

HIGHER HÖLDER REGULARITY FOR A SUBQUADRATIC NONLOCAL PARABOLIC EQUATION

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ABSTRACT. In this paper, we are concerned with the Hölder regularity for solutions of the nonlocal evolutionary equation

$$\partial_t u + (-\Delta_p)^s u = 0.$$

Here, $(-\Delta_p)^s$ is the fractional p -Laplacian, $0 < s < 1$ and $1 < p < 2$. We establish Hölder regularity with explicit Hölder exponents. We also include the inhomogeneous equation with a bounded inhomogeneity. In some cases, the obtained Hölder exponents are almost sharp. Our results complement the previous results for the superquadratic case when $p \geq 2$.

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1. INTRODUCTION AND MAIN RESULT

In this article, we establish higher Hölder continuity of weak solutions for the subquadratic nonlocal parabolic equation

$$\partial_t u + (-\Delta_p)^s u = 0. \tag{1.1}$$

Here $1 < p < 2$ and $0 < s < 1$. The operator $(-\Delta_p)^s$ is the fractional p -Laplace operator defined by

$$(-\Delta_p)^s u(x, t) = 2 \text{P.V.} \int_{\mathbb{R}^N} \frac{|u(x, t) - u(y, t)|^{p-2} (u(x, t) - u(y, t))}{|x - y|^{N+ps}} dy,$$

where P.V. denotes the principal value.

The main contribution of this paper is to prove that solutions are almost Θ -regular in space and almost Γ -regular in time, where

$$\Theta(s, p) := \begin{cases} \frac{sp}{p-1}, & \text{if } s < \frac{p-1}{p}, \\ 1, & \text{if } s \geq \frac{p-1}{p}, \end{cases} \quad \text{and} \quad \Gamma(s, p) := \begin{cases} 1, & \text{if } s < \frac{p-1}{p}, \\ \frac{1}{sp - (p-2)}, & \text{if } s \geq \frac{p-1}{p}. \end{cases}$$

We also allow a bounded right hand side in the equation, in which case these exponents are almost sharp. See Section 1.2.

These results are complementing the already existing Hölder estimates in [4], valid for $p \geq 2$.

1.1. Main result. Below we state our main theorem. For notation and relevant definitions, see Section 2.

Theorem 1.1. *Let $\Omega \subset \mathbb{R}^N$ be a bounded and open set, $I = (t_0, t_1]$, $1 < p < 2$ and $0 < s < 1$. Suppose $(x_0, T_0) \in \Omega \times I$ is such that*

$$Q_{2R, (2R)^{sp}}(x_0, T_0) \Subset \Omega \times I.$$

Assume that $u \in L^p(J; W_{\text{loc}}^{s,p}(\Omega)) \cap L^{p-1}(J; L_{sp}^{p-1}(\mathbb{R}^N)) \cap C(J; L_{\text{loc}}^2(\Omega))$ is a local weak solution of

$$\partial_t u + (-\Delta_p)^s u = f \quad \text{in } \Omega \times I,$$

as in Definition 2.1 where $f \in L_{\text{loc}}^\infty(\Omega \times I)$ and

$$\|u\|_{L^\infty(Q_{2R, (2R)^{sp}}(x_0, T_0))} + \sup_{-(2R)^{sp} + T_0 < t \leq T_0} \text{Tail}_{p-1, sp}(u(\cdot, t); x_0, R) < \infty.$$

Define the exponents

$$\Theta(s, p) := \begin{cases} \frac{sp}{p-1}, & \text{if } s < \frac{p-1}{p}, \\ 1, & \text{if } s \geq \frac{p-1}{p}, \end{cases} \quad \text{and} \quad \Gamma(s, p) := \begin{cases} 1, & \text{if } s < \frac{p-1}{p}, \\ \frac{1}{sp - (p-2)}, & \text{if } s \geq \frac{p-1}{p}. \end{cases} \quad (1.2)$$

Then

$$u \in C_{x, \text{loc}}^\theta(\Omega \times I) \cap C_{t, \text{loc}}^\gamma(\Omega \times I), \quad \text{for every } 0 < \theta < \Theta(s, p) \text{ and } 0 < \gamma < \Gamma(s, p).$$

More precisely, for every (x_0, T_0) such that

$$Q_{2R, (2R)^{sp}}(x_0, T_0) \Subset \Omega \times I,$$

there exists a constant $C = C(N, s, p, \theta, \gamma) > 0$ such that

$$\sup_{t \in [T_0 - (R/4)^{sp}, T_0]} [u(\cdot, t)]_{C^\theta(B_{R/4}(x_0))} \leq CM^{1 + \frac{2-p}{sp}} R^{-\theta} \quad (1.3)$$

and

$$\sup_{x \in B_{\frac{R}{4}}(x_0)} [u(x, \cdot)]_{C^\gamma((-4^{-sp}R^{sp} + T_0, T_0))} \leq CM R^{-\gamma}, \quad (1.4)$$

where

$$M = \|u\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + \sup_{t \in (-R^{sp} + T_0, T_0]} \text{Tail}_{p-1, sp}(u(\cdot, t); x_0, R)^{p-1} + R^{sp} \|f\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + 1.$$

1.2. Comments on our result. Regarding the almost sharpness of the spatial Hölder regularity, it suffices to study the stationary problem. Indeed, see in Example 1.5 in [3] and Section 1.2 in [15], where it is proved that if the inhomogeneity is merely in L^q , then solutions may not be $C^{sp/(p-1)}$ in general. See also Example 1.6 in [3], where it is shown that for $p = 2$ and $s = 1/2$, solutions are not in general Lipschitz in space.

We point out that the time regularity is almost sharp in the case $sp \leq (p-1)$. Indeed, in Remark 1.3 in [4] it is proved that solutions are not better than Lipschitz in time in general.

Finally, we wish to comment on the assumption on the tail. This is relevant, since there is a recent development on the regularity theory under the weaker assumption that the tail is merely in L^q for some $q > p-1$ (cf. [6], [25] and [31]), while we in the present paper assume that the tail is in L^∞ . This assumption is not unreasonable. Indeed, consider the following modified version of Example 5.2 in [25].

Example 1.2. Let $0 < s < 1$ and $1 < p < 2$ be such that $sp \leq p - 1$. Suppose u_n is a weak solution of

$$\begin{cases} \partial_t u_n + (-\Delta_p)^s u_n &= 0, & \text{in } B_1 \times (-1, 1], \\ u_n &= g_n, & \text{on } (\mathbb{R}^N \setminus B_1) \times (-1, 1], \\ u_n(\cdot, -1) &= 0, & \text{on } B_1. \end{cases}$$

Here, $g_n(x, t) = 0$ when $x \in \mathbb{R}^N$ and $t \in (-1, 0]$ while for $x \in \mathbb{R}^N$ and $t \in (0, 1]$,

$$g_n(x, t) = \delta f_n(t) + f'_n(t) \chi_{B_3 \setminus B_2}(x),$$

where we for $n > e$ define

$$f_n(t) = \begin{cases} e^{-1}, & e^{-1} \leq t \leq 1, \\ -t \ln t, & \frac{1}{n} < t < e^{-1}, \\ t \ln n, & 0 < t \leq \frac{1}{n}. \end{cases}$$

In addition, $\delta > 0$ is chosen so that

$$\delta + (-\Delta_p)^s \chi_{B_3 \setminus B_2}(x) \leq 0,$$

for all $x \in \mathbb{R}^N$. The existence of such a solution u_n is guaranteed by for instance Theorem 1.4 in [16]. To this end, we note that since $sp \leq (p - 1) < 1$, g_n lies in $W^{s,p}(\mathbb{R}^N)$ and with this choice of f_n we have $f_n, f'_n \in L^\infty(-1, 1]$. Hence, g_n is admissible for this theorem. For $x \in B_1$ and $t \in (-1, 0]$, we have $\partial_t g_n + (-\Delta_p)^s g_n = 0$ since $g_n(x, t) = 0$ for $t \in (-1, 0]$. We also see that $f'_n(t) \geq 0$ and therefore, for $x \in B_1$ and $t \in (0, 1]$, we have

$$\partial_t g_n + (-\Delta_p)^s g_n = \delta f'_n(t) + f'_n(t) (-\Delta_p)^s \chi_{B_3 \setminus B_2}(x) \leq 0.$$

Hence, g_n is a subsolution in $B_1 \times (-1, 1)$. By the comparison principle (see for example Proposition A.3 in [29]), $u_n \geq g_n$ for $x \in B_1$ and $t \in (-1, 1]$ and also $u_n(x, t) = 0$ (note that $g_n(x, t) = 0$ for $x \in \mathbb{R}^N$ and $t \in (-1, 0]$) for all $x \in B_1$ and $t \in (-1, 0]$. This implies that for $x \in B_1$,

$$\frac{u_n(x, 2/n) - u_n(x, -2/n)}{2/n} \geq \frac{g_n(2/n) - g_n(0)}{2/n} = \frac{g_n(2/n)}{2/n} = \ln n - \ln 2 \rightarrow \infty \text{ as } n \rightarrow \infty.$$

Hence, the sequence $\{u_n\}$ is not uniformly Lipschitz in time while

$$\text{Tail}_{p-1,sp}(u_n(\cdot, t); 0, 1)^{p-1} \simeq f_n^{p-1}(t) + (f'_n)^{p-1}(t)$$

is uniformly bounded in $L^q(-1, 1)$ for all $q < \infty$ but not for $q = \infty$. This shows that we cannot have an apriori Lipschitz estimate in time, in terms of the L^q norm for any finite q . Hence, in some sense the L^∞ -assumption on the tail is almost optimal.

By instead choosing $f_n(t) \sim t^{1-\varepsilon}$ one can show for each q there is an upper bound on which Hölder seminorm (in time) can be bounded in terms of the L^q norm of the tail.

1.3. Known results. The fractional p -Laplace equation

$$(-\Delta_p)^s u = 0, \quad 1 < p < \infty, \tag{1.5}$$

has been widely studied and the available literature is vast. For $p = 2$, see [23] for a local Hölder continuity result. We also refer to [35] and the references therein.

In the nonlinear case $1 < p < \infty$, Hölder regularity and Harnack inequalities for weak solutions are proved in [8, 10, 11]. In [32], Hölder continuity for viscosity solutions is established. Hölder continuity up to the boundary and fine boundary regularity has been studied in [19–22]

Higher regularity results for the nonlocal equation (1.5) are established in [3] for the case $p \geq 2$ and in [15] for $p < 2$ respectively.

Recently, higher Hölder regularity in the case $p = 2$ with a more general kernel is established in [33]. We also mention [12, 28], where sharp regularity results for the equation with a right hand side belonging to a Lorentz space are studied.

The parabolic counterpart of the equation (1.5), namely equation (1.1), has recently been studied by various authors.

When $p = 2$, local Hölder continuity of weak solutions for the equation (1.1) is proved in [7, 14, 24]. A Harnack inequality and local boundedness results can for instance be found in [5, 25–27, 36]. In addition, higher Sobolev regularity results can be found in [2].

In the nonlinear parabolic case, when $p > 2$, local boundedness result for the equation (1.1) is proved in [37] with zero right-hand side. For the non-zero right-hand side, local boundedness results can be found in [13] for any $1 < p < \infty$ and in [38] for any $p \geq 2$ respectively. Local Hölder continuity is proved in [13] for $p > 2$ and in [1, 30] for any $1 < p < \infty$ respectively.

For higher Hölder regularity results, when $p \geq 2$, we refer to [4] with zero right hand side and [17, 38] for non-zero right hand side respectively. Recently, higher Hölder regularity was obtained in the case $p = 2$ allowing for more general kernel and a right hand side, in [5].

It is worth mentioning that most of the results for nonlocal parabolic equations have been obtained under the assumption that the tail is locally bounded in time. Recently, there has been some advances when less restrictive assumptions on the tail have been assumed. This was initiated in [25] for the linear setting and considered for the case of the fractional p -Laplacian in [6] and [31].

Plan of the paper: In Section 2, we introduce some notation and discuss preliminary results used throughout the paper. This is followed by Section 3, where we obtain an improvement of regularity on the Besov scale, given some initial Hölder regularity. This is then iterated and yields the desired spatial regularity in the normalized setting in Section 4. In Section 5, the time regularity is obtained, using the known spatial regularity. Finally, in Section 6, we prove our main result by combining the previous results.

2. PRELIMINARIES

In this section, we introduce some notation and present preliminary results needed in the rest of the paper. Throughout the paper, we shall use the following notation: $B_r(x_0)$ denotes the ball of radius r with center at x_0 . When $x_0 = 0$, we write $B_r(0) := B_r$. Its Lebesgue measure is given by

$$|B_r(x_0)| = \omega(N)r^N,$$

where $\omega(N)$ is the volume of the unit ball B_1 . We use the following notation for the parabolic cylinder

$$Q_{R,r}(x_0, t_0) = B_R(x_0) \times (t_0 - r, t_0].$$

Again, when $x_0 = 0$ and $t_0 = 0$, we simply write $Q_{R,r}$. The conjugate exponent $\frac{l}{l-1}$ of $l > 1$ will be denoted by l' . We write c or C to denote a positive constant which may vary from line to line or even in the same line. The dependencies on parameters are written in the parentheses.

For any $1 < q < \infty$, we define the monotone function $J_q : \mathbb{R} \rightarrow \mathbb{R}$ by

$$J_q(t) = |t|^{q-2}t \tag{2.1}$$

and for $0 < s < 1$ and $1 < p < \infty$ we use the notation

$$d\mu = \frac{dx \, dy}{|x - y|^{N+ps}}. \tag{2.2}$$

If $\psi : \mathbb{R}^N \rightarrow \mathbb{R}$ is a function and $h \in \mathbb{R}^N$, then for any $x \in \mathbb{R}^N$, we define

$$\psi_h(x) = \psi(x + h), \quad \delta_h \psi(x) = \psi_h(x) - \psi(x)$$

and

$$\delta_h^2 \psi(x) = \delta_h(\delta_h \psi(x)) = \psi_{2h}(x) + \psi(x) - 2\psi_h(x). \quad (2.3)$$

Let $h \in \mathbb{R}^N$ and $\varphi, \psi : \mathbb{R}^N \rightarrow \mathbb{R}$ be two given functions, then the following discrete product rule holds:

$$\delta_h(\varphi\psi)(x) = (\psi_h \delta_h \varphi + \varphi \delta_h \psi)(x), \quad \forall x \in \mathbb{R}^N. \quad (2.4)$$

Similarly, for $\varphi : \mathbb{R}^N \times I \rightarrow \mathbb{R}$, for any fixed $t \in I$ and for every $x \in \mathbb{R}^N$, we define

$$\varphi_h(x, t) = \varphi(x + h, t), \quad \delta_h \varphi(x, t) = \varphi_h(x, t) - \varphi(x, t)$$

and

$$\delta_h^2 \varphi(x, t) = \delta_h(\delta_h \varphi(x, t)) = \varphi_{2h}(x, t) + \varphi(x, t) - 2\varphi_h(x, t). \quad (2.5)$$

Function spaces: Let $E \subset \mathbb{R}^N$, $N \geq 1$ be an open and bounded subset. Suppose $v : E \rightarrow \mathbb{R}$ is a function. Then for $0 \leq \delta \leq 1$, we define the δ -Hölder seminorm by

$$[v]_{C^\delta(E)} := \sup_{x \neq y \in E} \frac{|v(x) - v(y)|}{|x - y|^\delta}.$$

It will be necessary to introduce two function spaces. For this reason, let $1 \leq q < \infty$ and take $\psi \in L^q(\mathbb{R}^N)$. For $0 < \beta \leq 1$, define

$$[\psi]_{\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)} := \sup_{|h| > 0} \left\| \frac{\delta_h \psi}{|h|^\beta} \right\|_{L^q(\mathbb{R}^N)}.$$

The Besov-type spaces $\mathcal{N}_{\infty}^{\beta, q}$ are defined by

$$\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N) = \left\{ \psi \in L^q(\mathbb{R}^N) : [\psi]_{\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)} < +\infty \right\}, \quad 0 < \beta \leq 1.$$

The *Sobolev-Slobodeckii* space is defined as

$$W^{\beta, q}(\mathbb{R}^N) = \left\{ \psi \in L^q(\mathbb{R}^N) : [\psi]_{W^{\beta, q}(\mathbb{R}^N)} < +\infty \right\}, \quad 0 < \beta < 1,$$

where the seminorm $[\cdot]_{W^{\beta, q}(\mathbb{R}^N)}$ is given by

$$[\psi]_{W^{\beta, q}(\mathbb{R}^N)} = \left(\iint_{\mathbb{R}^N \times \mathbb{R}^N} \frac{|\psi(x) - \psi(y)|^q}{|x - y|^{N + \beta q}} dx dy \right)^{\frac{1}{q}}.$$

The above spaces are endowed with the norms

$$\|\psi\|_{\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)} = \|\psi\|_{L^q(\mathbb{R}^N)} + [\psi]_{\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)},$$

and

$$\|\psi\|_{W^{\beta, q}(\mathbb{R}^N)} = \|\psi\|_{L^q(\mathbb{R}^N)} + [\psi]_{W^{\beta, q}(\mathbb{R}^N)}.$$

We also introduce the space $W^{\beta, q}(\Omega)$ for a subset $\Omega \subset \mathbb{R}^N$,

$$W^{\beta, q}(\Omega) = \left\{ \psi \in L^q(\Omega) : [\psi]_{W^{\beta, q}(\Omega)} < +\infty \right\}, \quad 0 < \beta < 1,$$

where naturally

$$[\psi]_{W^{\beta, q}(\Omega)} = \left(\iint_{\Omega \times \Omega} \frac{|\psi(x) - \psi(y)|^q}{|x - y|^{N + \beta q}} dx dy \right)^{\frac{1}{q}}.$$

The space $W_0^{\beta, q}(\Omega)$ is the subspace of $W^{\beta, q}(\mathbb{R}^N)$ consisting of functions that are identically zero in the complement of Ω .

Parabolic Banach spaces: Suppose that $I \subset \mathbb{R}$ is an interval and let V be a separable and reflexive Banach space, with a norm $\|\cdot\|_V$. Let V^* be its topological dual space. Assume that v is a function such $v(t)$ belongs to V for almost every $t \in I$. If the function $t \mapsto \|v(t)\|_V$ is measurable on I and $1 \leq p \leq \infty$, then v belongs to the Banach space $L^p(I; V)$ if and only if

$$\int_I \|v(t)\|_V^p dt < \infty.$$

It is well known that the dual space of $L^p(I; V)$ can be characterized by

$$(L^p(I; V))^* = L^p(I; V^*).$$

See [34, Theorem 1.5]. We also write $v \in C(I; V)$ if the function $t \mapsto v(t)$ is continuous with respect to topology on V . Moreover, u is locally α -Hölder continuous ($0 < \alpha < 1$) in space (respectively, locally β -Hölder continuous ($0 < \beta < 1$) in time) on $\Omega \times I$ and write

$$u \in C_{x, \text{loc}}^\alpha(\Omega \times I) \quad \left(\text{respectively, } u \in C_{t, \text{loc}}^\beta(\Omega \times I) \right)$$

if for any compact subset $K \times J \subset \Omega \times I$, we have

$$\sup_{t \in J} [u(\cdot, t)]_{C^\alpha(K)} < \infty \quad \left(\text{respectively, } \sup_{x \in K} [u(x, \cdot)]_{C^\beta(J)} < \infty \right).$$

Tail spaces and weak solutions: The so-called *tail spaces* are expedient for nonlocal equations. The *tail space* is defined as

$$L_\alpha^q(\mathbb{R}^N) = \left\{ u \in L_{\text{loc}}^q(\mathbb{R}^N) : \int_{\mathbb{R}^N} \frac{|u|^q}{1 + |x|^{N+\alpha}} \, dx < +\infty \right\}, \quad q > 0 \text{ and } \alpha > 0,$$

and is endowed with the norm

$$\|u\|_{L_\alpha^q(\mathbb{R}^N)} = \left(\int_{\mathbb{R}^N} \frac{|u(x)|^q}{1 + |x|^{N+\alpha}} \, dx \right)^{\frac{1}{q}}.$$

The global behavior of a function $u \in L_\alpha^q(\mathbb{R}^N)$ is measured by the quantity

$$\text{Tail}_{q, \alpha}(u; x_0, R) = \left[R^\alpha \int_{\mathbb{R}^N \setminus B_R(x_0)} \frac{|u(x)|^q}{|x - x_0|^{N+\alpha}} \, dx \right]^{\frac{1}{q}}.$$

Here $x_0 \in \mathbb{R}^N$, $R > 0$, $\beta > 0$.

Definition 2.1. (*Local weak solution*) Let $1 < p \leq 2$ and $0 < s < 1$. Suppose $\Omega \subset \mathbb{R}^N$ is an open and bounded set and that $f \in L_{\text{loc}}^\infty(\Omega \times I)$. For any $t_0, t_1 \in \mathbb{R}$, we define $I = (t_0, t_1]$. We say that u is a local weak solution of the equation

$$\partial_t u + (-\Delta_p)^s u = f \text{ in } \Omega \times I$$

if for any closed interval $J = [T_0, T_1] \subset I$, the function u is such that

$$u \in L^p(J; W_{\text{loc}}^{s, p}(\Omega)) \cap L^{p-1}(J; L_{sp}^{p-1}(\mathbb{R}^N)) \cap C(J; L_{\text{loc}}^2(\Omega))$$

and it satisfies

$$\begin{aligned} & - \int_J \int_\Omega u(x, t) \partial_t \varphi(x, t) \, dx \, dt + \int_J \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} J_p(u(x) - u(y)) (\varphi(x) - \varphi(y)) \, d\mu \, dt \\ & = \int_\Omega u(x, T_0) \varphi(x, T_0) \, dx - \int_\Omega u(x, T_1) \varphi(x, T_1) \, dx + \int_J \int_\Omega f(x, t) \varphi(x, t) \, dx \, dt, \end{aligned} \quad (2.6)$$

for every $\varphi \in L^p(J; W^{s, p}(\Omega)) \cap C^1(J; L^2(\Omega))$ which has spatial support compactly contained in Ω . Here

$$d\mu = \frac{dx \, dy}{|x - y|^{N+ps}}$$

as defined in (2.2).

We have the following embedding result from [4, Theorem 2.8].

Theorem 2.2. Let $\psi \in \mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)$, where $0 < \beta < 1$ and $1 \leq q < \infty$ such that $\beta q > N$. Then for every $0 < \alpha < \beta - \frac{N}{q}$, we have $\psi \in C_{\text{loc}}^\alpha(\mathbb{R}^N)$. More precisely,

$$\sup_{x \neq y} \frac{|\psi(x) - \psi(y)|}{|x - y|^\alpha} \leq C \left([\psi]_{\mathcal{N}_{\infty}^{\beta, q}(\mathbb{R}^N)} \right)^{\frac{\alpha q + N}{\beta q}} \left(\|\psi\|_{L^q(\mathbb{R}^N)} \right)^{\frac{(\beta - \alpha)q - N}{\beta q}},$$

for some positive constant $C = C(N, q, \alpha, \beta)$ which blows up as $\alpha \nearrow \beta - \frac{N}{q}$.

The result below allows for power functions of the solution to be used as test functions. It can be proved by following the proof of [4, Lemma 3.3], see also [17, Lemma 4.1].

Lemma 2.3. *Let $a > 0$, $1 < p \leq 2$ and $0 < s < 1$. Suppose that u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \text{ in } B_2 \times (-2^{sp}a, 0]$$

as in Definition 2.1, where

$$f \in L_{\text{loc}}^\infty(B_2 \times (-2^{sp}a, 0]) \quad \text{and} \quad u \in L^\infty(E \times (-a, 0]),$$

for every $E \Subset B_2$. Let η be a non-negative Lipschitz function, with compact support in B_2 . Let τ be a smooth non-negative function such that $0 \leq \tau \leq 1$ and

$$\tau(t) = 0 \text{ for } t \leq T_0, \quad \tau(t) = 1 \text{ for } t \geq T_1$$

for some $-a < T_0 < T_1 < 0$. Then, for any locally Lipschitz function $F : \mathbb{R} \rightarrow \mathbb{R}$ and any $h \in \mathbb{R}^N$ such that $0 < |h| < \frac{1}{4} \text{dist}(\text{supp } \eta, \partial B_2)$, we have

$$\begin{aligned} & \int_{T_0}^{T_1} \iint_{\mathbb{R}^{2N}} \left(J_p(u_h(x, t) - u_h(y, t)) - J_p(u(x, t) - u(y, t)) \right) \\ & \times \left(F(\delta_h u(x, t)) \eta(x)^2 - F(\delta_h u(y, t)) \eta(y)^2 \right) \tau(t) \, d\mu \, dt \\ & + \int_{B_2} \mathcal{F}(\delta_h u(x, T_1)) \eta(x)^2 \, dx = \int_{T_0}^{T_1} \int_{B_2} \mathcal{F}(\delta_h u) \eta^2 \tau' \, dx \, dt + \int_{T_0}^{T_1} \int_{B_2} (\delta_h f) F(\delta_h u) \eta^2 \tau \, dx \, dt, \end{aligned} \quad (2.7)$$

where $\mathcal{F}(t) = \int_0^t F(\rho) \, d\rho$.

Proof. The proof follows exactly as in the proof of [17, Lemma 4.1] as well as [4, Lemma 3.3] by replacing η^p with η^2 . □

3. IMPROVED BESOV REGULARITY

In this section, we obtain an improvement of regularity on the Besov scale, given some initial Hölder regularity.

Proposition 3.1. *Let $1 < p < 2$, $0 < s < 1$ and $a > 0$. Suppose that u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \quad \text{in } B_2 \times (-2^{sp}a, 0]$$

where

$$\|f\|_{L^\infty(B_1 \times (-a, 0])} \leq 1, \quad \|u\|_{L^\infty(B_1 \times (-a, 0])} \leq 1,$$

$$\sup_{-a < t \leq 0} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1) \leq 1 \quad \text{and} \quad \sup_{-a < t \leq 0} [u(\cdot, t)]_{C^\gamma(B_1)} \leq 1,$$

for some $\gamma \in [0, 1)$. Assume also that for some $\alpha \in [0, 1)$, $1 \leq q < \infty$ and $0 < h_0 < \frac{1}{10}$, we have

$$\int_{T_0}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q \, dt < \infty \quad (3.1)$$

for R such that $4h_0 < R \leq 1 - 5h_0$, and for T_0 such that $-a < T_0 < 0$. Then for any ρ such that $T_0 < \rho + T_0 < 0$, we have

$$\begin{aligned} & \int_{T_0+\rho}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right\|_{L^{q+1}(B_{R-4h_0})}^{q+1} dt + \sup_{T_0+\rho < t \leq 0} \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \frac{|\delta_h u(x, t)|^{q+1}}{|h|^{\alpha q}} dx \\ & \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^0 \left(1 + \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q \right) dt, \end{aligned} \quad (3.2)$$

for some positive constant $C = C(N, s, p, q, h_0, \gamma)$.

Proof. We prove the result in two steps. In the first, we prove

$$\begin{aligned} & \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt + \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{\alpha q}} dx \\ & \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \left(1 + \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q \right) dt, \end{aligned} \quad (3.3)$$

with the upper limit $T_1 < 0$ and in Step 2, we prove (3.3) for $T_1 = 0$, then (3.2) follows by taking the supremum over T_1 .

Step 1: Estimate for $T_1 < 0$. Assume $\rho + T_0 < T_1 < 0$, let $r = R - 4h_0$ and take η to be a non-negative smooth function on \mathbb{R}^N such that

$$0 \leq \eta \leq 1 \text{ on } B_R, \quad \eta \equiv 1 \text{ on } B_r, \quad \eta \equiv 0 \text{ in } \mathbb{R}^N \setminus B_{\frac{R+r}{2}} \quad \text{and} \quad |\nabla \eta| \leq \frac{C}{h_0} \text{ on } B_{\frac{R+r}{2}},$$

for some positive constant C .

Take also $\tau : \mathbb{R} \rightarrow \mathbb{R}$ to be a smooth function such that $0 \leq \tau \leq 1$ in \mathbb{R} and

$$\tau \equiv 1 \text{ on } [T_0 + \rho, \infty), \quad \tau \equiv 0 \text{ on } (-\infty, T_0], \quad \text{and} \quad |\tau'| \leq \frac{C}{\rho} \text{ in } \mathbb{R},$$

for some positive constant C . Let $1 \leq q < \infty$, $0 < |h| < h_0$ and $\alpha \in [0, 1)$ be as in the statement of the theorem and define $\vartheta = \alpha - \frac{1}{q}$. Lemma 2.3 with $F(t) = J_{q+1}(t)$ implies upon dividing with $|h|^{1+\vartheta q}$ that

$$\begin{aligned} & \int_{T_0}^{T_1} \iint_{\mathbb{R}^N \times \mathbb{R}^N} \frac{\left(J_p(u_h(x, t) - u_h(y, t)) - J_p(u(x, t) - u(y, t)) \right)}{|h|^{1+\vartheta q}} \\ & \quad \times \left(J_{q+1}(\delta_h u(x, t)) \eta(x)^2 - J_{q+1}(\delta_h u(y, t)) \eta(y)^2 \right) \tau(t) d\mu dt \\ & + \frac{1}{q+1} \int_{B_2} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 dx \\ & = \frac{1}{q+1} \int_{T_0}^{T_1} \int_{B_2} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \tau' dx dt + \int_{T_0}^{T_1} \int_{B_2} \delta_h f \frac{J_{q+1}(\delta_h u)}{|h|^{1+\vartheta q}} \eta^2 \tau dx dt. \end{aligned} \quad (3.4)$$

The triple integral is now divided into three pieces:

$$\tilde{\mathcal{I}}_i := \int_{T_0}^{T_1} \mathcal{I}_i(t) \tau(t) dt, \quad i = 1, 2, 3,$$

where we for $t \in (T_0, T_1)$ define

$$\begin{aligned} \mathcal{I}_1(t) := & \iint_{B_R \times B_R} \frac{\left(J_p(u_h(x, t) - u_h(y, t)) - J_p(u(x, t) - u(y, t)) \right)}{|h|^{1+\vartheta q}} \\ & \times \left(J_{q+1}(\delta_h u(x, t)) \eta(x)^2 - J_{q+1}(\delta_h u(y, t)) \eta(y)^2 \right) d\mu, \end{aligned}$$

$$\mathcal{I}_2(t) := \iint_{(x,y) \in B_{\frac{R+r}{2}} \times (\mathbb{R}^N \setminus B_R)} \frac{(J_p(u_h(x,t) - u_h(y,t)) - J_p(u(x,t) - u(y,t)))}{|h|^{1+\vartheta q}} J_{q+1}(\delta_h u(x,t)) \eta(x)^2 \, d\mu,$$

and

$$\mathcal{I}_3(t) := - \iint_{(x,y) \in (\mathbb{R}^N \setminus B_R) \times B_{\frac{R+r}{2}}} \frac{(J_p(u_h(x,t) - u_h(y,t)) - J_p(u(x,t) - u(y,t)))}{|h|^{1+\vartheta q}} J_{q+1}(\delta_h u(y,t)) \eta(y)^2 \, d\mu,$$

where we used that η vanishes identically outside $B_{\frac{R+r}{2}}$. We also denote the terms on the right-hand side of (3.4) by \mathcal{I}_4 and \mathcal{I}_5 :

$$\mathcal{I}_4 := \frac{1}{q+1} \int_{T_0}^{T_1} \int_{B_2} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \tau' \, dx \, dt,$$

and

$$\mathcal{I}_5 := \int_{T_0}^{T_1} \int_{B_2} \delta_h f \frac{J_{q+1}(\delta_h u)}{|h|^{1+\vartheta q}} \eta^2 \tau \, dx \, dt.$$

Therefore, with the above notation, equation (3.4) reduces to the following equation

$$\tilde{\mathcal{I}}_1 + \frac{1}{q+1} \int_{B_2} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \, dx = -\tilde{\mathcal{I}}_2 - \tilde{\mathcal{I}}_3 + \mathcal{I}_4. \quad (3.5)$$

Estimate of $\tilde{\mathcal{I}}_1$: Since $1 < p < 2$, by the same argument as in the proof of [15, Pages 10–13, Proposition 3.1], we obtain for any $t \in (T_0, T_1)$

$$\mathcal{I}_1(t) \geq c^{-1} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 - C \int_{B_R} \frac{|\delta_h u(x,t)|^{p+q-1}}{|h|^{1+\vartheta q}} - C \int_{B_R} \frac{|\delta_h u(x,t)|^{q+1}}{|h|^{1+\vartheta q}}. \quad (3.6)$$

After integration with respect to t this becomes

$$\tilde{\mathcal{I}}_1 \geq c^{-1} \int_{T_0}^{T_1} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 \tau \, dt - C \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x)|^{p+q-1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt - C \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x)|^{q+1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt, \quad (3.7)$$

where $c = c(p, q)$ and $C = C(N, s, p, q, h_0)$ are positive constants, and $2\sigma = sp - \gamma(p-2)$. We remark that the properties of η and the given condition $\sup_{-a \leq t \leq 0} [u(\cdot, t)]_{C^\gamma(B_1)} \leq 1$ are used to derive the above estimate of $\tilde{\mathcal{I}}_1$. Using (3.7) in (3.5), we arrive at

$$\begin{aligned} & \int_{T_0}^{T_1} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 \tau \, dt + \int_{B_2} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \, dx \\ & \leq C \left(\int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x,t)|^{q+1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt + \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x,t)|^{p+q-1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt \right) \\ & \quad + c \left(|\tilde{\mathcal{I}}_2| + |\tilde{\mathcal{I}}_3| + |\mathcal{I}_4| + |\mathcal{I}_5| \right), \end{aligned} \quad (3.8)$$

where $C = C(N, s, p, q, h_0)$ is a positive constant.

Estimate of the nonlocal terms $\tilde{\mathcal{I}}_2$ and $\tilde{\mathcal{I}}_3$: First, we estimate $\mathcal{I}_2(t)$ for any $t \in (T_0, T_1)$. Since $|u| \leq 1$ in $B_1 \times (-a, 0]$, we have

$$|(J_p(u_h(x,t) - u_h(y,t)) - J_p(u(x,t) - u(y,t))) J_{q+1}(\delta_h u(x,t))| \leq C(p)(1 + |u_h(y,t)|^{p-1} + |u(y,t)|^{p-1}) |\delta_h u(x,t)|^q, \quad (3.9)$$

where $x \in B_{\frac{R+r}{2}}$, $y \in \mathbb{R}^N \setminus B_R$ and $4h_0 < R \leq 1 - 5h_0$. Therefore, $|x - y| \geq h_0|y|$ and we get

$$\begin{aligned} & \int_{\mathbb{R}^N \setminus B_R} \frac{1 + |u(y,t)|^{p-1} + |u_h(y,t)|^{p-1}}{|x - y|^{N+sp}} \, dy \\ & \leq C \left(1 + \int_{\mathbb{R}^N \setminus B_R} \frac{|u(y,t)|^{p-1}}{|y|^{N+sp}} \, dy + \int_{\mathbb{R}^N \setminus B_R} \frac{|u_h(y,t)|^{p-1}}{|y|^{N+sp}} \, dy \right), \end{aligned} \quad (3.10)$$

for some positive constant $C = C(N, s, p, h_0)$. Now, since $4h_0 < R$, $R < 1$, $|u| \leq 1$ in $B_1 \times (-a, 0]$ and $\text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1) \leq 1$ in $(-a, 0]$, we have

$$\begin{aligned} \int_{\mathbb{R}^N \setminus B_R} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy &\leq \int_{\mathbb{R}^N \setminus B_1} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy + R^{-N-sp} \int_{B_1} |u(y, t)|^{p-1} dy \\ &\leq \int_{\mathbb{R}^N \setminus B_1} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy + N\omega_N(4h_0)^{-N-sp} \\ &\leq C, \end{aligned} \quad (3.11)$$

where $C = C(N, s, p, h_0)$. As for u_h , we have

$$\begin{aligned} \int_{\mathbb{R}^N \setminus B_R} \frac{|u(y+h, t)|^{p-1}}{|y|^{N+sp}} dy &\leq \int_{\mathbb{R}^N \setminus B_R(h)} \frac{|u(y, t)|^{p-1}}{|y-h|^{N+sp}} dy \leq \left(\frac{3}{2}\right)^{N+sp} \int_{\mathbb{R}^N \setminus B_R(h)} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy \\ &\leq \left(\frac{3}{2}\right)^{N+sp} \left[\int_{\mathbb{R}^N \setminus B_1} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy + (R-h_0)^{-N-sp} \int_{B_1} |u(y, t)|^{p-1} dy \right] \\ &\leq C (\text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1)^{p-1} + (3h_0)^{-N-sp}) \\ &\leq C, \end{aligned} \quad (3.12)$$

for some positive constant $C = C(N, s, p, h_0)$. To obtain the above estimate, we have used that $B_R(h) \subset B_1$, $4h_0 < R \leq 1 - 5h_0$ and

$$\frac{|y-h|}{|y|} = \left| \frac{y}{|y|} - \frac{h}{|y|} \right| \geq \left| \frac{y}{|y|} \right| - \left| \frac{h}{|y|} \right| \geq 1 - \frac{h_0}{R-h_0} \geq \frac{2}{3}.$$

Using (3.11) and (3.12) in (3.10), we get

$$\int_{\mathbb{R}^N \setminus B_R} \frac{1 + |u(y, t)|^{p-1} + |u_h(y, t)|^{p-1}}{|x-y|^{N+sp}} dy \leq C(N, s, p, h_0). \quad (3.13)$$

Using (3.9) and (3.13) and recalling the expression of $\mathcal{I}_2(t)$, we get for any $t \in (T_0, T_1)$ that

$$\begin{aligned} |\mathcal{I}_2(t)| &\leq \iint_{(x,y) \in B_{\frac{R+r}{2}} \times (\mathbb{R}^N \setminus B_R)} \frac{|J_p(u_h(x, t) - u_h(y, t)) - J_p(u(x, t) - u(y, t))|}{|x-y|^{N+sp}} \frac{|\delta_h u(x, t)|^q}{|h|^{1+\vartheta q}} \eta(x)^2 dy dx \\ &\leq C(N, s, p, h_0) \int_{B_{\frac{R+r}{2}}} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} \eta^2 dx. \end{aligned}$$

Multiplying by τ and integrating the above estimate from T_0 to T_1 , we arrive at

$$|\tilde{\mathcal{I}}_2| \leq \int_{T_0}^{T_1} |\mathcal{I}_2| \tau dt \leq C \left(\int_{T_0}^{T_1} \left(\int_{B_R} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} \eta^2 dx \right) \tau dt \right) \leq C \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} dx dt, \quad (3.14)$$

for some positive constant $C = C(N, s, p, h_0)$. Here we have used that $0 \leq \tau \leq 1$ on \mathbb{R} . Similarly,

$$|\tilde{\mathcal{I}}_3| \leq C \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} dx dt, \quad (3.15)$$

for some positive constant $C = C(N, s, p, h_0)$.

Estimate of \mathcal{I}_4 and \mathcal{I}_5 : Using the properties of η and τ we have

$$|\mathcal{I}_4| = \frac{1}{q+1} \left| \int_{T_0}^{T_1} \int_{B_2} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \tau' dx dt \right| \leq \frac{C}{\rho} \int_{T_0}^{T_1} \int_{B_{\frac{R+r}{2}}} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} dx dt, \quad (3.16)$$

for some positive constant $C = C(N, p, q)$. By the L^∞ -bound on f together with the properties of η and τ , we also obtain

$$\begin{aligned} |\mathcal{I}_5| &= \left| \int_{T_0}^{T_1} \int_{B_2} \delta_h f \frac{J_{q+1}(\delta_h u)}{|h|^{1+\vartheta q}} \eta^2 \tau \, dx \, dt \right| \leq \int_{T_0}^{T_1} \int_{B_2} |\delta_h f| \frac{|J_{q+1}(\delta_h u)|}{|h|^{1+\vartheta q}} \eta^2 \tau \, dx \, dt \\ &\leq \|\delta_h f \eta\|_{L^\infty(B_2 \times (T_0, T_1))} \int_{T_0}^{T_1} \int_{B_2} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} \eta \, dx \, dt \\ &\leq 2 \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u|^q}{|h|^{1+\vartheta q}} \, dx \, dt. \end{aligned} \quad (3.17)$$

Using (3.14), (3.15), (3.16) and (3.17) in (3.8), we arrive at

$$\begin{aligned} &\int_{T_0+\rho}^{T_1} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 dt + \frac{c}{q+1} \int_{B_R} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 \, dx \\ &\leq C \left(\int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x, t)|^{q+1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt + \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x, t)|^{p+q-1}}{|h|^{1+\vartheta q}} \tau \, dx \, dt \right) \\ &\quad + C \left(\frac{1}{\rho} \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x, t)|^{q+1}}{|h|^{1+\vartheta q}} \, dx \, dt + \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x, t)|^q}{|h|^{1+\vartheta q}} \, dx \, dt \right) \\ &\leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \int_{B_R} \left(\frac{|\delta_h u(x, t)|^q}{|h|^{1+\vartheta q}} + \frac{|\delta_h u(x, t)|^{q+1}}{|h|^{1+\vartheta q}} + \frac{|\delta_h u(x, t)|^{p+q-1}}{|h|^{1+\vartheta q}} \right) \, dx \, dt \\ &\leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \int_{B_R} \frac{|\delta_h u(x, t)|^q}{|h|^{1+\vartheta q}} \, dx \, dt, \end{aligned} \quad (3.18)$$

where $C = C(N, s, p, q, h_0) > 0$ is a positive constant. Here we have used that $|\tau| \leq 1$ and that $|\delta_h u(x, t)| \leq 2$ for $(x, t) \in B_R \times (-a, 0] \subset B_1 \times (-a, 0]$. Next, we will find a lower bound of the first integral of the left hand side of (3.18), that is

$$\int_{T_0+\rho}^{T_1} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 dt.$$

Indeed, by following the same reasoning as in the proof of [15, Step 4, Proposition 3.1], we obtain for any $0 < |\xi|, |h| < h_0$ that

$$\int_{B_r} \left| \frac{\delta_\xi \delta_h u}{|\xi|^{\frac{2\sigma}{q+1}} |h|^{\frac{1+\vartheta q}{q+1}}} \right|^{q+1} dx \leq C \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 + C \int_{B_R} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} \, dx, \quad (3.19)$$

where $C = C(N, s, q, \sigma, h_0) > 0$ is a positive constant. We take $\xi = h$ in (3.19), take supremum over $0 < |h| < h_0$ and integrate over the time interval $(T_0 + \rho, T_1)$ to arrive at

$$\begin{aligned} \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_r} \left| \frac{\delta_h^2 u}{|h|^{\frac{2\sigma}{q+1}} |h|^{\frac{1+\vartheta q}{q+1}}} \right|^{q+1} dx \, dt &\leq C \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \left[\frac{|\delta_h u|^{\frac{q-1}{2}} \delta_h u}{|h|^{\frac{1+\vartheta q}{2}}} \eta \right]_{W^{\sigma,2}(B_R)}^2 dt \\ &\quad + C \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} \, dx \, dt, \end{aligned} \quad (3.20)$$

where $C = C(N, s, q, \sigma, h_0) > 0$ is a positive constant. By using (3.18) in (3.20) we obtain

$$\begin{aligned}
& \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_r} \left| \frac{\delta_h^2 u}{|h|^{\frac{2\sigma}{q+1} + \frac{1+\vartheta q}{q+1}}} \right|^{q+1} dx dt + \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{1+\vartheta q}} \eta^2 dx \\
& \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u(x)|^q}{|h|^{1+\vartheta q}} dx dt + C \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u|^{q+1}}{|h|^{1+\vartheta q}} dx dt \\
& \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u(x)|^q}{|h|^{1+\vartheta q}} dx dt,
\end{aligned} \tag{3.21}$$

where C depends on N, s, p, q, σ , and h_0 . In the last inequality, we have again used the fact that $|\delta_h u(x, t)| \leq 2$ for $x \in B_R$ and $t \in (-a, 0]$.

Recalling that $\vartheta = \alpha - \frac{1}{q}$ and $2\sigma = sp - \gamma(p-2)$, we obtain from (3.21) that

$$\begin{aligned}
& \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_r} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt + \sup_{0 < |h| < h_0} \int_{B_r} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{\alpha q}} dx \\
& \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \sup_{0 < |h| < h_0} \int_{B_R} \frac{|\delta_h u|^q}{|h|^{\alpha q}} dx dt,
\end{aligned} \tag{3.22}$$

for some positive constant $C = C(N, s, p, q, h_0, \gamma)$.

Since $1 < q < \infty$ and $|u| \leq 1$ in $B_1 \times (-a, 0]$, we may for $\alpha \in (0, 1)$ use the second estimate of [3, Lemma 2.6] to estimate the first order difference quotient in the right hand side of (3.22) by a second order difference quotient. Then (3.22) transforms into the inequality below upon recalling the relations between R, r and h_0 :

$$\begin{aligned}
& \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt + \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{\alpha q}} dx \\
& \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \left(1 + \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q \right) dt,
\end{aligned} \tag{3.23}$$

for some positive constant $C = C(N, s, p, q, h_0, \gamma)$. If $\alpha = 0$, we may directly use that $|u| \leq 1$ in $B_1 \times (-a, 0]$ together with (2.3) to arrive at (3.23).

Step 2: Conclusion for $T_1 = 0$. In this case, the previous proof does not directly work, since it relies on Lemma 2.3, which requires $T_1 < 0$. However, the constant C in (3.23) does not depend on T_1 , we can therefore use a limiting argument. By assumption, we have for some $\alpha \in [0, 1)$, $1 < q < \infty$ and $0 < h_0 < \frac{1}{10}$, that

$$\int_{T_0}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q < \infty$$

for $4h_0 < R \leq 1 - 5h_0$ and $-a < T_0 < 0$. For fixed ρ and T_0 , (3.23) implies that for every $T_1 < 0$ such that $\rho + T_0 < T_1$, there holds

$$\begin{aligned}
& \int_{T_0+\rho}^{T_1} \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt + \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \frac{|\delta_h u(x, T_1)|^{q+1}}{|h|^{\alpha q}} dx \\
& \leq \frac{C}{\min\{\rho, 1\}} \int_{T_0}^{T_1} \left(1 + \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^\alpha} \right\|_{L^q(B_{R+h_0})}^q \right) dt,
\end{aligned} \tag{3.24}$$

for some positive constant $C = C(N, s, p, q, h_0, \gamma)$. By the monotone convergence theorem,

$$\lim_{T \rightarrow 0^-} \int_{T_0+\rho}^T \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt = \int_{T_0+\rho}^0 \sup_{0 < |h| < h_0} \int_{B_{R-4h_0}} \left| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)+\alpha q}{q+1}}} \right|^{q+1} dx dt. \tag{3.25}$$

In addition, by the definition of local weak solution

$$t \mapsto \frac{\delta_h u(\cdot, t)}{|h|^{\frac{\alpha q}{q+1}}}$$

is locally a continuous function on $(-2^{sp}a, 0]$ with values in $L^2(B_r)$ for every fixed $0 < |h| < h_0$. Therefore,

$$\lim_{T \rightarrow 0^-} \left\| \frac{\delta_h u(\cdot, T)}{|h|^{\frac{\alpha q}{q+1}}} - \frac{\delta_h u(\cdot, 0)}{|h|^{\frac{\alpha q}{q+1}}} \right\|_{L^2(B_{R-4h_0})} = 0.$$

Since $q \geq 1$, this in turn implies that¹

$$\liminf_{T \rightarrow 0^-} \left\| \frac{\delta_h u(\cdot, T)}{|h|^{\frac{\alpha q}{q+1}}} \right\|_{L^{q+1}(B_{R-4h_0})} \geq \left\| \frac{\delta_h u(\cdot, 0)}{|h|^{\frac{\alpha q}{q+1}}} \right\|_{L^{q+1}(B_{R-4h_0})} \quad (3.26)$$

for every $0 < |h| < h_0$. Combining (3.25) and (3.26) with (3.24), gives that estimate (3.24) holds also for $T_1 = 0$. Finally, by taking the supremum over $T_1 \in [T_0 + \rho, 0]$ we obtain the desired estimate (3.2). \square

4. SPATIAL REGULARITY

Using Proposition 3.1, we establish the following spatial regularity results.

Proposition 4.1. *Assume that $a \geq a_0 > 0$, $0 < \kappa < 1$, $1 < p < 2$, $0 < s < 1$, and $\gamma \in [0, 1)$. Suppose u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \quad \text{in } B_2 \times (-2^{sp}a, 0]$$

as in Definition 2.1, where

$$\|f\|_{L^\infty(B_1 \times (-a, 0])} \leq 1, \quad \|u\|_{L^\infty(B_1 \times (-a, 0])} \leq 1,$$

$$\sup_{-a < t \leq 0} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1) \leq 1, \quad \text{and} \quad \sup_{-a < t \leq 0} [u(\cdot, t)]_{C^\gamma(B_1)} \leq 1,$$

for some $\gamma \in [0, 1)$. Let $\tau = \min\{sp - \gamma(p-2), 1\}$. Then for any $\varepsilon \in (0, \tau)$ we have

$$\sup_{-a(1-\kappa) \leq t \leq 0} [u(\cdot, t)]_{C^{\tau-\varepsilon}(B_{\frac{1}{2}})} \leq C,$$

for some positive constant $C = C(N, s, p, \varepsilon, \gamma, \kappa a_0)$.

Proof. Take $0 < \varepsilon < \tau$ and choose $q_0 = q_0(N, \varepsilon)$ so that

$$\tau - \frac{\varepsilon}{2} - \frac{N}{q_0} > \tau - \varepsilon > 0 \quad \text{and} \quad \frac{q_0}{q_0 + 1}(\tau - \frac{\varepsilon}{4}) \geq \tau - \frac{\varepsilon}{2}.$$

Then consider the sequence

$$\alpha_0 = 0, \quad \alpha_{i+1} := \frac{sp - \gamma(p-2) + \alpha_i q_0}{q_0 + 1}, \quad i = 0, \dots, i_\infty,$$

where we choose $i_\infty = i_\infty(N, p, s, \varepsilon, \gamma) \in \mathbb{N}$ such that

$$\alpha_{i_\infty-1} < \tau - \frac{\varepsilon}{4} \leq \alpha_{i_\infty}.$$

This is possible since the sequence of α_i is increasing and

$$\lim_{i \rightarrow \infty} \alpha_i = sp - \gamma(p-2).$$

Define also

$$h_0 = \frac{1}{40i_\infty}, \quad R_i = \frac{7}{8} - (5i+1)h_0, \quad \text{for } i = 0, \dots, i_\infty.$$

¹We use the following standard fact: if $\{f_n\}_{n \in \mathbb{N}}$ converges to f in $L^m(E)$, then

$$\liminf_{n \rightarrow \infty} \|f_n\|_{L^k(E)} \geq \|f\|_{L^k(E)}$$

for any $k \geq m$.

Note that

$$R_0 + h_0 = \frac{7}{8} \quad \text{and} \quad R_{i_\infty-1} - 4h_0 = \frac{3}{4}.$$

Now we apply Proposition 3.1 (ignoring the second term in the left-hand side of (3.2)) and apply Young's inequality with

$$q = q_0, \quad \rho = \frac{\kappa a}{2(i_\infty + 1)}, \quad T_0 = -a + (i + 1)\rho, \quad R = R_i.$$

We observe that $0 < \rho < -T_0$ for the above choice of T_0 , since $\kappa \in (0, 1)$. Further, $R_i - 4h_0 = R_{i+1} + h_0$. Therefore, we obtain the following iterative scheme of inequalities:

- For $i = 0$, we get

$$\int_{-a+2\rho}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\frac{sp-\gamma(p-2)}{q_0}}} \right\|_{L^{q_0}(B_{R_1+h_0})}^{q_0} dt \leq \frac{C}{\min\{\rho, 1\}} \int_{-a+\rho}^0 \left(\sup_{0 < |h| < h_0} \|\delta_h^2 u\|_{L^{q_0}(B_{7/8})}^{q_0} + 1 \right) dt. \quad (4.1)$$

Notice that $\frac{sp-\gamma(p-2)}{q_0+1} = \alpha_1$.

- For $i = 1, \dots, i_\infty - 2$, we have

$$\int_{-a+(i+2)\rho}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\alpha_{i+1}}} \right\|_{L^{q_0}(B_{R_{i+1}+h_0})}^{q_0} dt \leq \frac{C}{\min\{\rho, 1\}} \int_{-a+(i+1)\rho}^0 \left(\sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\alpha_i}} \right\|_{L^{q_0}(B_{R_i+h_0})}^{q_0} + 1 \right) dt. \quad (4.2)$$

- For $i = i_\infty - 1$, we have

$$\int_{-a+\frac{\kappa a}{2}}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\alpha_{i_\infty}}} \right\|_{L^{q_0}(B_{3/4})}^{q_0} dt \leq \frac{C}{\min\{\rho, 1\}} \int_{-a+i_\infty\rho}^0 \left(\sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\alpha_{i_\infty-1}}} \right\|_{L^{q_0}(B_{R_{i_\infty-1}+h_0})}^{q_0} + 1 \right) dt. \quad (4.3)$$

Here $C = C(N, s, p, \varepsilon, \gamma, h_0)$. Also, since $\|u\|_{L^\infty(B_1 \times (-a, 0])} \leq 1$, we have

$$\sup_{0 < |h| < h_0} \|\delta_h^2 u\|_{L^{q_0}(B_{7/8})} \leq 3. \quad (4.4)$$

Hence, using (4.4) in the above iterative scheme of inequalities (4.1), (4.2) and (4.3), we have the following estimate

$$\int_{-a(1-\frac{\kappa}{2})}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\alpha_{i_\infty}}} \right\|_{L^{q_0}(B_{3/4})}^{q_0} dt \leq \frac{C(N, s, p, \varepsilon, \gamma, h_0)}{(\min\{\kappa a, 1\})^{i_\infty}}. \quad (4.5)$$

As $\tau - \frac{\varepsilon}{4} \leq \alpha_{i_\infty}$, for all $|h| \leq 1$ we have

$$|h|^{\alpha_{i_\infty}} \leq |h|^{\tau - \frac{\varepsilon}{4}}.$$

Using this in (4.5) we arrive at

$$\int_{-a(1-\frac{\kappa}{2})}^0 \sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u}{|h|^{\tau - \frac{\varepsilon}{4}}} \right\|_{L^{q_0}(B_{3/4})}^{q_0} dt \leq \frac{C(N, s, p, \varepsilon, \gamma, h_0)}{(\min\{\kappa a, 1\})^{i_\infty}}. \quad (4.6)$$

Now we set

$$T_1 = 0, \quad T_0 = -a(1 - \kappa/2), \quad \rho = \frac{\kappa a}{2}, \quad \alpha = \tau - \frac{\varepsilon}{4}, \quad \text{and} \quad q = q_0.$$

Then,

$$R + h_0 = \frac{3}{4}, \quad R - 4h_0 = \frac{3}{4} - 5h_0 \geq \frac{5}{8}.$$

Since $a > 0$ and $\kappa \in (0, 1)$, we have $0 < \rho < T_1 - T_0$. We now apply Proposition 3.1 again, taking (4.6) into account (ignoring the first term in the left-hand side of (3.2) this time). This yields

$$\begin{aligned} \sup_{-a(1-\kappa) \leq t \leq 0} \sup_{0 < |h| < h_0} \left\| \frac{\delta_h u(\cdot, t)}{|h|^{\frac{(\tau-\varepsilon/4)q_0}{q_0+1}}} \right\|_{L^{q_0}(B_{5/8})}^{q_0} &\leq \frac{C}{\min\{\kappa a, 1\}} \int_{-a(1-\frac{\kappa a}{2})}^0 \left(\sup_{0 < |h| < h_0} \left\| \frac{\delta_h^2 u(\cdot, t)}{|h|^{\tau-\varepsilon/4}} \right\|_{L^{q_0}(B_{3/4})}^{q_0} + 1 \right) dt \\ &\leq \frac{C}{(\min\{\kappa a, 1\})^{i_\infty+1}}, \end{aligned} \quad (4.7)$$

for some positive constant $C = C(N, s, p, \varepsilon, \gamma, h_0)$. Here we have again used Young's inequality to reduce the power to q_0 . Since $\frac{q_0}{q_0+1} \geq \frac{\tau-\frac{\varepsilon}{2}}{\tau-\frac{\varepsilon}{4}}$, we have

$$\frac{(\tau - \frac{\varepsilon}{4})q_0}{q_0 + 1} \geq \tau - \frac{\varepsilon}{2}.$$

By using this in (4.7) we arrive at

$$\begin{aligned} & \sup_{-a(1-\kappa) \leq t \leq 0} \sup_{0 < |h| < h_0} \left\| \frac{\delta_h u(\cdot, t)}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(B_{5/8})} \\ & \leq \sup_{-a(1-\kappa) \leq t \leq 0} \sup_{0 < |h| < h_0} \left\| \frac{\delta_h u(\cdot, t)}{|h|^{\frac{(\tau-\frac{\varepsilon}{4})q_0}{q_0+1}}} \right\|_{L^{q_0}(B_{5/8})} \leq \frac{C(N, \varepsilon, p, s, \gamma, h_0)}{(\min\{\kappa a, 1\})^{i_\infty+1}}. \end{aligned} \quad (4.8)$$

Now we take $\chi \in C_c^\infty(B_{9/16})$ such that

$$0 \leq \chi \leq 1 \text{ in } B_{\frac{9}{16}}, \quad \chi \equiv 1 \text{ in } B_{1/2}, \quad |\nabla \chi| \leq C \text{ in } B_{\frac{9}{16}},$$

for some positive constant C . In particular, for any h with $0 < |h| < h_0$, we have

$$\frac{|\delta_h \chi|}{|h|^{\tau-\frac{\varepsilon}{2}}} \leq \frac{|\delta_h \chi|}{|h|} \leq C.$$

Also, recall that

$$\delta_h(\chi u) = \chi_h \delta_h u + u \delta_h \chi.$$

Hence, using the above properties of χ , for every $t \in [-a(1-\kappa), 0]$, we have

$$\begin{aligned} [u\chi]_{\mathcal{N}_\infty^{\tau-\varepsilon/2, q_0}(\mathbb{R}^N)} &= \sup_{|h| > 0} \left\| \frac{\delta_h(u\chi)}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(\mathbb{R}^N)} \\ &\leq \sup_{0 < |h| < h_0} \left\| \frac{\delta_h(u\chi)}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(\mathbb{R}^N)} + \sup_{|h| \geq h_0} \left\| \frac{\delta_h(u\chi)}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(\mathbb{R}^N)} \\ &\leq \sup_{0 < |h| < h_0} \left\| \frac{\chi_h \delta_h u}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(\mathbb{R}^N)} + \sup_{0 < |h| < h_0} \left\| \frac{u \delta_h \chi}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(\mathbb{R}^N)} \\ &\quad + \frac{1}{h_0^{\tau-\frac{\varepsilon}{2}}} \sup_{|h| \geq h_0} \|\delta_h(u\chi)\|_{L^{q_0}(\mathbb{R}^N)} \\ &\leq \sup_{0 < |h| < h_0} \left\| \frac{\delta_h u}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(B_{\frac{9}{16}+h_0})} + \|u\|_{L^{q_0}(B_{\frac{9}{16}+h_0})} \sup_{0 < |h| < h_0} \left\| \frac{\delta_h \chi}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^\infty(B_{\frac{9}{16}+h_0})} \\ &\quad + \frac{1}{h_0^{\tau-\frac{\varepsilon}{2}}} \sup_{|h| \geq h_0} \left(\|(u\chi)_h\|_{L^{q_0}(B_{\frac{9}{16}}(-h))} + \|u\chi\|_{L^{q_0}(B_{\frac{9}{16}})} \right) \\ &\leq \sup_{0 < |h| < h_0} \left\| \frac{\delta_h u}{|h|^{\tau-\frac{\varepsilon}{2}}} \right\|_{L^{q_0}(B_{\frac{9}{8}})} + C \|u\|_{L^{q_0}(B_1)}, \end{aligned}$$

for some positive constant $C = C(N, s, p, \varepsilon, \gamma, h_0)$. Since h_0 depends on $s, p, \varepsilon, \gamma$ and $\|u\|_{L^\infty(B_1 \times (-a, 0])} \leq 1$, the above estimate combined with (4.8) implies

$$\sup_{a(1-\kappa) \leq t \leq 0} [u\chi(\cdot, t)]_{\mathcal{N}_\infty^{\tau-\varepsilon/2, q_0}(\mathbb{R}^N)} \leq \frac{C(N, s, p, \varepsilon, \gamma)}{(\min\{\kappa a, 1\})^{c(N, s, p, \varepsilon, \gamma)}}. \quad (4.9)$$

Notice that by the choice of q_0 , we have

$$\tau - \varepsilon < \tau - \frac{\varepsilon}{2} - \frac{N}{q_0}.$$

Now we apply Theorem 2.2 with $q = q_0$, $\beta = \tau - \varepsilon/2$ and $\alpha = \tau - \varepsilon$ to obtain

$$\begin{aligned}
& \sup_{-a(1-\kappa) \leq t \leq 0} [u(\cdot, t)]_{C^{\tau-\varepsilon}(B_{1/2})} = \sup_{-a(1-\kappa) \leq t \leq 0} [(u\chi)(\cdot, t)]_{C^{\tau-\varepsilon}(B_{1/2})} \leq \sup_{-a(1-\kappa) \leq t \leq 0} [(u\chi)(\cdot, t)]_{C^{\tau-\varepsilon}(\mathbb{R}^N)} \\
& \leq C \sup_{-a(1-\kappa) \leq t \leq 0} \left(\left([u\chi(\cdot, t)]_{\mathcal{N}_\infty^{\tau-\frac{\varepsilon}{2}, q_0}(\mathbb{R}^N)} \right)^{\frac{(\tau-\varepsilon)q_0+N}{(\tau-\varepsilon/2)(q_0)}} \left(\|u\chi(\cdot, t)\|_{L^{q_0}(\mathbb{R}^N)} \right)^{\frac{(\frac{q_0}{2})\varepsilon-N}{(\tau-\varepsilon/2)q_0}} \right) \\
& \leq C \left(\sup_{-a(1-\kappa) \leq t \leq 0} [u\chi(\cdot, t)]_{\mathcal{N}_\infty^{\tau-\frac{\varepsilon}{2}, q_0}(\mathbb{R}^N)} \right)^{\frac{(\tau-\varepsilon)q_0+N}{(\tau-\varepsilon/2)(q_0)}} \left(\sup_{-a(1-\kappa) \leq t \leq 0} \|u\chi(\cdot, t)\|_{L^{q_0}(\mathbb{R}^N)} \right)^{\frac{\frac{\varepsilon q_0}{2}-N}{(\tau-\varepsilon/2)q_0}} \\
& \leq \frac{C}{(\min\{\kappa a, 1\})^{c \frac{(\tau-\varepsilon)q_0+N}{(\tau-\varepsilon/2)q_0}}},
\end{aligned}$$

where we to obtain the above estimate, have also used the estimate (4.9) and the fact that $\|u\|_{L^\infty(B_1 \times (-a, 0])} \leq 1$. Here $C = C(N, s, p, \varepsilon, \gamma)$ and $c = c(N, s, p, \varepsilon, \gamma)$ are positive constants. The proof follows by using that $\min\{\kappa a, 1\} \geq \min\{\kappa a_0, 1\}$ since $a \geq a_0$. \square

By yet another iteration process, we arrive at the final almost $sp/(p-1)$ -regularity in space.

Theorem 4.2 (Almost $sp/(p-1)$ -regularity). *Let $1 < p < 2$ and $0 < s < 1$. Suppose u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \quad \text{in } B_2 \times (-2^{sp}, 0]$$

where

$$\begin{aligned}
& \|u\|_{L^\infty(B_1 \times (-1, 0])} \leq 1, \quad \|f\|_{L^\infty(B_1 \times (-1, 0])} \leq 1, \\
& \text{and} \quad \sup_{t \in (-1, 0]} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1)^{p-1} \leq 1.
\end{aligned}$$

Then for any $\varepsilon \in (0, \Theta)$, there is $\sigma(\varepsilon, s, p) \in (0, \frac{1}{2}]$, such that $u(\cdot, t) \in C^{\Theta-\varepsilon}(B_\sigma)$ for all $t \in (-\sigma^{sp}, 0]$, where

$$\Theta = \min(sp/(p-1), 1).$$

Moreover,

$$\sup_{t \in (-\sigma^{sp}, 0]} [u(\cdot, t)]_{C^{\Theta-\varepsilon}(B_\sigma)} \leq C(s, p, \varepsilon, N).$$

Proof. The idea is to apply Proposition 4.1 iteratively. Take $\varepsilon \in (0, \Theta)$ and define

$$\gamma_0 = 0, \quad \gamma_{i+1} = sp - \gamma_i(p-2) - \frac{\varepsilon(p-1)}{2}.$$

Then $\{\gamma_i\}$ is an increasing sequence and $\gamma_i \rightarrow sp/(p-1) - \varepsilon/2$, as $i \rightarrow \infty$. It is clear that there is $i_\infty = i_\infty(s, p, \varepsilon) \in \mathbb{N}$ such that $\gamma_{i_\infty} \geq \Theta - \varepsilon$ and $\gamma_{i_\infty-1} < 1$.

Define

$$v_i(x, t) = \frac{u(2^{-i}x, 2^{-isp}M_i^{2-p}t)}{M_i}$$

and

$$\begin{aligned}
M_i &= 1 + \|u\|_{L^\infty(B_{2^{-i}} \times (-2^{-isp}, 0])} + \sup_{t \in (-2^{-isp}, 0]} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, 2^{-i}) \\
&\quad + 2^{-isp/(p-1)} \|f\|_{L^\infty(B_{2^{-i}} \times (-2^{-isp}, 0])}^{\frac{1}{p-1}} + 2^{-i\gamma_i} \sup_{t \in (2^{-isp}, 0]} [u(\cdot, t)]_{C^{\gamma_i}(B_{2^{-i}})} \\
&\leq C(N, p, s, \varepsilon) \left(1 + \sup_{t \in (-2^{-isp}, 0]} [u(\cdot, t)]_{C^{\gamma_i}(B_{2^{-i}})} \right) \\
&= C(N, p, s, \varepsilon) \left(1 + M_{i-1} 2^{(i-1)\gamma_i} \sup_{t \in (-M_{i-1}^{p-2} 2^{-isp}, 0]} [v_{i-1}(\cdot, t)]_{C^{\gamma_i}(B_{\frac{1}{2}})} \right) \\
&\leq C(N, p, s, \varepsilon) \left(1 + M_{i-1} \sup_{t \in (-M_{i-1}^{p-2} 2^{-isp}, 0]} [v_{i-1}(\cdot, t)]_{C^{\gamma_i}(B_{\frac{1}{2}})} \right).
\end{aligned} \tag{4.10}$$

Then v_i is a local weak solution of the equation $v_t + (-\Delta_p)^s v = f_i$ in $B_2 \times (-2^{sp} M_i^{p-2}, 0]$, where

$$f_i(x, t) = 2^{-isp} \frac{f(2^{-i}x, 2^{-isp} M_i^{2-p}t)}{M_i^{p-1}}.$$

Moreover, if

$$\sup_{t \in (-2^{-isp}, 0]} [u(\cdot, t)]_{C^{\gamma_i}(B_{2^{-i}})} < \infty,$$

then $M_i < \infty$ and v_i and f_i are well defined and satisfy

$$\|v_i\|_{L^\infty(B_1 \times (-M_i^{p-2}, 0])} \leq 1, \quad \sup_{t \in (-M_i^{p-2}, 0]} \text{Tail}_{p-1, sp}(v_i(\cdot, t); 0, 1)^{p-1} \leq 1,$$

$$\sup_{t \in (-M_i^{p-2}, 0]} [v_i(\cdot, t)]_{C^{\gamma_i}(B_1)} \leq 1, \quad \text{and} \quad \|f_i\|_{L^\infty(B_1 \times (-M_i^{p-2}, 0])} \leq 1.$$

Now we apply Proposition 4.1 with $a = M_i^{p-2}$ and $\kappa = 1 - 2^{-sp}$ to v_i in the cylinders $B_2 \times (-2^{sp} M_i^{p-2}, 0]$ successively with $\gamma = \gamma_i$ and ε replaced by $\frac{\varepsilon(p-1)}{2}$ and obtain for $i = 1$ to $i = i_\infty$

$$\begin{aligned} & \sup_{t \in (-2^{-sp}, 0]} [v_0(\cdot, t)]_{C^{\gamma_1}(B_{\frac{1}{2}})} \leq C(s, p, \varepsilon, N), \\ M_1 & \leq C(s, p, \varepsilon, N) \left(1 + \sup_{t \in (-2^{-sp}, 0]} [v_0(\cdot, t)]_{C^{\gamma_1}(B_{\frac{1}{2}})} \right) \leq C(s, p, \varepsilon, N), \\ & \sup_{t \in (-M_1^{p-2} 2^{-sp}, 0]} [v_1(\cdot, t)]_{C^{\gamma_2}(B_{\frac{1}{2}})} \leq C(s, p, \varepsilon, N), \\ M_2 & \leq C(s, p, \varepsilon, N) \left(1 + M_1 \sup_{t \in (-M_1^{p-2} 2^{-sp}, 0]} [v_1(\cdot, t)]_{C^{\gamma_2}(B_{\frac{1}{2}})} \right) \leq C(s, p, \varepsilon, N), \\ & \sup_{t \in (-M_{i-1}^{p-2} 2^{-sp}, 0]} [v_{i-1}(\cdot, t)]_{C^{\gamma_i}(B_{\frac{1}{2}})} \leq C(s, p, \varepsilon, N), \\ M_i & \leq C(N, p, s, \varepsilon) \left(1 + M_{i-1} \sup_{t \in (-M_{i-1}^{p-2} 2^{-isp}, 0]} [v_{i-1}(\cdot, t)]_{C^{\gamma_i}(B_{\frac{1}{2}})} \right) \leq C(s, p, \varepsilon, N), \\ & \dots \\ & \sup_{t \in (-M_{i_\infty-1}^{p-2} 2^{-sp}, 0]} [v_{i_\infty-1}(\cdot, t)]_{C^{\min(\gamma_{i_\infty}, 1 - \frac{\varepsilon(p-1)}{2})}(B_{\frac{1}{2}})} \leq C(s, p, \varepsilon, N). \end{aligned} \quad (4.11)$$

Note that at each step above we have used Proposition 4.1 for a time interval with $a = M_i^{p-2} \geq C(s, p, \varepsilon, N) = a_0$ and we have also used (4.10) to estimate M_i . If $sp > 1$, we only do one iteration and in particular $i_\infty = 1$. In particular in that case (4.11) becomes

$$\sup_{t \in (-2^{-sp}, 0]} [v_0(\cdot, t)]_{C^{sp - \frac{\varepsilon(p-1)}{2}}} \leq C(s, p, \varepsilon, N).$$

Scaling back to u and using that $\gamma_{i_\infty} \geq \Theta - \varepsilon$, we obtain

$$\begin{aligned} \sup_{t \in (-2^{-(i_\infty)sp}, 0]} [u(\cdot, t)]_{C^{\Theta-\varepsilon}(B_{2^{-i_\infty}})} &= \sup_{t \in (-M_{i_\infty-1}^{p-2} 2^{-sp}, 0]} 2^{(i_\infty-1)(\Theta-\varepsilon)} M_{i_\infty-1} [v_{i_\infty-1}(\cdot, t)]_{C^{\Theta-\varepsilon}(B_{\frac{1}{2}})} \\ &\leq C(s, p, \varepsilon, N). \end{aligned}$$

This is the desired result with $\sigma = 2^{-i_\infty}$. □

Now we apply Theorem 4.2 to prove the following spatial regularity result.

Theorem 4.3 (Spatial almost $C^{sp/(p-1)}$ regularity). *Let $\Omega \subset \mathbb{R}^N$ be a bounded and open set, $I = (t_0, t_1]$, $1 < p < 2$ and $0 < s < 1$. Suppose u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \quad \text{in } \Omega \times I,$$

with $f \in L^\infty_{\text{loc}}(\Omega \times I)$ such that

$$\|u\|_{L^\infty(Q_{2R,(2R)^{sp}}(x_0,T_0))} + \sup_{-(2R)^{sp}+T_0 < t \leq T_0} \text{Tail}_{p-1,sp}(u(\cdot, t); x_0, R) < \infty,$$

where (x_0, T_0) are such that

$$Q_{2R,(2R)^{sp}}(x_0, T_0) \Subset \Omega \times I.$$

Then $u \in C^{\Theta-\varepsilon}_{x,\text{loc}}(\Omega \times I)$ for every $\varepsilon \in (0, \Theta)$, where $\Theta = \min(sp/(p-1), 1)$.

More precisely, for every $\varepsilon \in (0, \Theta)$, $R > 0$ and every (x_0, T_0) such that

$$Q_{2R,(2R)^{sp}}(x_0, T_0) \Subset \Omega \times I,$$

there exist constants $C = C(N, s, p, \varepsilon) > 0$ and $0 < \sigma(\varepsilon, s, p) \leq \frac{1}{2}$ such that

$$\sup_{t \in (T_0 - (\sigma R)^{sp}, T_0]} [u(\cdot, t)]_{C^{\Theta-\varepsilon}(B_{\frac{\sigma R}{2}}(x_0))} \leq C \mathcal{M}^{1+\frac{2-p}{sp}} R^{-(\Theta-\varepsilon)}, \quad (4.12)$$

where

$$\mathcal{M} = \|u\|_{L^\infty(Q_{R,R^{sp}}(x_0,T_0))} + \sup_{t \in (T_0 - R^{sp}, T_0]} \text{Tail}_{p-1,sp}(u(\cdot, t); x_0, R)^{p-1} + R^{sp} \|f\|_{L^\infty(Q_{R,R^{sp}}(x_0,T_0))} + 1.$$

Proof. We perform the proof in the case $x_0 = 0$ and $T_0 = 0$.

Let

$$u_R(x, t) := \frac{1}{M} u(RM^{\frac{p-2}{sp}}x + y_0, R^{sp}t), \quad \text{for } x \in B_2, t \in (-2^{sp}, 0]$$

where $M = M(R)$ is given by

$$\begin{aligned} M &= \left(2 + \left(\frac{2N\omega(N)}{sp} \right)^{\frac{1}{p-1}} \right) \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])} + R^{sp} \|f\|_{L^\infty(B_R \times (-R^{sp}, 0])} \\ &\quad + 2(1 - \sigma)^{-N-sp} \sup_{t \in (-R^{sp}, 0]} \text{Tail}_{p-1,sp}(u(\cdot, t); 0, R)^{p-1} + 1 \end{aligned}$$

and y_0 is chosen so that

$$\sigma R M^{\frac{p-2}{sp}} + |y_0| \leq \sigma R \quad (4.13)$$

where $\sigma \in (0, \frac{1}{2}]$ is as in Theorem 4.2. Since $1 < p < 2$ and $M \geq 1$, (4.13) implies

$$2RM^{\frac{p-2}{sp}} + |y_0| \leq 2RM^{\frac{p-2}{sp}} + \sigma R - \sigma R M^{\frac{p-2}{sp}} = RM^{\frac{p-2}{sp}}(2 - \sigma) + \sigma R \leq 2R.$$

Therefore u_R is a local weak solution of $\partial_t u + (-\Delta_p)^s u = \tilde{f}$ in $B_2 \times (-2^{sp}, 0]$, where

$$\tilde{f}(x, t) = \frac{R^{sp}}{M} f(RM^{\frac{p-2}{sp}}x + y_0, R^{sp}t).$$

It is also straight forward to verify that (4.13) implies

$$\|u_R\|_{L^\infty(B_1 \times (-1, 0])} = M^{-1} \|u\|_{L^\infty(B_{\frac{p-2}{RM^{sp}}}(y_0) \times (-R^{sp}, 0])} \leq M^{-1} \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])} \leq 1,$$

as well as

$$\|\tilde{f}\|_{B_1 \times (-1, 0]} = M^{-1} R^{sp} \|f\|_{L^\infty(B_{\frac{p-2}{RM^{sp}}}(y_0) \times (-R^{sp}, 0])} \leq M^{-1} R^{sp} \|f\|_{L^\infty(B_R \times (-R^{sp}, 0])} \leq 1.$$

We will now verify that also

$$\sup_{t \in (-1, 0]} \int_{\mathbb{R}^N \setminus B_1} \frac{|u_R(z, t)|^{p-1}}{|z|^{N+sp}} dz \leq 1.$$

We have

$$\begin{aligned}
\int_{\mathbb{R}^N \setminus B_1} \frac{|u_R(z, t)|^{p-1}}{|z|^{N+sp}} dz &= R^{sp} M^{(p-2)-(p-1)} \int_{\mathbb{R}^N \setminus B_{RM \frac{p-2}{sp}}(y_0)} \frac{|u(y, R^{sp}t)|^{p-1}}{|y-y_0|^{N+sp}} dy \\
&= R^{sp} M^{-1} \left(\int_{B_R \setminus B_{RM \frac{p-2}{sp}}(y_0)} \frac{|u(y, R^{sp}t)|^{p-1}}{|y-y_0|^{N+sp}} dy + \int_{\mathbb{R}^N \setminus B_R} \frac{|u(y, R^{sp}t)|^{p-1}}{|y-y_0|^{N+sp}} dy \right) \\
&= I_1 + I_2.
\end{aligned}$$

We note that $|y_0| \leq \sigma R$, which implies that if $y \in B_R^c$, then $|y-y_0| \geq (1-\sigma)|y|$. Therefore

$$\sup_{t \in (-1, 0]} I_2 \leq R^{sp} M^{-1} (1-\sigma)^{-N-sp} \sup_{t \in (-R^{sp}, 0]} \int_{\mathbb{R}^N \setminus B_R} \frac{|u(y, t)|^{p-1}}{|y|^{N+sp}} dy \leq \frac{1}{2}$$

by the choice of M . For I_1 , we instead have

$$\begin{aligned}
\sup_{t \in (-1, 0]} I_1 &\leq \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])}^{p-1} R^{sp} M^{-1} \int_{\mathbb{R}^N \setminus B_{RM \frac{p-2}{sp}}} \frac{1}{|\tilde{y}|^{N+sp}} d\tilde{y} \\
&= \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])}^{p-1} R^{sp} M^{-1} \int_{RM \frac{p-2}{sp}}^\infty N \omega(N) r^{-1-sp} dr \\
&= \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])}^{p-1} \frac{M^{-(p-1)} N \omega(N)}{sp} \\
&\leq \frac{1}{2},
\end{aligned}$$

again by the choice of M . By Theorem 4.2, u_R satisfies the estimate

$$\sup_{t \in (-\sigma^{sp}, 0]} [u_R(x, t)]_{C^{\Theta-\varepsilon}(B_\sigma)} \leq C, \quad C = C(N, s, p, \varepsilon).$$

By scaling back, we obtain

$$\sup_{t \in (-\sigma R)^{sp}, 0]} [u(x, t)]_{C^{\Theta-\varepsilon}\left(B_{\sigma RM \frac{p-2}{sp}}(y_0)\right)} \leq CM^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)}. \quad (4.14)$$

Since this is valid for all y_0 satisfying (4.13), we can, by varying y_0 , cover the whole $B_{\sigma R/2}$ and obtain

$$\sup_{t \in (-\sigma R)^{sp}, 0]} [u(x, t)]_{C^{\Theta-\varepsilon}(B_{\frac{\sigma R}{2}})} \leq CM^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)}. \quad (4.15)$$

Once this is settled, this proves the theorem.

Let us provide the details of how to vary y_0 . First of all, if $M^{\frac{p-2}{sp}} \geq 1/2$, then (4.14) with $y_0 = 0$ implies (4.15) directly. Therefore, we assume $M^{\frac{p-2}{sp}} < 1/2$ in what follows. We need to estimate

$$\frac{|u(x, t) - u(y, t)|}{|x - y|^{\Theta-\varepsilon}}, \quad x, y \in B_{\frac{\sigma R}{2}}, t \in (-\sigma R)^{sp}, 0].$$

Take $x, y \in B_{\sigma R/2}$ and fix $t \in (-\sigma R)^{sp}, 0]$. If $|x - y| \leq \sigma RM^{\frac{p-2}{sp}}$, it follows that

$$x, y \in B_{\sigma RM \frac{p-2}{sp}}((x-y)/2)$$

and

$$\sigma RM^{\frac{p-2}{sp}} + |(x-y)/2| \leq \sigma R/2 + \sigma R/4 \leq 3\sigma R/4 \leq \sigma R$$

so that the choice $y_0 = (x-y)/2$ is admissible for (4.13). We may therefore apply (4.14) directly by choosing $y_0 = (x-y)/2$ to obtain

$$\frac{|u(x, t) - u(y, t)|}{|x - y|^{\Theta-\varepsilon}} \leq CM^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)} \leq CM^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)}.$$

If instead $|x - y| \geq \sigma R M^{\frac{p-2}{sp}}$, we take

$$z_i = x + \frac{y - x}{\lceil M^{\frac{2-p}{sp}} \rceil} i, \quad i = 0, \dots, J = \lceil M^{\frac{2-p}{sp}} \rceil.$$

Since $x, y \in B_{\sigma R/2}$, we have $|z_i - z_{i+1}| = \frac{|x-y|}{\lceil M^{\frac{2-p}{sp}} \rceil} < \sigma R M^{\frac{p-2}{sp}}$, $z_0 = x$ and $z_J = y$. This choice implies that

$$z_i, z_{i+1} \in B_{\sigma R M^{\frac{p-2}{sp}}/2}((z_i - z_{i+1})/2)$$

and

$$\sigma R M^{\frac{p-2}{sp}} + |(z_i - z_{i+1})/2| \leq \sigma R/2 + \sigma R/4 \leq \sigma R,$$

as before. Therefore, the choice $y_0 = (z_i - z_{i+1})/2$ is admissible for (4.13). We can therefore apply (4.14) with $y_0 = (z_i - z_{i+1})/2$ and obtain

$$\frac{|u(z_i, t) - u(z_{i+1}, t)|}{|z_i - z_{i+1}|^{\Theta-\varepsilon}} \leq C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)}.$$

By the triangle inequality, we can now conclude

$$\begin{aligned} |u(x, t) - u(y, t)| &\leq \sum_{i=0}^J |u(z_i, t) - u(z_{i+1}, t)| \leq \sum_{i=0}^J C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)} |z_i - z_{i+1}|^{\Theta-\varepsilon} \\ &\leq \sum_{i=0}^J C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)} \left(\frac{|x-y|}{\lceil M^{\frac{2-p}{sp}} \rceil} \right)^{\Theta-\varepsilon} \\ &\leq C J M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)} M^{\frac{p-2}{sp}(\Theta-\varepsilon)} |x-y|^{\Theta-\varepsilon} \\ &\leq C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)} |x-y|^{\Theta-\varepsilon} \end{aligned}$$

where we have used that $J = \lceil M^{\frac{2-p}{sp}} \rceil \leq M^{\frac{2-p}{sp}} + 1 \leq 2M^{\frac{2-p}{sp}}$. This proves (4.15) and the proof is complete. \square

Remark 4.4. We note that by a covering argument, we may, under the assumptions of Theorem 4.3, obtain the estimate

$$\sup_{t \in (T_0 - (\frac{R}{2})^{sp}, T_0]} [u(\cdot, t)]_{C^{\Theta-\varepsilon}(B_{\frac{R}{2}}(x_0))} \leq C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)}, \quad (4.16)$$

where

$$\mathcal{M} = \|u\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + \sup_{t \in (T_0 - R^{sp}, T_0]} \text{Tail}_{p-1, sp}(u(\cdot, t); x_0, R)^{p-1} + R^{sp} \|f\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + 1.$$

Indeed, we may cover $B_{\frac{R}{2}}(x_0) \times (-(\frac{R}{2})^{sp} + T_0, T_0]$ with a finite number of cylinders of the form

$$B_{\frac{\sigma R}{2}}(x_i) \times \left(-(\frac{\sigma R}{2})^{sp} + t_j, t_j \right], \quad i = 1, \dots, n, \quad j = 1, \dots, m,$$

where $B_{\frac{R}{2}}(x_i) \subset B_R(x_0)$ and $(-(\frac{R}{2})^{sp} + t_j, t_j] \subset (-R^{sp} + T_0, T_0]$. We may then apply Theorem 4.3 to each of these cylinders and obtain

$$\sup_{t \in [t_j - (\frac{\sigma R}{2})^{sp}, t_j]} [u(\cdot, t)]_{C^{\Theta-\varepsilon}(B_{\frac{\sigma R}{2}}(x_i))} \leq C M^{1+\frac{2-p}{sp}(\Theta-\varepsilon)} R^{-(\Theta-\varepsilon)},$$

where

$$\mathcal{M} = \|u\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + \sup_{t \in (T_0 - R^{sp}, T_0]} \text{Tail}_{p-1, sp}(u(\cdot, t); x_0, R)^{p-1} + R^{sp} \|f\|_{L^\infty(Q_{R, R^{sp}}(x_0, T_0))} + 1.$$

By the triangle inequality, this implies the desired inequality (4.16).

5. TIME REGULARITY

In this section, we prove Hölder continuity in the time variable, assuming Hölder regularity in the spatial variable. For $u \in L^1(Q_{R,r}(x_0, t_0))$, we will use the notation

$$\bar{u}_{(x_0, t_0), R, r} = \int_{Q_{R,r}(x_0, t_0)} u \, dx \, dt.$$

When the center (x_0, t_0) is clear from the context, we simply write $\bar{u}_{R,r}$.

Proposition 5.1. *Let $1 < p < 2$, $0 < s < 1$ and $\Theta(s, p) = \min(\frac{sp}{p-1}, 1)$. Suppose that u is a local weak solution of*

$$\partial_t u + (-\Delta_p)^s u = f \text{ in } B_2 \times (-2^{sp}, 0]$$

as in Definition 2.1, where

$$\|u\|_{L^\infty(B_1 \times (-1, 0])} \leq 1, \quad \sup_{t \in (-1, 0]} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, 1) \leq 1, \quad \text{and} \quad \|f\|_{L^\infty(B_1 \times (-1, 0])} \leq 1.$$

Further, assume that for some $\delta \in (s, \Theta(s, p))$, there exists a positive constant K_δ depending on δ such that

$$\sup_{t \in (-2^{-sp}, 0]} [u(\cdot, t)]_{C^\delta(B_{1/2})} \leq K_\delta. \quad (5.1)$$

Then there is a constant $C = C(N, s, p, K_\delta, \delta) > 0$ such that

$$|u(x, t) - u(x, \tau)| \leq C |t - \tau|^\gamma, \quad \text{for all } x \in B_{\frac{1}{4}} \text{ and for all } t, \tau \in (-4^{-sp}, 0]$$

where

$$\gamma = \frac{1}{\frac{sp}{\delta} + (2-p)}.$$

In particular, $u \in C_t^\gamma(Q_{\frac{1}{4}, 4^{-sp}})$.

Proof. Take $(x_0, t_0) \in Q_{\frac{1}{4}, 4^{-sp}}$ and choose

$$0 < r < \frac{1}{8}, \quad 0 < \theta < \frac{1}{2} (2^{-sp} - 4^{-sp}).$$

By construction,

$$Q_{r, \theta}(x_0, t_0) \subset B_{\frac{3}{8}} \times (-2^{-sp}, 0].$$

Let $\eta \in C_c^\infty(B_{r/2}(x_0))$ be a non-negative smooth function, such that

$$\eta \equiv \|\eta\|_{L^\infty(B_{r/2}(x_0))} \text{ on } B_{r/4}(x_0), \quad \bar{\eta}_r = \frac{1}{|B_r(x_0)|} \int_{B_r(x_0)} \eta \, dx = 1 \quad \text{and} \quad \|\nabla \eta\|_{L^\infty(B_{r/2}(x_0))} \leq \frac{C}{r},$$

for some constant $C = C(\|\eta\|_{L^\infty(B_{r/2}(x_0))}, N) > 0$. Note that since the average of η is 1, we have the estimate

$$\|\eta\|_{L^\infty(B_{r/2}(x_0))} = \frac{1}{|B_{r/4}(x_0)|} \int_{B_{r/4}(x_0)} \eta \, dx \leq \frac{|B_r(x_0)|}{|B_{r/4}(x_0)|} \bar{\eta}_r = 4^N.$$

By the triangle inequality,

$$\begin{aligned} \int_{Q_{r, \theta}(x_0, t_0)} |u(x, t) - \bar{u}_{r, \theta}| \, dx \, dt &\leq \int_{Q_{r, \theta}(x_0, t_0)} |u(x, t) - (\overline{u \eta})_{r, \theta}(t)| \, dx \, dt \\ &\quad + \int_{Q_{r, \theta}(x_0, t_0)} |\bar{u}_{r, \theta} - (\overline{u \eta})_{r, \theta}| \, dx \, dt \\ &\quad + \int_{Q_{r, \theta}(x_0, t_0)} |(\overline{u \eta})_{r, \theta} - (\overline{u \eta})_r(t)| \, dx \, dt \\ &=: A_1 + A_2 + A_3, \end{aligned} \quad (5.2)$$

where

$$\overline{(u\eta)}_r(t) = \int_{B_r(x_0)} u(y, t) \eta(y) \, dy.$$

Following the same steps in the proof of [4, Proposition 6.2] we arrive at

$$A_2 \leq A_1 + A_3, \quad (5.3)$$

$$A_1 \leq C K_\delta r^\delta, \quad \text{for some } C = C(N, s, p) > 0, \quad (5.4)$$

and

$$A_3 \leq \sup_{T_0, T_1 \in (t_0 - \theta, t_0]} \left| \overline{(u\eta)}_r(T_0) - \overline{(u\eta)}_r(T_1) \right|. \quad (5.5)$$

For $T_0, T_1 \in (t_0 - \theta, t_0]$ with $T_0 < T_1$, we use the weak formulation (2.6) with $\varphi(x, t) = \eta(x)$, to obtain

$$\begin{aligned} |B_r(x_0)| \left| \overline{(u\eta)}_r(T_0) - \overline{(u\eta)}_r(T_1) \right| &= \left| \int_{B_r(x_0)} u(x, T_0) \eta(x) \, dx - \int_{B_r(x_0)} u(x, T_1) \eta(x) \, dx \right| \\ &= \left| \int_{T_0}^{T_1} \iint_{\mathbb{R}^N \times \mathbb{R}^N} J_p(u(x, \tau) - u(y, \tau)) (\eta(x) - \eta(y)) \, d\mu(x, y) \, d\tau \right| \\ &\leq \left| \int_{T_0}^{T_1} \iint_{B_r(x_0) \times B_r(x_0)} J_p(u(x, \tau) - u(y, \tau)) (\eta(x) - \eta(y)) \, d\mu(x, y) \, d\tau \right| \\ &\quad + 2 \left| \int_{T_0}^{T_1} \iint_{(\mathbb{R}^N \setminus B_r(x_0)) \times B_{r/2}(x_0)} J_p(u(x, \tau) - u(y, \tau)) \eta(x) \, d\mu(x, y) \, d\tau \right| \\ &\quad + \left| \int_{T_0}^{T_1} \int_{B_r(x_0)} f(x, \tau) \eta(x) \, dx \, d\tau \right| \\ &= J_1 + J_2 + J_3. \end{aligned} \quad (5.6)$$

For J_1 , the estimate performed in the proof of [4, Proposition 6.2] still applies and gives

$$J_1 \leq C K_\delta^{p-1} \theta r^{N+\delta(p-1)-sp}, \quad (5.7)$$

for some constant $C = C(N, s, p, \delta) > 0$. Regarding J_2 , we may follow the steps in the proof of [38, Proposition 5.7] and obtain

$$J_2 \leq C \theta r^N \left(1 + r^{\delta(p-1)-sp} \right) \leq C \theta r^{N+\delta(p-1)-sp}, \quad (5.8)$$

for some constant $C = C(N, s, p, \delta, K_\delta) > 0$. Finally, we estimate J_3 as follows

$$\begin{aligned} J_3 &\leq \int_{T_0}^{T_1} \int_{B_r(x_0)} |f(x, \tau)| \eta(x) \, dx \, dt \leq \|f\|_{L^\infty(B_r(x_0) \times (T_0, T_1))} \int_{T_0}^{T_1} \int_{B_r(x_0)} \eta(x) \, dx \, dt \\ &\leq (T_1 - T_0) |B_r(x_0)| \|f\|_{L^\infty(B_1 \times (-1, 0))} \int_{B_r(x_0)} \eta(x) \, dx \leq C(N) \theta r^N. \end{aligned} \quad (5.9)$$

The combination of (5.5)–(5.9) implies

$$A_3 \leq C(1 + K_\delta^{p-1}) \theta (1 + r^{\delta(p-1)-sp}) \leq C(1 + K_\delta^{p-1}) \theta r^{\delta(p-1)-sp}. \quad (5.10)$$

Therefore, by (5.2) together with (5.3)

$$\int_{Q_{r,\theta}(x_0, t_0)} |u(x, t) - \bar{u}_{r,\theta}| \, dx \, dt \leq C \left(r^\delta + \theta r^{\delta(p-1)-sp} \right), \quad (5.11)$$

for some constant $C = C(N, s, p, \delta, K_\delta) > 0$.

We now split the rest of the proof into two cases.

Case 1: $sp + \delta(2 - p) \geq 1$. Choose

$$\theta = \frac{1}{2} \left(\frac{1}{2^{sp}} - \frac{1}{4^{sp}} \right) r^{sp+\delta(2-p)}.$$

Then (5.11) reads

$$\int_{Q_{r,\theta}(x_0,t_0)} |u(x,t) - \bar{u}_{r,\theta}| \, dx \, dt \leq Cr^\delta,$$

for some constant $C = C(N, s, p, \delta, K_\delta) > 0$.

Now we use the characterization of the Campanato spaces in \mathbb{R}^{n+1} with a general metric in [18], see also [9]. Our setting does not fit directly in the context considered there, since we only work with cylinders that are one sided in the time direction, that is $(t - r^{sp+\delta(2-p)}, t] \times B_r(x)$ instead of $(t - r^{sp+\delta(2-p)}, t + r^{sp+\delta(2-p)}) \times B_r(x)$. Still, if one follows the proof in [18] with small modifications, one can also conclude the result in this setting. By [18, Theorem 3.2], u is δ -Hölder continuous in $Q_{1/4, 1/4^{sp}}$ with respect to the metric

$$d((x, \tau_1), (y, \tau_2)) = \max \{ |x - y|, |\tau_2 - \tau_1|^{\frac{1}{sp+\delta(2-p)}} \}.$$

Note that since $sp + \delta(2-p) \geq 1$, d is a metric. The balls of radius r for this metric are of the form $(t - r^{sp+\delta(2-p)}, t + r^{sp+\delta(2-p)}) \times B_r(x)$.

In particular, for any $\tau_1, \tau_2 \in (-\frac{1}{4^{sp}}, 0]$ we have the estimate

$$\sup_{x \in \bar{B}_{1/4}} |u(x, \tau_1) - u(x, \tau_2)| \leq C |\tau_1 - \tau_2|^\gamma,$$

where the constant $C = C(\delta, K_\delta, N, s, p) > 0$, and

$$\gamma = \frac{\delta}{sp + \delta(2-p)} = \frac{1}{\frac{sp}{\delta} + 2 - p}.$$

Case 2: $sp + \delta(2-p) < 1$. In this case, we make the choice

$$r = \frac{1}{2} \left(\frac{1}{2^{sp}} - \frac{1}{4^{sp}} \right) \theta^{\frac{1}{sp+\delta(2-p)}}.$$

From (5.11) we obtain

$$\int_{Q_{r,\theta}(x_0,t_0)} |u(x,t) - \bar{u}_{r,\theta}| \, dx \, dt \leq C \theta^{\frac{\delta}{sp+\delta(2-p)}}.$$

Again, by [18, Theorem 3.2] we obtain that u is $\frac{\delta}{sp+\delta(2-p)}$ -Hölder continuous, in $Q_{1/4, 1/4^{sp}}$ with respect to the metric

$$\tilde{d} = \max \left\{ |x - y|^{sp+\delta(2-p)}, |\tau_1 - \tau_2| \right\}.$$

As $sp + \delta(2-p) < 1$, \tilde{d} is indeed a metric. In particular, we have the estimate

$$\sup_{x \in \bar{B}_{1/4}} |u(x, \tau_1) - u(x, \tau_2)| \leq C |\tau_1 - \tau_2|^\gamma,$$

for some constant $C = C(\delta, K_\delta, N, s, p) > 0$, where

$$\gamma = \frac{\delta}{sp + \delta(2-p)}.$$

□

6. PROOF OF THE MAIN THEOREM

We are now ready to give the proof of our main theorem, namely Theorem 1.1, that encompasses both the spatial regularity and regularity in time.

Proof of Theorem 1.1. The proof follows from a combination of Theorem 4.3, Remark 4.4 and Proposition 5.1. We spell out the details below. It remains to prove the regularity in time. We assume $x_0 = 0$ and $T_0 = 0$ and argue as in the proof of Theorem 4.3. Let

$$u_R(x, t) := \frac{1}{M} u(RM^{\frac{p-2}{sp}}x + y_0, R^{sp}t), \quad \text{for } (x, t) \in B_2 \times (-2^{sp}, 0]$$

where y_0 is chosen so that

$$\frac{1}{2}RM^{\frac{p-2}{sp}} + |y_0| \leq R/2 \quad (6.1)$$

and

$$M = \left(2 + \left(\frac{2N\omega(N)}{sp} \right)^{\frac{1}{p-1}} \right) \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])} + 2^{1+N+sp} \sup_{t \in (-R^{sp}, 0]} \text{Tail}_{p-1, sp}(u(\cdot, t); 0, R)^{p-1} \\ + R^{sp} \|f\|_{L^\infty(B_R \times (-R^{sp}, 0])} + 1.$$

Estimate (6.1) implies

$$2RM^{\frac{p-2}{sp}} + |y_0| \leq 2R.$$

Therefore, u_R is a local weak solution of $\partial_t u + (-\Delta_p)^s u = \tilde{f}$ in $B_2 \times (-2^{sp}, 0]$, where

$$\tilde{f}(x, t) := \frac{R^{sp}}{M} f(RM^{\frac{p-2}{sp}} x + y_0, R^{sp} t).$$

With the notation $\tilde{R} = RM^{\frac{p-2}{sp}}$, it is straight forward to verify that (6.1) implies

$$\|u_R\|_{L^\infty(B_1 \times (-1, 0])} = M^{-1} \|u\|_{L^\infty(B_{\tilde{R}}(y_0) \times (-R^{sp}, 0])} \leq M^{-1} \|u\|_{L^\infty(B_R \times (-R^{sp}, 0])} \leq 1.$$

As in the proof of Theorem 4.3 we also have

$$\sup_{t \in (-1, 0]} \int_{\mathbb{R}^N \setminus B_1} \frac{|u_R(z, t)|^{p-1}}{|z|^{N+sp}} dz \leq 1.$$

We also have

$$\|\tilde{f}\|_{L^\infty(B_1 \times (-1, 0])} = \frac{R^{sp}}{M} \left\| f(RM^{\frac{p-2}{sp}} x + y_0, R^{sp} t) \right\|_{L^\infty(B_1 \times (-1, 0])} \\ = \frac{R^{sp}}{M} \|f\|_{L^\infty(B_{\tilde{R}}(y_0) \times (-R^{sp}, 0])} \leq \frac{R^{sp}}{M} \|f\|_{L^\infty(B_R \times (-R^{sp}, 0])} \leq 1.$$

The above bounds combined with Theorem 4.3 and Remark 4.4 imply

$$\sup_{t \in (-2^{-sp}, 0]} [u_R(\cdot, t)]_{C^\theta(B_{\frac{1}{2}})} \leq C, \quad (6.2)$$

for every $\theta \in (0, \Theta)$ with $C = C(N, s, p, \theta) > 0$. By using this together with Proposition 5.1, we obtain

$$\sup_{x \in B_{\frac{1}{4}}} [u_R(x, \cdot)]_{C^\gamma((-4^{-sp}, 0])} \leq C \quad (6.3)$$

where

$$\gamma = \frac{1}{\frac{sp}{\theta} + (2-p)},$$

and $C = C(N, s, p, \theta)$. Scaling back, (6.2) and (6.3) imply, (again with the notation $\tilde{R} = RM^{\frac{p-2}{sp}}$)

$$\sup_{t \in (-(R/2)^{sp}, 0]} [u(x, t)]_{C^\theta(B_{\frac{\tilde{R}}{2}}(y_0))} \leq CM^{1+\frac{(2-p)}{sp}} R^{-\theta} \quad (6.4)$$

and

$$\sup_{x \in B_{\frac{\tilde{R}}{4}}(y_0)} [u(x, \cdot)]_{C^\gamma((-4^{-sp} R^{sp}, 0])} \leq CM R^{-\gamma} \quad (6.5)$$

for all y_0 that satisfies (6.1), with the constant $C = C(N, s, p, \theta) > 0$. Therefore, we obtain the estimates (6.4) and (6.5) in the whole $B_{R/4}$ by varying y_0 as in the proof of Theorem 4.3. Since this holds for all $\theta < \Theta$ and with $\gamma = (sp/\theta + (2-p))^{-1}$ which converges to Γ as $\theta \rightarrow \Theta$, this implies the desired result. \square

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