ}:=\left[0_{[n \times l]}: \lambda_{1, s_{t}} \operatorname{diag}\left\{\phi_{1} \tau_{1, s_{t}}, \ldots, \phi_{n} \tau_{n, s_{t}}\right\}: 0_{[n \times(n-1) p]}\right] \tag{113}
\end{equation*}
$$

and

$$
\hat{\mathrm{Y}}_{s_{t}}^{\circ}:=\left[\begin{array}{cc}
\varepsilon_{s_{t}} I_{l} & 0_{[l \times n p]}  \tag{114}\\
0_{[n p \times l]} & \lambda_{1, s_{t}}\left(J_{s_{t}} \otimes \operatorname{diag}\left\{\tau_{1, s_{t}}, \ldots, \tau_{n, s_{t}}\right\}\right)
\end{array}\right]
$$

with $J_{s_{t}}:=\operatorname{diag}\left\{1^{\lambda_{2, s_{t}}}, \ldots, p^{\lambda_{2, s_{t}}}\right\}$, respectively, and $\hat{\xi}^{\circ}:=\left[\xi_{1}: \cdots: \xi_{d}\right]$ is an $(n \times d)$ matrix of residual process. Note that one can add constraints for elements of the coefficient matrix $\Pi_{s_{t}}$ to the matrices of dummy variables, see Miranda-Agrippino and Ricco (2018). It is worth mentioning that the matrices of dummy variables $\hat{y}_{s_{t}}$ and $\hat{Y}_{s_{t}}$ should not depend on the covariance matrix $\Sigma_{s_{t}}$. If the dummy variables depend on the covariance matrix, an OLS estimator $\hat{\pi}_{s_{t}}$, and matrix $\Lambda_{0, s_{t}}$ depend on the covariance matrix $\Sigma_{s_{t}}$, see below. Consequently, in this case, one can not use the results of Proposition 2. For this reason, we choose the prior condition (111). Equation (112), can be written by

$$
\begin{equation*}
\hat{y}_{s_{t}}=\left(\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime} \otimes I_{n}\right) \pi_{s_{t}}+\hat{\xi} \tag{115}
\end{equation*}
$$

where $\hat{y}_{s_{t}}$ and $\hat{\xi}$ are $([n d] \times 1)$ vectors and are vectorizations of the matrix of dummy variables $\hat{y}_{s_{t}}^{\circ}$ and matrix of the residual process $\hat{\xi}^{\circ}$, respectively, i.e., $\hat{y}_{s_{t}}:=\operatorname{vec}\left(\hat{y}_{s_{t}}^{\circ}\right)$ and $\hat{\xi}:=\operatorname{vec}\left(\hat{\xi}^{\circ}\right)$. It follows from equation (115) that

$$
\begin{equation*}
\pi_{s_{t}} \stackrel{d}{=}\left(\left(\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime}\right)^{-1} \hat{\mathrm{Y}}_{s_{t}}^{\circ}\right) \otimes I_{n}\right) \hat{y}_{s_{t}}+\left(\left(\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime}\right)^{-1} \hat{\mathrm{Y}}_{s_{t}}^{\circ}\right) \otimes I_{n}\right) \hat{\xi} \tag{116}
\end{equation*}
$$

where $d$ denotes equal distribution. It should be noted that the first term of the right-hand side of the above equation is a vecorization of the ordinary least square (OLS) estimator of the coefficient matrix $\Pi_{s_{t}}$, namely, $\pi_{0, s_{t}}:=\operatorname{vec}\left(\hat{\Pi}_{s_{t}}\right)=\operatorname{vec}\left(\hat{y}_{s_{t}}^{\circ}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime}\right)^{-1}\right)$. Consequently, conditional on $\Sigma_{s_{t}}, s_{t}$, and $\mathcal{F}_{0}$, a distribution of the coefficient vector $\pi_{s_{t}}$ is given by

$$
\begin{equation*}
\pi_{s_{t}} \mid \Sigma_{s_{t}}, s_{t}, \mathcal{F}_{0} \sim \mathcal{N}\left(\pi_{0, s_{t}},\left(\Lambda_{0, s_{t}} \otimes \Sigma_{s_{t}}\right)\right) \tag{117}
\end{equation*}
$$

where $\Lambda_{0, s_{t}}:=\left(\hat{\mathrm{Y}}_{s_{t}}\left(\hat{\mathrm{Y}}_{s_{t}}^{\circ}\right)^{\prime}\right)^{-1}$ is a $(d \times d)$ diagonal matrix. Consequently, conditional on $\Sigma_{s_{t}}$, $s_{t}$, and $\mathcal{F}_{0}$, columns of the random coefficient matrix $\Pi_{s_{t}}$ are independent. For the moment conditions (109), (110), and (111), we can use the results of Proposition 2.

### 3.2 Simulation Methods

By applying Propositions 2 and 3, one can obtain exact density function of the random vector $\bar{y}_{t}$, namely,

$$
\begin{equation*}
f\left(\bar{y}_{t} \mid \mathcal{F}_{0}\right)=\sum_{\bar{s}_{t}} f\left(\bar{y}_{t} \mid \bar{s}_{t}, \mathcal{F}_{0}\right) \prod_{i=0}^{N} \frac{\Gamma\left(\sum_{j=1}^{N} \alpha_{i j}\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}\right)} \frac{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)}{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}\right)\right)\right)} . \tag{118}
\end{equation*}
$$

However, this exact density function has the following two main disadvantages:
(i) it is difficult to obtain characteristics (such as mean, quantile, marginal densities, distribution, and so on) of the mixture density function $f\left(\bar{y}_{t} \mid \mathcal{F}_{0}\right)$,
(ii) and it is difficult to calculate the sum with respect to $\bar{s}_{t}$. For example, if the length of the regime vector $\bar{s}_{t}$ equals 30 and the regime number equals 3 , then we have to calculate $3^{30} \approx 2.06 \times 10^{14}$ summands.

If the dimensions increase, the disadvantages are seriously worsen. Therefore, from a practical point of view, we need to develop Monte-Carlo simulation method.

### 3.2.1 General Method

According to the conditional probability formula and Proposition 1, we have that

$$
\begin{align*}
f\left(\bar{y}_{t}^{c}, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{t}\right) & =f\left(\bar{y}_{t}^{c} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{t}\right) f_{*}\left(\pi_{\delta} \mid \Sigma_{\delta}, \delta, \mathcal{F}_{0}\right) f_{*}\left(\Sigma_{\delta} \mid \delta, \mathcal{F}_{0}\right) \\
& \times f\left(\pi_{\alpha} \mid \Sigma_{\alpha}, \bar{s}_{t}, \mathcal{F}_{t}\right) f\left(\Sigma_{\alpha} \mid \bar{s}_{t}, \mathcal{F}_{t}\right) f\left(\bar{s}_{t}^{c} \mid s_{t}, \mathrm{P}, \mathcal{F}_{0}\right) f\left(\bar{s}_{t}, \mathrm{P} \mid \mathcal{F}_{t}\right) \tag{119}
\end{align*}
$$

The above equation tells us that how to generate random sample from $\left(\bar{y}_{t}^{c}, \pi_{\hat{s}_{t}}, \Sigma_{\hat{s}_{t}}, s, \mathrm{P}\right)$ for given information $\mathcal{F}_{t}$. The direction of our simulation method move toward from right to left for the above equation. To generate random samples, first, generate the regime vector and transition probability matrix $\left(\bar{s}_{t}, \mathrm{P}\right)$ from the posterior density function $f\left(\bar{s}_{t}, \mathrm{P} \mid \mathcal{F}_{t}\right)$. Next, using the regime vector $\bar{s}_{t}$ and transition probability matrix P , generate regime vector $\bar{s}_{t}^{c}$ from the conditional density function $f\left(\bar{s}_{t}^{c} \mid \bar{s}_{t}, \mathrm{P}, \mathcal{F}_{0}\right)$, so on.

First, we consider a simulation method that generate the regime vector and transition probability matrix ( $\bar{s}_{t}, \mathrm{P}$ ) from the posterior density function $f\left(\bar{s}_{t}, \mathrm{P} \mid \mathcal{F}_{t}\right)$. As mentioned above, for given $\mathcal{F}_{0}$, the regime-switching process $s_{t}$ is not a Markov chain. Therefore, we develop the Gibbs sampling method to generate ( $\bar{s}_{t}, \mathrm{P}$ ). In the Bayesian statistics, the Gibbs sampling is often used when the joint distribution is not known explicitly or is difficult to sample from directly, but the conditional distribution of each variable is known and is easy to sample from. Constructing the Gibbs sampler to approximate the joint posterior distribution $f\left(\bar{s}_{t}, \mathrm{P} \mid \mathcal{F}_{t}\right)$ is straightforward: New values $\left(\bar{s}_{t}(\ell), \mathrm{P}(\ell)\right)$, $\ell=1, \ldots, \mathcal{L}$ can be generated by

- generate $\mathrm{P}(\ell)$ from $f\left(\mathrm{P} \mid \bar{s}_{t}(\ell), \mathcal{F}_{t}\right)$,
- generate $\bar{s}_{t}(\ell)$ from $f\left(\bar{s}_{t} \mid \mathrm{P}(\ell), \mathcal{F}_{t}\right)$.

To generate $\mathrm{P}(\ell)$ from $f\left(\mathrm{P} \mid \bar{s}_{t}(\ell), \mathcal{F}_{t}\right)$, we apply equation (17) in Proposition 1, density function (83), equation (84) in Proposition 3, and the Bayesian formula. Then, we have that

$$
\begin{equation*}
f\left(\mathrm{P} \mid \bar{s}_{t}(\ell), \mathcal{F}_{t}\right)=\prod_{i=0}^{N} \frac{\Gamma\left(\sum_{j=1}^{N}\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}(\ell)\right)\right)\right)}{\prod_{j=1}^{N} \Gamma\left(\alpha_{i j}+n_{i j}\left(\bar{s}_{t}(\ell)\right)\right)} \prod_{j=1}^{N} p_{i j}^{\alpha_{i j}+n_{i j}\left(\bar{s}_{t}(\ell)\right)-1} . \tag{120}
\end{equation*}
$$

Thus, one can deduce that conditional on $\bar{s}_{t}(\ell)$ and $\mathcal{F}_{t}$, for $i=0, \ldots, N$, each row of the transition probability matrix P are independent and has Dirichlet distribution with parameter $\alpha_{i}\left(\bar{s}_{t}(\ell)\right):=$ $\left(\alpha_{i 1}+n_{i 1}\left(\bar{s}_{t}(\ell)\right), \ldots, \alpha_{i N}+n_{i N}\left(\bar{s}_{t}(\ell)\right)\right)^{\prime}$. Consequently, the simulation method that generate $\mathrm{P}(\ell)$ for given $\bar{s}_{t}(\ell)$ and $\mathcal{F}_{t}$ as follows:

- generate $\mathrm{P}_{i}(\ell)$ from $\operatorname{Dir}\left(\alpha_{i}\left(\bar{s}_{t}(\ell)\right)\right)$ for $i=0, \ldots, N$.

Collect $\mathrm{P}_{i}(\ell)$ for $i=0, \ldots, N$ into an $([N+1] \times N)$ matrix $\mathrm{P}(\ell)$, that is, $\mathrm{P}(\ell):=\left[\mathrm{P}_{0}(\ell)^{\prime}: \cdots: \mathrm{P}_{N}(\ell)^{\prime}\right]^{\prime}$. Let $\hat{\mathrm{P}}(\ell):=\left[\mathrm{P}_{1}(\ell)^{\prime}: \cdots: \mathrm{P}_{N}(\ell)^{\prime}\right]^{\prime}$ be an $(N \times N)$ transition probability matrix, which omits first row of the matrix $\mathrm{P}(\ell)$.

Now we consider a sampling method that generate $\bar{s}_{t}(\ell)$ from $f\left(\bar{s}_{t} \mid \mathrm{P}(\ell), \mathcal{F}_{t}\right)$. Here we follow the book of Hamilton (1994), see also Battulga (2022) and Battulga (2023a). If we assume that the regime-switching process in regime $j$ at time $u$, then according to equation (81), the conditional density function of the random vector $y_{u}$ is given by the following equation

$$
\begin{align*}
\eta_{u, j} & :=f\left(y_{u} \mid s_{u}=j, \mathcal{F}_{u-1}\right) \\
& =\frac{1}{\pi^{n / 2}} \frac{\left|\Lambda_{0, j}\right|^{-n / 2} \Gamma_{n}\left(\left(\nu_{0, j}+1\right) / 2\right)\left|V_{0, j}\right|^{\nu_{0, j} / 2}}{\left(1+\mathrm{Y}_{u}^{\prime} \Lambda_{0, j} \mathrm{Y}_{u}\right)^{n / 2} \Gamma_{n}\left(\nu_{0, j} / 2\right)\left|B_{u, j}+V_{0, j}\right|^{\left(\nu_{0, j}+1\right) / 2}} \tag{121}
\end{align*}
$$

for $u=1, \ldots, t$ and $j=1, \ldots, N$, where $B_{u, j}$ is given by equation (82). For all $u=1, \ldots, t$, we collect the conditional density functions of $y_{u}$ into an $(n \times 1)$ vector $\eta_{t}$, that is, $\eta_{u}:=\left(\eta_{u, 1}, \ldots, \eta_{u, N}\right)^{\prime}$. Let us denote a probabilistic inference about the value of the regime-switching process $s_{u}$ equals to $j$, based on the information $\mathcal{F}_{u}$ and transition probability matrix $\mathrm{P}(\ell)$ by $\mathbb{P}\left(s_{u}=j \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right)$. Collect these conditional probabilities $\mathbb{P}\left(s_{u}=j \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right)$ for $j=1, \ldots, N$ into an $(N \times 1)$ vector $z_{u \mid u}(\ell)$, that is, $z_{u \mid u}(\ell):=\left(\mathbb{P}\left(s_{u}=1 \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right), \ldots, \mathbb{P}\left(s_{u}=N \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right)\right)^{\prime}$. Also, we need a probabilistic forecast about the value of the regime-switching process at time $u+1$ equals $j$ conditional on data up to and including time $u$ and transition probability matrix $\mathrm{P}(\ell)$. Collect these forecasts into an $(N \times 1)$ vector $z_{u+1 \mid u}(\ell)$, that is, $z_{u+1 \mid u}(\ell):=\left(\mathbb{P}\left(s_{u+1}=1 \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right), \ldots, \mathbb{P}\left(s_{u+1}=N \mid \mathrm{P}(\ell), \mathcal{F}_{u}\right)\right)^{\prime}$.

The probabilistic inference and forecast for each time $u=1, \ldots, t$ can be found by iterating on the following pair of equations:

$$
\begin{equation*}
z_{u \mid u}(\ell)=\frac{\left(z_{u \mid u-1}(\ell) \odot \eta_{u}\right)}{i_{N}^{\prime}\left(z_{u \mid u-1}(\ell) \odot \eta_{u}\right)} \quad \text { and } \quad z_{u+1 \mid u}(\ell)=\hat{\mathrm{P}}(\ell)^{\prime} z_{u \mid u}(\ell), \quad u=1, \ldots, t \tag{122}
\end{equation*}
$$

where $\odot$ is the Hadamard product of two vectors, $\eta_{u}$ is the $(N \times 1)$ vector, whose $j$-th element is given by equation (121), $\hat{\mathrm{P}}(\ell)$ is the $(N \times N)$ transition probability matrix, and $i_{N}$ is an $(N \times 1)$ vector, whose elements equal 1 . Given a starting value $z_{1 \mid 0}(\ell):=\mathrm{P}_{0}(\ell)^{\prime}$ one can iterate on (122) for $u=1, \ldots, t$ to calculate the values of $z_{u \mid u}(\ell)$ and $z_{u+1 \mid u}(\ell)$. To obtain marginal distributions of the regime vector $\bar{s}_{t}$ conditional on the transition probability matrix $\mathrm{P}(\ell)$ and information $\mathcal{F}_{t}$, let us introduce $(N \times 1)$ smoothed inference vector $z_{u \mid t}(\ell):=\left(\mathbb{P}\left(s_{u}=1 \mid \mathrm{P}(\ell), \mathcal{F}_{t}\right), \ldots, \mathbb{P}\left(s_{u}=N \mid \mathrm{P}(\ell), \mathcal{F}_{t}\right)\right)^{\prime}$ for $u=1, \ldots, t$. The smoothed inference vectors can be obtained by using the Kim (1994)'s smoothing algorithm:

$$
\begin{equation*}
z_{u \mid t}(\ell)=z_{u \mid u}(\ell) \odot\left\{\hat{\mathrm{P}}(\ell)^{\prime}\left(z_{u+1 \mid t}(\ell) \oslash z_{u+1 \mid u}(\ell)\right)\right\}, \quad u=t-1, \ldots, 1 \tag{123}
\end{equation*}
$$

where $\oslash$ is an element-wise division of two vectors. The smoothed probabilities $z_{u \mid t}(\ell)$ are found by iterating on (123) backward for $u=t-1, \ldots, 1$. This iteration is started with $z_{t \mid t}(\ell)$, which is obtained from (122) for $u=t$. Thus, the simulation method that generate $\bar{s}_{t}(\ell)$ for given $\mathrm{P}(\ell)$ and $\mathcal{F}_{t}$ as follows:

- generate $s_{u}(\ell)$ from $z_{u \mid t}(\ell)$ for $u=1, \ldots, t$.

Collect $s_{u}(\ell)$ for $u=1, \ldots, t$ into $(t \times 1)$ vector $\bar{s}_{t}(\ell)$, namely, $\bar{s}_{t}(\ell):=\left(s_{1}(\ell), \ldots, s_{t}(\ell)\right)^{\prime}$.
Second, we consider a simulation method that generate the regime vector $\bar{s}_{t}^{c}(\ell)$ from the density function $f\left(\bar{s}_{t}^{c} \mid s_{t}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)$. Note that conditional on the transition probability matrix $\mathrm{P}(\ell)$ and initial information $\mathcal{F}_{0}$, the regime-switching process $s_{t}$ is a Markov chain. Thus, to sample the regime vector $\bar{s}_{t}^{c}(\ell)$ from the density function $f\left(\bar{s}_{t}^{c} \mid s_{t}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)$, we can use the Markov property. That is, we have that

$$
\begin{equation*}
f\left(\bar{s}_{t}^{c} \mid s_{t}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)=f\left(s_{T} \mid s_{T-1}, \mathrm{P}(\ell), \mathcal{F}_{0}\right) \ldots f\left(s_{t+1} \mid s_{t}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right) \tag{124}
\end{equation*}
$$

Thus, a simulation method that generate $\bar{s}_{t}^{c}(\ell)$ for given $s_{t}(\ell), \mathrm{P}(\ell)$, and $\mathcal{F}_{0}$ as follows:

- generate $s_{t+1}(\ell)$ from $f\left(s_{t+1} \mid s_{t}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)$,
- generate $s_{t+2}(\ell)$ from $f\left(s_{t+2} \mid s_{t+1}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)$,
- generate $s_{T}(\ell)$ from $f\left(s_{T} \mid s_{T-1}(\ell), \mathrm{P}(\ell), \mathcal{F}_{0}\right)$.

Collect $s_{u}(\ell)$ for $u=t+1, \ldots, T$ into $([T-t] \times 1)$ vector $\bar{s}_{t}^{c}(\ell)$, namely, $\bar{s}_{t}^{c}(\ell):=\left(s_{t+1}(\ell), \ldots, s_{T}(\ell)\right)^{\prime}$.
Third, we consider a simulation method that generate the coefficient vector $\pi_{\bar{s}_{t}^{c}(\ell)}(\ell)$ and covariance matrix $\Sigma_{\bar{s}_{t}^{c}(\ell)}(\ell)$ from the density function $f\left(\pi_{\bar{s}_{t}^{c}(\ell)}, \Sigma_{\bar{s}_{t}^{c}(\ell)} \mid s(\ell), \mathcal{F}_{t}\right)$. Let $\mathcal{A}_{\bar{s}_{t}(\ell)}=\left\{\alpha_{1}(\ell), \ldots, \alpha_{r_{\alpha(\ell)}}(\ell)\right\}$ and $\mathcal{A}_{\bar{s}_{t}^{c}(\ell)}=\left\{\beta_{1}(\ell), \ldots, \beta_{r_{\beta(\ell)}}(\ell)\right\}$ be the duplication removed sets, corresponding the regime vectors $\bar{s}_{t}(\ell)$ and $\bar{s}_{t}^{c}(\ell)$, respectively. To eliminate unnecessary simulations, instead of the regimes in the set $\mathcal{A}_{\bar{s}_{t}(\ell)}$, one should consider regimes in intersection set of the sets $\mathcal{A}_{\bar{s}_{t}(\ell)}$ and $\mathcal{A}_{\bar{s}_{t}^{c}(\ell)}$. Let us assume that the intersection set and a difference set of the sets are given by $\mathcal{A}_{\bar{s}_{t}(\ell)} \cap \mathcal{A}_{\bar{s}_{t}^{c}(\ell)}=\left\{\gamma_{1}(\ell), \ldots, \gamma_{r_{\gamma(\ell)}}(\ell)\right\}$ and $\mathcal{A}_{\bar{s}_{t}^{c}(\ell)} \backslash \mathcal{A}_{\bar{s}_{t}(\ell)}=\left\{\delta_{1}(\ell), \ldots, \delta_{k}(\ell)\right\}$, respectively. Then, according to equations (10), (73) and (74), a simulation method that generates $\left(\pi_{\gamma_{k}(\ell)}(\ell), \Sigma_{\gamma_{k}(\ell)}(\ell)\right)$ for $\ell=1, \ldots, r_{\gamma(\ell)}$ as follows: for $k=1, \ldots, r_{\gamma(\ell)}$,

- generate $\Sigma_{\gamma_{k}(\ell)}(\ell)$ from $\mathcal{I W}\left(\nu_{0, \gamma_{k}(\ell)}+q_{t, \gamma_{k}(\ell)}, \bar{B}_{t, \gamma_{k}(\ell)}+V_{0, \gamma_{k}(\ell)}\right)$,
- generate $\pi_{\gamma_{k}(\ell)}(\ell)$ from $\mathcal{N}\left(A_{\gamma_{k}(\ell)} b_{\gamma_{k}(\ell)}, A_{\gamma_{k}(\ell)}\right)$.

On the other hand, according to equations (10) and (15) and marginal density functions of equations (50) and (51), a simulation method that generates $\left(\pi_{\delta_{k}(\ell)}(\ell), \Sigma_{\delta_{k}(\ell)}(\ell)\right)$ for $\ell=1, \ldots, r_{\delta(\ell)}$ as follows: if $r_{\delta(\ell)}>0$, then for $k=1, \ldots, r_{\delta(\ell)}$,

- generate $\Sigma_{\delta_{k}(\ell)}(\ell)$ from $\mathcal{I} \mathcal{W}\left(\nu_{0, \delta_{k}(\ell)}, V_{0, \delta_{k}(\ell)}\right)$,
- generate $\pi_{\delta_{k}(\ell)}(\ell)$ from $\mathcal{N}\left(\pi_{0, \delta_{k}(\ell)}, \Lambda_{0, \delta_{k}(\ell)} \otimes \Sigma_{\delta_{k}(\ell)}(\ell)\right)$.

Let $\hat{\beta}(\ell):=\left(\gamma_{1}(\ell), \ldots, \gamma_{r_{\gamma}(\ell)}(\ell), \delta_{1}(\ell), \ldots, \delta_{r_{\delta(\ell)}}(\ell)\right)^{\prime}$ be an $\left(r_{\beta(\ell)} \times 1\right)$ regime vector. The regime vector $\hat{\beta}(\ell)$ has same elements as the duplication removed regime vector $\beta(\ell)$, but positions of the elements are different for the two regime vectors. Collect the realizations for $k=1, \ldots, r_{\gamma(\ell)}, \Sigma_{\gamma_{k}(\ell)}(\ell)$ and $\pi_{\gamma_{k}(\ell)}(\ell)$ and for $k=1, \ldots, r_{\delta(\ell)}, \Sigma_{\delta_{k}(\ell)}(\ell)$ and $\pi_{\delta_{k}(\ell)}(\ell)$ into $\left(\left[n d r_{\beta(\ell)}\right] \times 1\right)$ vector $\pi_{\hat{\beta}(\ell)}(\ell)$ and $\left(n \times\left[n d r_{\beta(\ell)}\right]\right)$ $\operatorname{matrix} \Sigma_{\hat{\beta}(\ell)}(\ell)$, namely,

$$
\begin{equation*}
\pi_{\hat{\beta}(\ell)}(\ell):=\left(\pi_{\gamma_{1}(\ell)}(\ell)^{\prime}, \ldots, \pi_{\gamma_{r_{\gamma(\ell)}}(\ell)}(\ell)^{\prime}, \pi_{\delta_{1}(\ell)}(\ell)^{\prime}, \ldots, \pi_{\delta_{r_{\delta(\ell)}}(\ell)}(\ell)^{\prime}\right)^{\prime} \tag{125}
\end{equation*}
$$

and

$$
\begin{equation*}
\Sigma_{\hat{\beta}(\ell)}(\ell):=\left[\Sigma_{\gamma_{1}(\ell)}(\ell): \cdots: \Sigma_{\gamma_{r_{\gamma(\ell)}}(\ell)}(\ell), \Sigma_{\delta_{1}(\ell)}(\ell): \cdots: \Sigma_{\delta_{r_{\delta(\ell)}}(\ell)}(\ell)\right] \tag{126}
\end{equation*}
$$

Similar to equation (37), for $u=t+1, \ldots, T$, we denote a position of the regime $s_{u}(\ell)$ in the regime vector $\hat{\beta}(\ell)$ by $o_{\ell}(\ell)$. Let us define a matrix $D_{\hat{\beta}(\ell)}:=\left[j_{o_{t+1}(\ell)}: \cdots: j_{o_{T}(\ell)}\right]^{\prime}$, where $j_{o}(\ell)$ is an $\left(r_{\beta(\ell)} \times 1\right)$ unit vector, whose $o$-th element 1 and others 0 . Then, one revives the vector $\pi_{\bar{s}_{t}^{c}(\ell)}=\left(D_{\hat{\beta}(\ell)} \otimes I_{n d}\right) \pi_{\hat{\beta}(\ell)}$ and matrix

$$
\begin{equation*}
\Sigma_{\bar{s}_{t}^{c}(\ell)}=\operatorname{diag}\left\{\left(\left(D_{\hat{\beta}(\ell)} \otimes I_{n}\right) \Sigma_{\hat{\beta}(\ell)}\right)_{1}, \ldots,\left(\left(D_{\hat{\beta}(\ell)} \otimes I_{n}\right) \Sigma_{\hat{\beta}(\ell)}\right)_{T}\right\} . \tag{127}
\end{equation*}
$$

Fourth, we consider a simulation method that generate the regime vector $\bar{y}_{t}^{c}(\ell)$ from the density function $f\left(\bar{y}_{t}^{c} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{t}\right)$. Let us assume that

$$
\varphi_{s}=\left[\begin{array}{l}
\varphi_{1, \bar{s}_{t}}  \tag{128}\\
\varphi_{2, \bar{s}_{t}^{c}}
\end{array}\right] \quad \text { and } \quad \Psi_{s}=\left[\begin{array}{cc}
\Psi_{11, \bar{s}_{t}} & 0 \\
\Psi_{21, \bar{s}_{t}^{c}} & \Psi_{22, \bar{s}_{t}^{c}}
\end{array}\right]
$$

are partitions of the vector $\varphi_{s}$ and matrix $\Psi_{s}$, corresponding to random sub vectors $\bar{y}_{t}$ and $\bar{y}_{t}^{c}$ of the random vector $y$. Then, due to Battulga (2024b), a distribution of the random vector $\bar{y}_{t}^{c}$ is given by

$$
\begin{equation*}
\bar{y}_{t}^{c} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{t} \sim \mathcal{N}\left(\Psi_{22, \bar{s}_{t}^{c}}^{-1}\left(\varphi_{2, \bar{s}_{t}^{c}}-\Psi_{21, \bar{s}_{t} \bar{y}_{t}}\right), \Psi_{22, \bar{s}_{t}}^{-1} \Sigma_{\bar{s}_{t}^{c}}\left(\Psi_{22, \bar{s}_{t}^{c}}^{-1}\right),\right. \tag{129}
\end{equation*}
$$

where $\Sigma_{\bar{s}_{t}^{c}}=\operatorname{diag}\left\{\Sigma_{s_{t+1}}, \ldots, \Sigma_{s_{T}}\right\}$ is an $([n(T-t)] \times[n(T-t)])$ block diagonal matrix, corresponding to the regime vector $\bar{s}_{t}^{c}$. Thus, a simulation method that generate the vector of endogenous variables $\bar{y}_{t}^{c}(\ell)$ for given $\pi_{\bar{s}_{t}(\ell)}(\ell), \Sigma_{\bar{s}_{t}(\ell)}(\ell), s(\ell)$, and $\mathcal{F}_{t}$ as follows:

- generate $\bar{y}_{t}^{c}(\ell)$ from $\mathcal{N}\left(\Psi_{22, \bar{s}_{t}^{c}(\ell)}^{-1}\left(\varphi_{2, \bar{s}_{t}^{c}(\ell)}-\Psi_{21, \bar{s}_{t}^{c}(\ell)} \bar{y}_{t}\right), \Psi_{22, \bar{s}_{t}^{c}(\ell)}^{-1} \Sigma_{\bar{s}_{t}^{c}(\ell)}(\ell)\left(\Psi_{22, \bar{s}_{t}^{c}(\ell)}^{-1}\right)^{\prime}\right)$, where the matrix $\Psi_{22, \bar{s}_{t}^{c}(\ell)}$ and vector $\varphi_{s_{t}^{c}(\ell)}-\Psi_{21, \bar{s}_{t}^{c}(\ell)} \bar{y}_{t}$ are given by

$$
\Psi_{22, \bar{c}_{t}^{( }(\ell)}:=\left[\begin{array}{ccccccc}
I_{n} & 0 & \ldots & 0 & \ldots & 0 & 0  \tag{130}\\
-A_{1, s_{t+2}(\ell)} & I_{n} & \ldots & 0 & \ldots & 0 & 0 \\
\vdots & \vdots & \ldots & \vdots & \ldots & \vdots & \vdots \\
0 & 0 & \ldots & -A_{p-1, s_{T-1}(\ell)} & \ldots & I_{n} & 0 \\
0 & 0 & \ldots & -A_{p, s_{T}(\ell)} & \ldots & -A_{1, s_{T}(\ell)} & I_{n}
\end{array}\right]
$$

and

$$
\varphi_{2, \bar{s}_{t}^{c}(\ell)}-\Psi_{21, \bar{s}_{t}^{c}(\ell)} \bar{y}_{t}:=\left[\begin{array}{c}
A_{0, s_{t+1}(\ell)} \psi_{t+1}+A_{1, s_{t+1}(\ell)} y_{t}+\cdots+A_{p, s_{t+1}(\ell)} y_{t+1-p}  \tag{131}\\
A_{0, s_{t+2}(\ell)} \psi_{t+2}+A_{2, s_{t+2}(\ell)} y_{t}+\cdots+A_{p, s_{t+2}(\ell)} y_{t+2-p} \\
\vdots \\
A_{0, s_{T-1}(\ell)} \psi_{T-1} \\
A_{0, s_{T}(\ell)} \psi_{T}
\end{array}\right]
$$

and they are obtained from the vector $\pi_{\bar{s}_{t}^{c}(\ell)}(\ell)$. It should be noted that traditional methods that generate the vector $\bar{y}_{t}^{c}$ are based on an iterative method for $y_{t+1}, \ldots, y_{T}$ by generating $\xi_{t+1}, \ldots, \xi_{T}$, see Karlsson (2013). As a result, if $T-t$ is large, the simulation method reduces the computational burden that generates the random vector $\bar{y}_{t}^{c}$ as compared to the traditional algorithms.

### 3.2.2 Importance Sampling Method

Now, we consider the importance sampling method for the Bayesian MS-VAR process. We estimate a probability of a rare event, corresponding to the endogenous variables by the important sampling method. In the importance sampling method, one changes the real probability measure $\mathbb{P}$. The new probability measure $\tilde{\mathbb{P}}$ must be chosen that the rare event more frequently comes from than the real probability measure $\mathbb{P}$. Let $f\left(y, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)$ and $\tilde{f}\left(y, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)$ be joint density functions under the real probability measure $\mathbb{P}$ and new probability measure $\tilde{\mathbb{P}}$, respectively, for given initial information $\mathcal{F}_{0}$ and

$$
\begin{equation*}
L=L\left(y, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(y, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right) / \tilde{f}\left(y, \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right) \tag{132}
\end{equation*}
$$

be the likelihood ratio. Let us choose density functions that corresponds to the new probability measure $\tilde{\mathbb{P}}$ by

$$
\begin{equation*}
\tilde{f}\left(\bar{y}_{t}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right)=f\left(\bar{y}_{t}, \Sigma_{\hat{s}}, s, \mathrm{P} \mid \mathcal{F}_{0}\right) \tag{133}
\end{equation*}
$$

if $s_{u} \in \gamma$, then

$$
\begin{align*}
& \tilde{f}\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathcal{F}_{t}\right) \\
& / \frac{1}{(2 \pi)^{n d}\left|A_{s_{u}}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}\left(\pi_{s_{u}}-A_{s_{u}} b_{s_{u}}\right)^{\prime} A_{s_{u}}^{-1}\left(\pi_{s_{u}}-A_{s_{u}} b_{s_{u}}\right)\right\} \\
& \times \frac{1}{(2 \pi)^{n d}\left|A_{s_{u}}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}\left(\pi_{s_{u}}-A_{s_{u}} b_{s_{u}}-\theta_{s_{u}} A_{s_{u}}\left(\mathrm{Y}_{u} \otimes I_{n}\right) z_{u}\right)^{\prime}\right.  \tag{134}\\
& \left.\times A_{s_{u}}^{-1}\left(\pi_{s_{u}}-A_{s_{u}} b_{s_{u}}-\theta_{s_{u}} A_{s_{u}}\left(\mathrm{Y}_{u} \otimes I_{n}\right) z_{u}\right)\right\}
\end{align*}
$$

if $s_{u} \in \delta$, then

$$
\begin{align*}
& \tilde{f}\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathcal{F}_{t}\right) \\
& / \frac{1}{(2 \pi)^{n d}\left|\Lambda_{0, s_{u}}\right|^{n / 2}\left|\Sigma_{s_{u}}\right|^{d / 2}} \exp \left\{-\frac{1}{2}\left(\pi_{s_{u}}-\pi_{0, s_{u}}\right)^{\prime}\left(\Lambda_{0, s_{u}}^{-1} \otimes \Sigma_{s_{u}}^{-1}\right)\left(\pi_{s_{u}}-\pi_{0, s_{u}}\right)\right\} \\
& \times \frac{1}{(2 \pi)^{n d}\left|\Lambda_{0, s_{u}}\right|^{n / 2}\left|\Sigma_{s_{u}}\right|^{d / 2}} \exp \left\{-\frac{1}{2}\left(\pi_{s_{u}}-\pi_{0, s_{u}}-\theta_{s_{u}}\left(\Lambda_{0, s_{u}} \mathrm{Y}_{u} \otimes \Sigma_{s_{u}}\right) z_{u}\right)^{\prime}\right.  \tag{135}\\
& \left.\times\left(\Lambda_{0, s_{u}}^{-1} \otimes \Sigma_{s_{u}}^{-1}\right)\left(\pi_{s_{u}}-\pi_{0, s_{u}}-\theta_{s_{u}}\left(\Lambda_{0, s_{u}} \mathrm{Y}_{u} \otimes \Sigma_{s_{u}}\right) z_{u}\right)\right\},
\end{align*}
$$

and

$$
\begin{align*}
& \tilde{f}\left(\bar{y}_{t}^{c} \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\bar{y}_{t}^{c} \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)=f\left(\bar{y}_{t}^{c} \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathcal{F}_{t}\right) \\
& / \frac{1}{(2 \pi)^{n}\left|\Sigma_{s_{u}}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}\left(y_{u}-\Pi_{s_{u}} \mathrm{Y}_{u}\right)^{\prime} \Sigma_{s_{u}}^{-1}\left(y_{u}-\Pi_{s_{u}} \mathrm{Y}_{u}\right)\right\}  \tag{136}\\
& \times \frac{1}{(2 \pi)^{n}\left|\Sigma_{s_{u}}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}\left(y_{u}-\Pi_{s_{u}} \mathrm{Y}_{u}-\theta_{s_{u}} \Sigma_{s_{u}} z_{u}\right)^{\prime} \Sigma_{s_{u}}^{-1}\left(y_{u}-\Pi_{s_{u}} \mathrm{Y}_{u}-\theta_{s_{u}} \Sigma_{s_{u}} z_{u}\right)\right\}
\end{align*}
$$

for $u=t+1, \ldots, T$, where $\theta_{s_{u}}$ is a positive constant, depending on the random coefficient vector $\pi_{s_{u}}$, random covariance matrix $\Sigma_{s_{t}}$, and regime $s_{u}$ and $z_{u}$ is an $(n \times 1)$ vector, whose elements are known. Note that if $\theta_{s_{u}}=0$, then the new probability measure $\tilde{\mathbb{P}}$ equals the real probability measure $\mathbb{P}$. If we compare the density functions $\tilde{f}\left(\bar{y}_{t}^{c} \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)$ and $f\left(\bar{y}_{t}^{c} \mid \pi_{\hat{s}}, \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)$, one can conclude that conditional distribution of $y_{u}$ changes from $y_{u} \mid \pi_{s_{u}}, s_{u}, \mathcal{F}_{u-1} \sim \mathcal{N}\left(\Pi_{s_{u}} \mathrm{Y}_{u}, \Sigma_{s_{u}}\right)$ to $y_{u} \mid \pi_{s_{u}}, s_{u}, \mathcal{F}_{u-1} \sim \mathcal{N}\left(\Pi_{s_{u}} \mathrm{Y}_{u}+\theta_{s_{u}} \Sigma_{s_{u}} z_{u}, \Sigma_{s_{u}}\right)$ and for each $v=t+1, \ldots, T(v \neq u)$, the conditional distribution of other sub random vector $y_{v}$ of the random vector $\bar{y}_{t}^{c}$ does not change. The same explanation holds for the density functions $\tilde{f}\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)$ and $f\left(\pi_{\hat{s}} \mid \Sigma_{\hat{s}}, s, \mathrm{P}, \mathcal{F}_{t}\right)$. Then, it can be shown that for $u=t+1, \ldots, T$, the likelihood ratio is given by

$$
\begin{equation*}
L_{u}=\exp \left\{-\theta_{s_{u}} X_{u}+\psi\left(\theta_{s_{u}}\right)\right\} \tag{137}
\end{equation*}
$$

where the random variable $X_{u}$ is given by $X_{u}:=z_{u}^{\prime} y_{u}$ and the quadratic function $\psi\left(\theta_{s_{u}}\right)$ for $\theta_{s_{u}}$ is given by

$$
\psi\left(\theta_{s_{u}}\right):=\left\{\begin{array}{lll}
\theta_{u} z_{u}^{\prime} C_{u, s_{u}} \mathrm{Y}_{u}+\frac{1}{2} \theta_{u}^{2}\left(1+\mathrm{Y}_{u}^{\prime} \Lambda_{0, s_{u} \mid u}^{-1} \mathrm{Y}_{u}\right) z_{u}^{\prime} \Sigma_{s_{u}} z_{u} & \text { if } & s_{u} \in \gamma  \tag{138}\\
\theta_{u} z_{u}^{\prime} \Pi_{s_{u}} \mathrm{Y}_{u}+\frac{1}{2} \theta_{u}^{2}\left(1+\mathrm{Y}_{u}^{\prime} \Lambda_{0, s_{u}} \mathrm{Y}_{u}\right) z_{u}^{\prime} \Sigma_{s_{u}} z_{u} & \text { if } & s_{u} \in \delta
\end{array}\right.
$$

For each $u=t+1, \ldots, T$, by choosing $z_{u}$ by the unit vector, one can extract elements of the vector of endogenous variables $y_{u}$. If the process $y_{t}$ consists of returns of financial assets, then by choosing $z_{u}$ by weight vector, one obtains portfolio return.

Now we consider a conditional probability $\mathbb{P}\left(X_{u}>x_{u} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{u-1}\right)$ for large $x_{u} \in \mathbb{R}$ and $u=t+1, \ldots, T$. Since $\theta_{s_{u}}$ is the positive constant, for the conditional probability, by equation (137), the following inequality holds

$$
\begin{equation*}
\mathbb{P}\left(X_{u}>x_{u} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{u-1}\right)=\tilde{\mathbb{E}}\left[1_{\left\{X_{u}>x_{u}\right\}} L_{u} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{u-1}\right] \leq \exp \left\{-\theta_{s_{u}} x_{u}+\psi\left(\theta_{s_{u}}\right)\right\} \tag{139}
\end{equation*}
$$

for $u=t+1, \ldots, T$, where for a generic event $A \in \mathcal{H}_{T}, 1_{A}$ is the indicator function of the event $A$, see Glasserman et al. (2000). Also, for the second order moment, it holds

$$
\begin{equation*}
m_{2}\left(x_{u}, \theta_{s_{u}}\right):=\tilde{\mathbb{E}}\left[1_{\left\{X_{u}>x_{u}\right\}} L_{u}^{2} \mid \pi_{\beta}, \Sigma_{\beta}, s, \mathcal{F}_{u-1}\right] \leq \exp \left\{-2 \theta_{s_{u}} x_{u}+2 \psi\left(\theta_{s_{u}}\right)\right\} \tag{140}
\end{equation*}
$$

To reduce a variance of the importance sampling, we need to keep the right hand side of the above inequality as low as possible. To minimize the right-hand side of the above equation, we minimize the exponent using the parameter $\theta_{s_{t}}$. The minimizer of the right-hand side of the above equation is given by

$$
\theta_{s_{u}}\left(x_{u}\right):=\left\{\begin{array}{lll}
\frac{x_{u}-z_{u}^{\prime} C_{u, s_{u}} \mathrm{Y}_{u}}{\left(1+\mathrm{Y}_{u}^{\prime} \Lambda_{0, s_{u} \mid u}^{-1} \mathrm{Y}_{u}\right) z_{u}^{\prime} \Sigma_{s_{u}} z_{u}} & \text { if } & s_{u} \in \gamma  \tag{141}\\
\frac{x_{u}-z_{u}^{\prime} \Pi_{s_{u}} \mathrm{Y}_{u}}{\left(1+\mathrm{Y}_{u}^{\prime} \Lambda_{0, s_{u}} \mathrm{Y}_{u}\right) z_{u}^{\prime} \Sigma_{s_{u}} z_{u}} & \text { if } & s_{u} \in \delta
\end{array}\right.
$$

for $u=t+1, \ldots, T$. Therefore, an importance sampling method that estimates the conditional probabilities $\mathbb{P}\left(X_{u}>x_{u} \mid \mathcal{F}_{t}\right)$ for $u=t+1, \ldots, T$ as follows: for $\ell=1, \ldots, \mathcal{L}$,

- generate $\left(\bar{y}_{t}^{c}(\ell), \pi_{\bar{s}_{t}^{c}(\ell)}(\ell), \Sigma_{\bar{s}_{t}^{c}(\ell)}(\ell), \bar{s}_{t}^{c}(\ell)\right)$ using the general simulation method,
- for $u=t+1, \ldots, T$,
- calculate $\theta_{s_{u}(\ell)}^{*}\left(x_{u}, \ell\right)$ using equation (141),
- if $s_{u}(\ell) \in \gamma(\ell)$, generate $\pi_{s_{u}(\ell)}^{*}(\ell)$ from

$$
\begin{equation*}
\mathcal{N}\left(A_{s_{u}(\ell)}(\ell) b_{s_{u}(\ell)}(\ell)+\theta_{s_{u}(\ell)}^{*}\left(x_{u}, \ell\right)\left(\mathrm{Y}_{u}(\ell) \otimes I_{n}\right) z_{u}, A_{s_{u}}(\ell)\right) \tag{142}
\end{equation*}
$$

- if $s_{u}(\ell) \in \delta(\ell)$, generate $\pi_{s_{u}(\ell)}^{*}(\ell)$ from

$$
\begin{equation*}
\mathcal{N}\left(\pi_{0, s_{u}(\ell)}+\theta_{s_{u}(\ell)}^{*}\left(x_{u}, \ell\right)\left(\Lambda_{0, s_{u}(\ell)} \mathrm{Y}_{u}(\ell) \otimes \Sigma_{s_{u}(\ell)}(\ell)\right) z_{u}, \Lambda_{0, s_{u}(\ell)} \otimes \Sigma_{s_{u}(\ell)}(\ell)\right) \tag{143}
\end{equation*}
$$

- generate $y_{u}^{*}(\ell)$ from

$$
\begin{equation*}
\mathcal{N}\left(\Pi_{s_{u}}^{*} Y_{u}(\ell)+\theta_{s_{u}(\ell)}^{*}\left(x_{u}, \ell\right) \Sigma_{s_{u}(\ell)} z_{u}, \Sigma_{s_{u}(\ell)}(\ell)\right) \tag{144}
\end{equation*}
$$

where $\pi_{s_{u}(\ell)}^{*}(\ell)=\operatorname{vec}\left(\Pi_{s_{u}(\ell)}^{*}(\ell)\right)$,

- calculate $L_{u}^{*}(\ell)$ using equation (137), where $X_{u}^{*}(\ell)=z_{u}^{\prime} y_{u}^{*}(\ell)$,
- and for $u=t+1, \ldots, T$, estimate the probabilities $\mathbb{P}\left(X_{u}>x_{u} \mid \mathcal{F}_{t}\right)$ by

$$
\begin{equation*}
\hat{\mathbb{P}}\left(X_{u}>x_{u} \mid \mathcal{F}_{t}\right)=\frac{1}{\mathcal{L}} \sum_{\ell=1}^{\mathcal{L}} 1_{\left\{X_{u}^{*}(\ell)>x_{u}\right\}} L_{u}^{*}(\ell) \tag{145}
\end{equation*}
$$

where calculations of the matrix $A_{s_{u}(\ell)}(\ell)$ and vectors $b_{s_{u}(\ell)}(\ell)$ and $Y_{u}(\ell)$ are based on the vectors $\bar{y}_{t}$ and $\bar{y}_{t}^{c}(\ell)$.

## 4 Numerical Results

Now we consider numerical results. For means of illustration, we have chosen three companies, listed in the S\&P 500 index from different sectors. In order to increase the number of price and dividend observation points, we take quarterly data instead of yearly data. Our data covers a period from Q1, 1985 to Q4, 2023. That leads to $t=156$ observations for Johnson \& Johnson (J\&J), PepsiCo, and Walmart. All quarterly price and dividend data have been collected from Yahoo Finance.

### 4.1 Dividend Discount Model

Before we move to the numerical results, we provide a brief review of the dividend discount model (DDM), which is useful for the numerical results. Let us assume that there are $m$ companies, and the companies will not default in the future. For DDM with default risk, we refer to Battulga et al. (2022). As mentioned before, the basic idea of all DDMs is that the market price of a stock equals the sum of the stock's next period price and dividend discounted at the required rate of return. Therefore, for successive prices of $i$-th company, the following relation holds

$$
\begin{equation*}
P_{i, t}=\left(1+k_{i, t}\right) P_{i, t-1}-d_{i, t}, \quad i=1, \ldots, m, t=1,2, \ldots, \tag{146}
\end{equation*}
$$

where $k_{i, t}$ is the required rate of return on stock, $P_{i, t}$ is the stock price, and $d_{i, t}$ is the dividend, respectively, at time $t$ of $i$-th company. In vector form, the above equation is written by

$$
\begin{equation*}
P_{t}=\left(i_{m}+k_{t}\right) \odot P_{t-1}-d_{t}, \quad t=1,2, \ldots, \tag{147}
\end{equation*}
$$

where $k_{s_{t}}:=\left(k_{1, t}, \ldots, k_{m, t}\right)^{\prime}$ is an $(m \times 1)$ vector of the required rate of returns on stocks at time $t$, $P_{t}:=\left(P_{1, t}, \ldots, P_{m, t}\right)^{\prime}$ is an $(m \times 1)$ price vector at time $t$, and $d_{t}:=\left(d_{1, t}, \ldots, d_{m, t}\right)^{\prime}$ is an $(m \times 1)$ dividend vector at time $t$ of the companies. On the other hand, we assume that a dividend of $i$-th company is proportional to stock price of the company. To price dividend paying option, Merton (1974) used the assumption. Consequently, dividends of the companies are modeled by

$$
\begin{equation*}
d_{t}=\alpha_{t} \odot P_{t-1}, \quad t=1,2, \ldots, \tag{148}
\end{equation*}
$$

where $\alpha_{t}=\left(\alpha_{1, t}, \ldots, \alpha_{m, t}\right)^{\prime}$ is an $(m \times 1)$ vector of dividend-to-price ratios at time $t$ of the companies. Consequently, by equation (147) and (148), the price vector at time $t$ is written by

$$
\begin{equation*}
P_{t}=\left(i_{m}+k_{t}-\alpha_{t}\right) P_{t-1} . \tag{149}
\end{equation*}
$$

To the vector of dividend-to-price ratios take positive values, instead of equation (148), we work a vector of $\log$ dividend-to-price ratios, which is given by the following equation

$$
\begin{equation*}
\tilde{d}_{t}=\tilde{\alpha}_{t}-\tilde{P}_{t-1}, \tag{150}
\end{equation*}
$$

where $\tilde{d}_{t}:=\ln \left(d_{t}\right)$ is an $(m \times 1) \log$ dividend vector at time $t, \tilde{P}_{t-1}:=\ln \left(P_{t-1}\right)$ is an $(m \times 1) \log$ price vector at time $t-1, \tilde{\alpha}_{t}$ is the $(m \times 1)$ vector of $\log$ dividend-to-price ratios at time $t$. As a result, equation (149) becomes

$$
\begin{equation*}
P_{t}=\left(i_{m}+k_{t}-\exp \left\{\tilde{\alpha}_{t}\right\}\right) P_{t-1} . \tag{151}
\end{equation*}
$$

It follows from equations (147) and (150) that for $t=1,2, \ldots$, vectors of the required rate of returns and $\log$ dividend-to-price ratios of the companies are obtained by

$$
\begin{equation*}
k_{t}=\left(P_{t}+d_{t}\right) \oslash P_{t-1}-i_{m} \tag{152}
\end{equation*}
$$

and

$$
\begin{equation*}
\tilde{\alpha}_{t}=\ln \left(d_{t} \oslash P_{t-1}\right), \tag{153}
\end{equation*}
$$

respectively. By repeating equation (151), for $t=0,1, \ldots$ and $r=0,1, \ldots$, we obtain the price vectors at time $t+r$ of the companies

$$
\begin{equation*}
P_{t+r}=\prod_{j=1}^{r}\left(i_{m}+k_{t+j}-\exp \left\{\tilde{\alpha}_{t+j}\right\}\right) \odot P_{t} \tag{154}
\end{equation*}
$$

where for $q=1,2, \ldots$ and generic $(m \times 1)$ vectors $o_{1}, \ldots, o_{q}, \prod_{j=1}^{q} o_{j}=o_{1} \odot \cdots \odot o_{q}$ is an element-wise product of the vectors $o_{1}, \ldots, o_{q}$ and with convention $\prod_{j=q}^{q-1} o_{j}=i_{m}$.

### 4.2 Maximum Likelihood Estimation

It is not difficult to show that the required rate of returns of the selected companies are $\mathrm{AR}(0)$ processes, see Figure 1. Thus, for each firm, we model the required rate of returns by the following AR(0) process

$$
\begin{equation*}
k_{i, t}=c_{i, s_{t}}+\xi_{i, t}, \quad i=1,2,3, \tag{155}
\end{equation*}
$$

where the regime-switching process $s_{t}$ takes one of the values $\{1,2,3\}$ and $c_{i, s_{t}}$ is a constant, corresponding to $i-$ th company and the regime $s_{t}$. We suppose that a variance of the residual process $\xi_{i, t}$ in the regime $s_{t}$ of the $i$-th company equals $\sigma_{i, s_{t}}^{2}$.

We present maximum likelihood estimations of the parameters for the selected companies in Table 1. Maximum likelihood estimation method can be found in Hamilton (1990, 1994), see also Battulga (2022, 2023a). The $2-9$ th rows of Table 1 correspond to that the required rate of returns of the companies are modeled by the regime-switching process with three regimes and the $10-13$ th rows of the same Table correspond to that the required rate of returns of the companies take constant values (the regime-switching process takes one regime).

Table 1: Maximum Likelihood Estimations of Parameters of Selected Companies

| Row | Parameters | Johnson \& Johnson |  |  | Pepsi |  |  | Walmart |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | $c_{i, j}$ | 15.64\% | 4.26\% | -6.41\% | 6.29\% | 2.73\% | -13.90\% | 15.09\% | 1.74\% | -5.60\% |
| 3 | $\sigma_{i, j}$ | 0.047 | 0.052 | 0.054 | 0.098 | 0.055 | 0.022 | 0.096 | 0.066 | 0.083 |
| 4 | $\hat{P}_{i}$ | 0.222 | 0.384 | 0.395 | 0.908 | 0.092 | 0.000 | 0.460 | 0.000 | 0.540 |
| 5 |  | 0.099 | 0.645 | 0.256 | 0.000 | 0.933 | 0.067 | 0.000 | 0.932 | 0.068 |
| 6 |  | 0.232 | 0.768 | 0.000 | 0.890 | 0.000 | 0.110 | 0.683 | 0.164 | 0.153 |
| 7 | $\tau_{i, j}$ | 1.285 | 2.814 | 1.000 | 10.842 | 14.865 | 1.124 | 1.851 | 14.789 | 1.181 |
| 8 | $\pi_{i, j}$ | 0.146 | 0.634 | 0.220 | 0.404 | 0.554 | 0.042 | 0.269 | 0.517 | 0.213 |
| 9 | $k_{i, \infty}$ | 3.58\% |  |  | 3.47\% |  |  | 3.77\% |  |  |
| 10 | $c_{i}$ | 3.58\% |  |  | 3.54\% |  |  | 4.02\% |  |  |
| 11 | $k_{i, L}$ | 2.24\% |  |  | 2.18\% |  |  | 2.25\% |  |  |
| 12 | $k_{i, U}$ | 4.92\% |  |  | 4.90\% |  |  | 5.80\% |  |  |
| 13 | $\sigma$ | 0.084 |  |  | 0.086 |  |  | 0.112 |  |  |

In order to obtain estimations of the parameters, which correspond to the $2-9$ th rows of Table 1 we assume that the regime-switching process $s_{t}$ follows a Markov chain with three regimes, namely, up regime (regime 1), normal regime (regime 2), and down regime (regime 3). For the normal regime, most of the time of the regime-switching process $s_{t}$ lasts in regime 2 . Since explanations are comparable for the other companies, we give explanations only for J\&J. In the 2nd row of Table 1, for each company $i=1,2,3$, we provide estimations of the parameters $c_{i, 1}, c_{i, 2}, c_{i, 3}$. For $\mathrm{J} \& \mathrm{~J}$, in regimes 1,2 , and 3 , estimations of the required rate of return are $15.64 \%, 4.26 \%$, and $-6.41 \%$, respectively. For example, in the normal regime, the required rate of return of J\&J could be $4.26 \%$ on average.

In the 3rd row of Table 1, we present parameter estimations of standard deviations of the error random variables $\xi_{i, t}$ for the selected companies. For J\&J, the parameter estimations of the standard
deviations equal 0.047 (regime 1 ), 0.052 (regime 2 ), and 0.054 (regime 3 ). The 13 th row of Table 1 corresponds to the parameter estimations of standard deviations, in which the required rate of returns of the companies are modeled by regime-switching process with one regime. For J\&J, the parameter estimation equals 0.084 . As we compare the 9 th row and 13 th row of the Table, we can see that the estimations that correspond to the regime-switching process with three regimes are significantly lower than the ones that correspond to the regime-switching process with one regime, except the up regime of PepsiCo.

The $4-6$ th rows of Table 1 correspond to the transition probability matrix $\hat{P}$. For the selected companies, their transition probability matrices $\hat{P}_{s}$ are ergodic, where ergodic means that one of the eigenvalues of $\hat{P}$ is unity and that all other eigenvalues of $\hat{P}$ are inside the unit circle, see Hamilton (1994). From the 4 th row of Table 1, one can deduce that if the required rate of return of J\&J is in the up regime, then in the next period, it will switch to the up regime with a probability of 0.22 , the normal regime with a probability of 0.384 , or the down regime with a probability of 0.395 . If the required rate of return of $J \& J$ in the normal regime, corresponding to row 5 of the Table, then in the next period, it will switch to the up regime with a probability of 0.099 , the normal regime with a probability of 0.645 , or the down regime with a probability of 0.256 . Finally, if the required rate of return of $J \& J$ is in the down regime, then in the next period, it will switch to the up regime with a probability of 0.232 or the normal regime with a probability of 0.768 because of the down regime's zero probability, see 6 th row of the same Table.

We provide the average persistence times of the regimes in the 7 th row of Table 1. The average persistence time of the regime $s_{t}$ is defined by $\tau_{s_{t}}:=1 /\left(1-p_{s_{t} s_{t}}\right)$ for $s_{t} \in\{1,2,3\}$. From Table 1, one can conclude that up, normal, and down regimes of J\&J's required rate of return will persist on average for $1.285,2.814$, and 1.000 quarters, respectively.

In the 8 th row of Table 1, we give ergodic probabilities $\pi$ of the selected companies. Ergodic probability vector $\pi$ of an ergodic Markov chain is obtained from an equation $\hat{\mathrm{P}} \pi=\pi$. The ergodic probability vector represents long-run probabilities, which do not depend on the initial probability vector $z_{1 \mid 0}$. After sufficiently long periods, the required rate of return of $J \& J$ will be in the up regime with a probability of 0.146 , the normal regime with a probability of 0.634 , or the down regime with a probability of 0.220 , which are irrelevant to initial regimes.

The 9 th row of Table 1 is devoted to long-run expectations of the required rate of returns of the selected companies. The long-run expectation of the required rate of return is defined by $k_{\infty}:=$ $\lim _{t \rightarrow \infty} \mathbb{E}\left(k\left(s_{t}\right)\right)$. For $J \& J$, it equals $3.58 \%$. So that, after long periods, the average required rate of return of J\&J converges to $3.58 \%$.

Finally, for the one regime case, parameter estimations of the required rate of returns at time Q4, 2023 of the firms are presented in row 10 of the Table, while the corresponding $95 \%$ confidence intervals are included in rows 11 and 12 below. Here we use formulas in Battulga (2023a) to calculate the parameter estimation and confidence bands. Note that since the required rate of return estimation expresses the average quarterly return of the companies, we can convert them yearly using a formula $(1+k)^{4}-1$. The Table further illustrates average returns ( $3.58 \%$ for $J \& J$ ) and return variability, as the return is supposed to lie within the $(2.24 \%, 4.92 \%)$ interval with a $95 \%$ probability.

For the selected firms, plotting the smoothed probabilistic inferences with a return series will be interesting. For each period $u=1, \ldots, t$, and each firm, the smoothed inferences are calculated by equation (123), and the return series are calculated by equation (152). In Figure 1, we plotted the resulting series as a function of period $u$. In Figure 1, the left axis corresponds to the return series, while the right axis corresponds to the smoothed inference series for each company. From the Figure and the 9 th and 13 th rows of Table 1, we can deduce that the regime-switching processes with three regimes are more suited to explain the required rate of return series as compared to the regime-switching processes with one regime.

Figure 1: Returns VS Regime Probabilities of Selected Companies


### 4.3 Bayesian Estimation

Now, we aim to obtain future theoretical prices of the selected companies using equation (154). To get the future prices of the firms, we assume that the vectors of the required rate of returns and the log dividend-to-price ratios of the firms are placed on the Bayesian MS-VAR process $y_{t}$. We also assume that the process $y_{t}$ is modeled by the Bayesian MS-VAR process of order 4, which is given by the following equation

$$
\begin{equation*}
y_{t}=a_{0, s_{t}}+A_{1, s_{t}} y_{t-1}+\cdots+A_{4, s_{t}} y_{t-4}+\xi_{t}, t=1, \ldots, T, \tag{156}
\end{equation*}
$$

where $y_{t}=\left(k_{t}^{\prime}, \tilde{\alpha}_{t}^{\prime}\right)^{\prime}$ is a $(6 \times 1)$ vector of endogenous variables with $k_{t}:=\left(k_{1, t}, k_{2, t}, k_{3, t}\right)^{\prime}$ and $\tilde{\alpha}_{t}:=$ $\left(\tilde{\alpha}_{1, t}, \tilde{\alpha}_{2, t}, \tilde{\alpha}_{3, t}\right)^{\prime}, \xi_{t}=\left(\xi_{1, t}, \ldots, \xi_{6, t}\right)^{\prime}$ is a $(6 \times 1)$ residual process, $a_{0, s_{t}}$ is a $(6 \times 1)$ random coefficient vector at regime $s_{t}$, and for $i=1, \ldots, 4, A_{i, s_{t}}$ are $(6 \times 6)$ random coefficient matrices at regime $s_{t}$.

For the vector of $\log$ dividend-to-price ratios $\tilde{\alpha}_{t}$ of the selected companies, it can be shown that the ratios follow the unit root process. On the other hand, the vector of the required rate of returns $k_{t}$ of the selected companies is a stationary process, see Figure 1. Consequently, conditional expectations of diagonal elements of the random matrix $A_{1, s_{t}}$ are chosen by $\phi:=(0,0,0,1,1,1)^{\prime}$.

We suppose that the scale matrix $V_{0, s_{t}}$ is a diagonal matrix and its diagonal elements, corresponding to the process of $\log$ dividend-to-price ratios are estimated by sample variances of the processes, modeled by univariate $\operatorname{AR(4).~For~other~diagonal~elements,~corresponding~to~the~required~}$
rate of returns, we use the maximum likelihood estimations of parameters, which are given in Table 1. Therefore, for each regime $s_{t}=1,2,3$, we choose the scale matrix $V_{0, s_{t}}$ by

$$
\begin{align*}
V_{0,1} & :=\operatorname{diag}\left\{0.047^{2}, 0.098^{2}, 0.096^{2}, 0.092^{2}, 0.094^{2}, 0.133^{2}\right\} \\
V_{0,2} & :=\operatorname{diag}\left\{0.052^{2}, 0.055^{2}, 0.066^{2}, 0.092^{2}, 0.094^{2}, 0.133^{2}\right\}  \tag{157}\\
V_{0,3} & :=\operatorname{diag}\left\{0.054^{2}, 0.022^{2}, 0.083^{2}, 0.092^{2}, 0.094^{2}, 0.133^{2}\right\} .
\end{align*}
$$

Also, based on the same Table, for each regime, we choose conditional expectation of the random vector $a_{0, s_{t}}$ by $c_{1}:=\mathbb{E}\left[a_{0, s_{t}} \mid \Sigma_{s_{t}}, s_{t}=1, \mathcal{F}_{0}\right]=(0.15,0.06,0.15,0,0,0)^{\prime}, c_{2}:=\mathbb{E}\left[a_{0, s_{t}} \mid \Sigma_{s_{t}}, s_{t}=2, \mathcal{F}_{0}\right]=$ $(0.04,0.03,0.02,0,0,0)^{\prime}$, and $c_{3}:=\mathbb{E}\left[a_{0, s_{t}} \mid \Sigma_{s_{t}}, s_{t}=3, \mathcal{F}_{0}\right]=(-0.07,-0.14,-0.05,0,0,0)^{\prime}$. For the other hyperparameters, we choose $\varepsilon_{j}=\lambda_{1, j}=20$ and $\lambda_{2, i}=\tau_{i, j}=1$ for each regime $j=1,2,3$ and each endogenous variable $i=1, \ldots, 6$. As a result, the matrices of the dummy variables $\hat{y}_{s_{t}}^{\circ}$ and $\hat{\mathrm{Y}}_{s_{t}}^{\circ}$, which are given in equations (113) and (114) are represented by

$$
\begin{equation*}
\hat{y}_{s_{t}}^{\circ}:=20\left[c_{s_{t}}: \operatorname{diag}\{0,0,0,1,1,1\}: 0_{[6 \times 20]}\right] \tag{158}
\end{equation*}
$$

and

$$
\hat{\mathrm{Y}}_{s_{t}}^{\circ}:=20\left[\begin{array}{cc}
1 & 0_{[1 \times 24]}  \tag{159}\\
0_{[24 \times 1]} & (\operatorname{diag}\{1,2,3,4\} \otimes \operatorname{diag}\{1,1,1,1,1,1\})
\end{array}\right]
$$

where dimensions of the matrices of the dummy variables $\hat{y}_{s_{t}}^{\circ}$ and $\hat{Y}_{s_{t}}^{\circ}$ are $(6 \times 25)$ and $(25 \times 25)$, respectively.

In order to obtain future eight quarters' theoretical prices and their $95 \%$ confidence bands of the selected companies, we use equation (154) and make a simulation of $\mathcal{L}=10,000$. The following Table presents the results of the theoretical prices and confidence bands.

Table 2: Future Theoretical Prices and $95 \%$ Confidence Bands of Selected Companies

| Companies |  |  | $P_{t}$ | $P_{t+1}$ | $P_{t+2}$ | $P_{t+3}$ | $P_{t+4}$ | $P_{t+5}$ | $P_{t+6}$ | $P_{t+7}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |$P_{t+8}$.

For Table 2, T/Price, L/Bound, and U/Bound mean theoretical price, lower bound, and upper bound, respectively. The column $P_{t}$ represents real prices at time Q4, 2023 of the selected companies. For each $u=1, \ldots, 8$, the column $P_{t+u}$ expresses future prices at time $t+u$ (after $u$ quarters from $\mathrm{Q} 4,2023$ ) of the companies. In particular, the column $P_{t+4}$ represents future prices in $\mathrm{Q} 4,2024$. The same column further explains that the theoretical price in Q4, 2024 of J\&J equals 174.29 , and the price in Q4, 2024 of the firm will lie within the (131.30,225.62) interval with a $95 \%$ probability. The same explanations hold for other columns and other companies. From the Table, one can deduce that histograms of the future prices are right skewed, and the skewness increases as time increases.

## 5 Conclusion

In this paper, for the general Bayesian MS-VAR process, we obtain some useful density functions for Monte-Carlo simulations. The density functions tell us that conditional on the regime vectors
and initial information, the vector of endogenous variables is independent of model's some random components. Thus, one only needs the prior distributions to calculate the density functions, and the results have yet to be explored before.

In a particular case of the general Bayesian MS-VAR process, we also get closed-form density functions of the random components of the model. In particular, we find that joint distributions of future values of the random coefficient matrix are matrix variate student distribution, see equation (48). Hence, one can analyze impulse response by directly generating the coefficient matrix from the density. Also, we provide a new density function, which has yet to be introduced before of future values of the endogenous variables; see equations (44) and (77). Thus, future studies may concentrate on marginal density functions and direct simulation methods for the density function. Further, we obtain a characteristic function of the random coefficient matrix, which can be used to calculate the forecast of the endogenous variables.

In the paper, we developed Monte-Carlo simulation algorithms. The simulation method's novelty is that it removes the regime vector duplication. As a result, our proposed Monte-Carlo simulation method departs from the previous simulation methods with regime switching. We also provide importance sampling method to estimate probability of a rare event, corresponding to the future endogenous variables. Since the method can be used to calculate quantiles, in this case, the quantiles of the future endogenous variables become more reliable than navy simulation methods.

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